

# Scattering from 3-D Cavities with a Plug and Play Numerical Scheme Combining IE, PDE, and Modal Techniques

André Barka, Paul Soudais, and Dominique Volpert

**Abstract**—In this paper, we present a multidomain and multimethod coupling scheme called FACTOPO, based on generalized scattering matrix computations on three-dimensional (3-D) subdomains. The global target  $\Omega$  is split in  $N_V$  subdomains  $(V_i)_{i=1, N_V}$ , separated by  $N_I$  fictitious surfaces  $(\Gamma_j)_{j=1, N_I}$ . We use a modal representation of the tangent fields on the interfaces. In each domain, the generalized Scattering matrix  $S_i$  is computed with different methods such as the 3-D finite-element method (FEM) or the electric field integral equation (EFIE). This coupling scheme leads to an important reduction in computational resources, especially for cavities with one dimension much larger than the other two. The advantages of this formulation for parametric studies will be illustrated by two cases: computing the RCS of an air-intake terminated with a flat PEC or a fan (CHANNEL) and of an antenna structure coupled to an electronic feed with a varying parameter (DENEB). Numerical as well as experimental results are presented.

**Index Terms**—Boundary integral equations, cavities, electromagnetic scattering, finite-element method, mode matching.

## I. INTRODUCTION

THE electromagnetic scattering from the interior of a complex jet engine inlet contributes significantly to the overall radar cross section (RCS) of a modern jet aircraft. The scattering mechanisms in jet or missile inlets are complicated and difficult to simulate accurately. The geometry is both complicated (engine face, structural obstacles, materials) and electrically large.

In previous work, asymptotic techniques have been employed, such as the geometrical shooting and bouncing ray method (SBR), and hybrid combinations of asymptotic high frequency and modal methods ([1], [2]) to propagate the fields from the inlet opening to the engine face. Hybrid SBR finite-difference time-domain (FDTD), physical optics (PO)-FDTD ([3]) and SBR-modal finite-element method (FEM) ([4]) were presented for analyzing the scattering from three-dimensional (3-D) inlet cavities. In these hybrid methods, the FDTD or the FEM are used to determine the reflection matrices associated with the termination. The modal analysis, PO, or rays are used to analyze the air intake. However, for the channels, these techniques are limited to the high-frequency region. Hybrid numerical methods have been developed in the frequency domain so as to combine both the advantages of the integral equations (IE) for unbounded domains, and the FEM

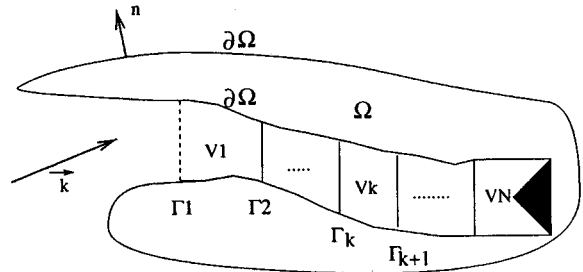


Fig. 1. Target decomposition.

to efficiently model inhomogeneous and anisotropic media ([5]–[11]). They are widely used for the RCS evaluation of large and complex targets, but, unfortunately, many of these formulations are not really suitable in a context of parametric investigations (local inlet engine modifications), or cooperative work during an aircraft project.

Several authors ([7]) have developed connection schemes based on microwave network theory. The 3-D cavity is recessed in an infinite ground plane and is divided into sections and each section is represented by a generalized admittance matrix analyzed independently from the rest of the cavity. Number of formulations are based on the decoupling of the problem in subdomains ([5], [6]) each one characterized by an admittance matrix. In ([7]), the admittance matrix is computed with a boundary-integral method (BIM) and the fields on the interfaces are expanded with local pulse functions. When the cavities are complex, some authors have proposed to compute the admittance matrices with the FEM ([6], [8]).

In this paper, we present a multidomain and multimethod coupling scheme based on generalized scattering matrix computations of 3-D subdomains. The global target  $\Omega$  is split into  $N_V$  subdomains  $(V_i)_{i=1, N_V}$  separated by  $N_I$  fictitious surfaces  $(\Gamma_j)_{j=1, N_I}$  (Fig. 1). We use waveguide modes as expansion functions on the fictitious surfaces for modeling the field propagation from the cavity aperture down to the cavity termination. For each subdomain (even the exterior 3-D volume), the generalized Scattering matrix  $S_i$  is computed with different methods such as the 3-D FEM or the electric field integral equation (EFIE) combined with a generalized waveguide modal representation of the fields on the fictitious surfaces ([12], [13]). Then, the different objects are connected by cascading the different  $S$  matrices. In a context of parametric investigations, the scattering matrices of the modified domains have to be re-evaluated, the other ones are simply re-used in

the connection step. This strategy reduces significantly the computation time compared to traditional hybrid methods for which a geometric or electromagnetic modification requires a new computation of the complete target. Furthermore, the  $S_i$  matrix computations are totally independent allowing code and data protection during a multi-industrial aircraft project.

We will emphasize the strong reduction in computational resources obtained with this coupling scheme and especially the waveguide modal expansion. The advantages of this formulation for parametric studies will be illustrated by two cases: computing the RCS of an air intake terminated by a flat PEC or a fan and of an antenna structure coupled to an electronic feed with a varying parameter.

## II. FORMULATION

The target  $\Omega$  is split into  $N_V$  subdomains  $(V_i)_{i=1, N_V}$  by  $N_I$  fictitious surfaces  $(\Gamma_j)_{j=1, N_I}$  (Fig. 1). Note that  $V_0$  is an unbounded volume, and the volumes  $\{V_1, \dots, V_{N_V}\}$  are bounded. In each bounded or unbounded volume  $V_i$  of the decomposition, the boundary  $\partial V_i$  is made of  $n_i$  fictitious surfaces  $\Gamma_j$  and a part of  $\partial\Omega$ . The surrounding medium has permittivity  $\varepsilon_0$  and permeability  $\mu_0$ . The scatterer is illuminated by an incident wave  $\{E_{\text{inc}}, H_{\text{inc}}\}$  with wavenumber  $k = \omega/c$ . The electromagnetic fields  $\mathbf{E}, \mathbf{H}$  are homogenized by expressing the EFIE and FEM formulations with the fields  $E = \sqrt{\varepsilon_0}\mathbf{E}$  and  $H = \sqrt{\mu_0}\mathbf{H}$ .

### A. EFIE

The exterior problem (in the unbounded region  $V_0$ ) is recast on the surface  $\partial V_0$  by means of the EFIE. The EFIE, written in weak form, is given by

$$\begin{aligned} & \frac{j}{4\pi} \iint_{\partial V_0} k^2 G(\Phi, J') - G((\nabla_S \Phi), (\nabla'_S J')) ds ds' \\ & + \frac{k}{2} \int_{\partial V_0} \Phi (n \times K) ds \\ & + \frac{k}{4\pi} \iint_{\partial V_0} (\nabla' G) \cdot (\Phi \times K') ds ds' \\ & = k \int_{\partial V_0} \Phi \cdot E_{\text{sources}} ds \end{aligned} \quad (1)$$

with  $J = n \times H$ ,  $K = E \times n$ ,  $G(r) = e^{-jkr}/r$ ,  $r = \|\vec{MM}'\|$ , the primed quantities (e.g.,  $J'$ ) are taken at the emission point  $M'$ , the others are taken at the observation point  $M$ .

The functions  $\Phi$  are the Rao–Wilton–Glisson (RWG) divergence-conforming basis functions ([14]) used for the discretization of the boundary integral equation.

The linear system is solved with an out-of-core solver with asynchronous  $I/O$ . Very efficient out-of-core solvers exist on supercomputers, workstations and PC's. They are very attractive for applications with large number of right hand sides.

### B. FEM

The weak form of the partial differential equation for the interior problem in  $V_i$  relates the magnetic field in the volume to

the trace of the tangential electric field (or equivalently  $n \times E$ ) on its boundary  $\partial V_i$

$$\begin{aligned} & j \int_{V_i} k^2 (\mu H) \cdot \varphi dv - j \int_{V_i} (\varepsilon^{-1} \nabla \times H) \cdot (\nabla \times \varphi) dv \\ & = -k \int_{\partial V_i} (n \times E) \cdot \varphi ds. \end{aligned} \quad (2)$$

The interior problem 2 is discretized with tetrahedral curl-conforming edge-elements functions  $\varphi$  ([15]). These elements guarantee that the null space of the curl operator is correctly approximated (no spurious modes are added to the solution). With these elements, only the tangential components of the fields are continuous at element boundaries, i.e., the normal components are allowed to jump, which is the correct physical property.

### C. Modal Functions on the Fictitious Surfaces

On each fictitious surface  $\Gamma_j$  of  $V_i$ , the tangential fields  $(n \times E, n \times H)$  are expanded in a set of waveguide mode functions  $(n \times E_p^j, n \times H_p^j)$ . For clarity in the following formulation, the functions  $n \times E_p^j$  are extended by zero on all the other surfaces of  $\partial V_i$ . These modes are computed on planar surfaces of any shape with a scalar potential formulation ([12]) discretized with an FEM generalized to compute the dispersion characteristics ([13]). If  $p_j$  denotes the number of modes on  $\Gamma_j$ , the total tangential fields are written as

$$\begin{cases} (n \times E)_{\Gamma_j} = \sum_{p=1, p_j} (a_{i,p}^j + b_{i,p}^j) (n \times E_p^j) \\ (n \times H)_{\Gamma_j} = \sum_{p=1, p_j} (a_{i,p}^j - b_{i,p}^j) (n \times H_p^j). \end{cases} \quad (3)$$

If  $V_i$  has  $n_i$  interfaces, the total number of modes is  $\sum_{j=1, n_i} p_j$ . We shall now introduce these field decompositions in the EFIE and FEM formulations (1), (2). By linearity of the Maxwell equations, the tangent magnetic field on  $\partial V_i$  is a linear combination of the following fields:

$$\begin{aligned} (n \times H)_{\partial V_i} = & \sum_{j=1, n_i} \sum_{p=1, p_j} (a_{i,p}^j + b_{i,p}^j) (n \times H_{\text{excitation}}^{j,p})_{\partial V_i} \\ & + (n \times H_{\text{source}})_{\partial V_i} \end{aligned} \quad (4)$$

$n \times H_{\text{excitation}}^{j,p}$  is a tangent magnetic field defined on the surface  $\partial V_i$  induced by the  $p$ th electrical modal field  $n \times E_p^j$  belonging to the interface  $j$  and extended by zero on the other surfaces. In the same way,  $n \times H_{\text{source}}$  is the tangent magnetic field on  $\partial V_0$  induced by the incident wave  $\{E_{\text{inc}}, H_{\text{inc}}\}$  illuminating the scatterer when all the fictitious surfaces are perfectly conductive.

The  $H_{\text{excitation}}^{j,p}$  can be computed from the following FEM equation for a bounded volume  $V_i$ :

$$\begin{aligned} & j \int_{V_i} k^2 (\mu H_{\text{excitation}}^{j,p}) \cdot \varphi dv \\ & - j \int_{V_i} (\varepsilon^{-1} \nabla \times H_{\text{excitation}}^{j,p}) \cdot (\nabla \times \varphi) dv \\ & = -k \int_{\Gamma_j} (n \times E_p^j) \cdot \varphi ds. \end{aligned} \quad (5)$$

The EFIE can be used in this formulation to compute the  $H_{\text{excitation}}^{j,p}$  fields for both bounded and unbounded volumes and

$$\begin{aligned} & \frac{j}{4\pi} \iint_{\partial V_i} k^2 G(\Phi \cdot (J_p^j)') - G((\nabla_S \Phi) \cdot (\nabla'_S (J_p^j)')) ds ds' \\ &= -\frac{k}{2} \int_{\Gamma_j} \Phi \cdot (n \times (K_p^j)) ds \\ & - \frac{k}{4\pi} \iint_{\Gamma_j} (\nabla' G) \cdot (\Phi \times (K_p^j)') ds ds' \end{aligned} \quad (6)$$

with  $J_p^j = n \times H_{\text{excitation}}^{j,p}$ ,  $K_p^j = E_p^j \times n$ .

The scatterer is illuminated by an incident wave  $\{E_{\text{inc}}, H_{\text{inc}}\}$  located in the exterior unbounded domain  $V_0$ . The  $J_{\text{source}} = n \times H_{\text{source}}$  field is solution of the following integral equation:

$$\begin{aligned} & \frac{j}{4\pi} \iint_{\partial V_0} k^2 G(\Phi \cdot J'_{\text{source}}) - G((\nabla_S \Phi) \cdot (\nabla'_S J'_{\text{source}})) ds ds' \\ &= k \int_{\partial V_0} \Phi \cdot E_{\text{inc}} ds. \end{aligned} \quad (7)$$

#### D. Scattering Matrices

We shall now characterize the volume  $V_i$  by its scattering matrix  $S_i$ . On all of the  $n_i$  fictitious surfaces  $\Gamma_j$ , the tangential components of the total magnetic fields are written

$$\begin{aligned} & \sum_{p=1, p_j} (a_{i,p}^j - b_{i,p}^j) \cdot (n \times H_p^j) \\ &= (n \times H_{\text{source}, \partial V})_{/\Gamma_j} \\ & + \left( \sum_{j=1, n_i} \sum_{p=1, p_j} (a_{i,p}^j + b_{i,p}^j) \cdot (n \times H_{\text{excitation}}^{j,p}) \right)_{/\Gamma_j}. \end{aligned} \quad (8)$$

We define the Hermitian scalar product of the vectors  $u, v$ :  $\langle u, v \rangle_{\Gamma_j} = \int_{\Gamma_j} u \cdot v^* ds$ . By expressing the  $b_i^j$  coefficients associated with the outgoing waves in terms of the  $a_i^j$  coefficients associated with the incoming waves on the  $n_i$  fictitious surfaces, we obtain the following system:

$$\begin{pmatrix} b_i^1 \\ \vdots \\ b_i^{n_i} \end{pmatrix} = \begin{bmatrix} U_i^{11} & \cdot & \cdot & U_i^{1n_i} \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ U_i^{n_i 1} & \cdot & \cdot & U_i^{n_i n_i} \end{bmatrix}^{-1} \cdot \left\{ \begin{bmatrix} V_i^{11} & \cdot & \cdot & V_i^{1n_i} \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ V_i^{n_i 1} & \cdot & \cdot & V_i^{n_i n_i} \end{bmatrix} \cdot \begin{pmatrix} a_i^1 \\ \vdots \\ a_i^{n_i} \end{pmatrix} + \begin{pmatrix} I_i^1 \\ \vdots \\ I_i^{n_i} \end{pmatrix} \right\} \quad (9)$$

with the matrix and vector elements

$$I_i^j[p] = -\langle n \times H_{\text{source}}, E_p^j \rangle_{\Gamma_j} \cdot p_j \times 1 \quad \text{column vector} \quad (10)$$

$$\begin{aligned} U_i^{jj}[p, q] &= \langle n \times H_{\text{excitation}}^{j,p}, E_q^j \rangle_{\Gamma_j} \\ & + \langle n \times H_p^j, E_q^j \rangle_{\Gamma_j} \quad p_j \times p_j \quad \text{matrix} \end{aligned} \quad (11)$$

$$\begin{aligned} U_i^{kj}[p, q] &= \langle n \times H_{\text{excitation}}^{k,p}, E_q^j \rangle_{\Gamma_j} \\ & \cdot p_j \times p_k \quad \text{matrix} \quad \forall k \neq j \end{aligned} \quad (12)$$

$$\begin{aligned} V_i^{jj}[p, q] &= -\langle n \times H_{\text{excitation}}^{j,p}, E_q^j \rangle_{\Gamma_j} \\ & + \langle n \times H_p^j, E_q^j \rangle_{\Gamma_j} \quad p_j \times p_j \quad \text{matrix} \end{aligned} \quad (13)$$

$$\begin{aligned} V_i^{kj}[p, q] &= -\langle n \times H_{\text{excitation}}^{k,p}, E_q^j \rangle_{\Gamma_j} \\ & \cdot p_j \times p_k \quad \text{matrix} \quad \forall k \neq j. \end{aligned} \quad (14)$$

The scattering matrix of  $V_i$  is defined by the  $S_i = U_i^{-1} \cdot V_i$  matrix of the right hand side of equation (9). The vector  $b_{\text{source}} = U_0^{-1} \cdot I_0$  corresponds to the outgoing waves generated by the  $H_{\text{source}}$  fields in  $V_0$ .

After the scattering matrices  $S_1, \dots, S_{N_V}$  of the cavity domains have been computed, the interior domain is assembled with a standard connection scheme ([16, Appendix 1]) yielding the scattering matrix  $S_{\text{Int}}$ . Finally, the exterior domain  $V_0$  and the interior  $V_{\text{Int}}$  are assembled by identification of the outgoing waves on the fictitious surface  $\Gamma_1$ . We get the following linear system:

$$[I_d - S_0 S_{\text{Int}}] \{b_0^1\} = \{b_{\text{source}}\}. \quad (15)$$

Then, once the vector  $\{b_0^1\}$  has been determined, the total electromagnetic field is recombined on  $\partial V_0$  for all the incident waves

$$\begin{aligned} n \times H_{\partial V_0} &= (n \times H_{\text{source}})_{\partial V_0} + \sum_{j=1, n_0} \sum_{p=1, p_0} \\ & \cdot (a_{0,p}^j + b_{0,p}^j) \cdot (n \times H_{\text{excitation}}^{j,p})_{\partial V_0} \end{aligned} \quad (16)$$

$$n \times E_{\partial V_0} = \sum_{j=1, n_0} \sum_{p=1, p_0} (a_{0,p}^j + b_{0,p}^j) \cdot (n \times E_p^j). \quad (17)$$

### III. TEST CASES

#### A. Air Intake Geometry: "CHANNEL"

The geometry of this case is an evolutive channel enclosed in a circular cylinder. The entry of the channel has an elliptic cross section, the end of the channel has a circular cross section. The object is perfectly conducting. The geometry is presented in Fig. 2.

The wave vector of the incident wave for  $\phi = 0$  is directed along  $-X$ , and the electric field is parallel to  $Y$  ( $\phi\phi$  polarization) or to  $Z$  ( $\theta\theta$  polarization).

The location of  $(y_s, z_s)$  the center of the waveguide cross section is a function of  $x$

$$y_s = -0.04878 + 0.116 \sin^2 \left( \frac{\pi}{2} \frac{x}{1.360} \right); \quad z_s = 0.$$

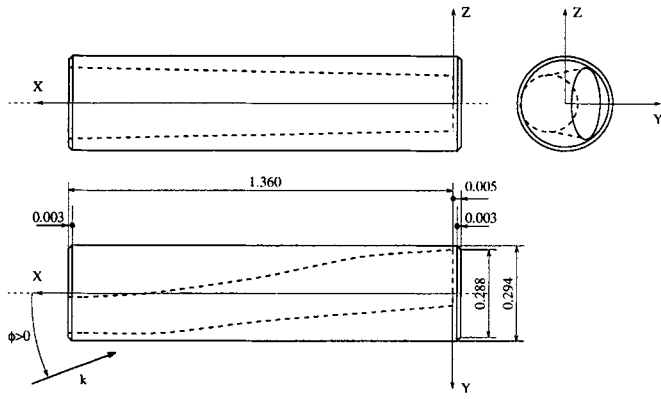


Fig. 2. Geometry of the problem (all dimensions are in meters).

The elliptic cross section is also a function of  $x$

For  $0 \leq x \leq 1.300$

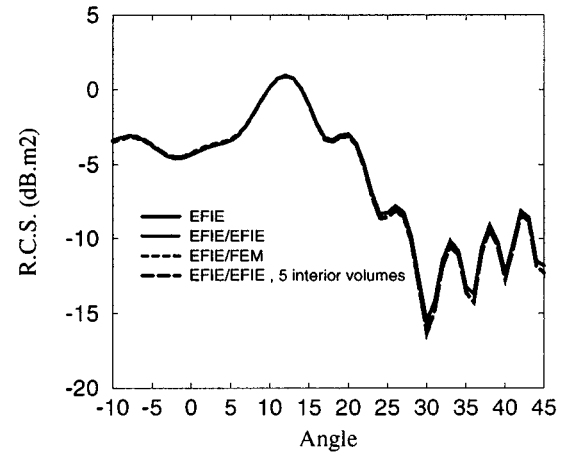
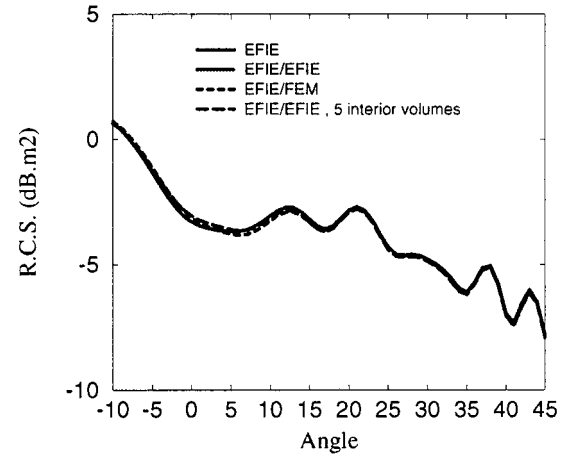
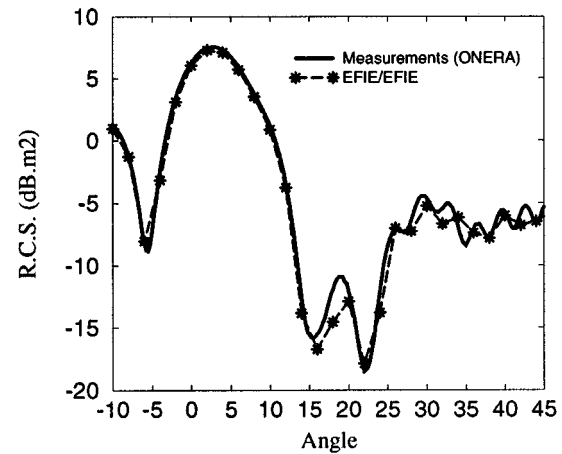
$$\left( \frac{z - z_s}{0.11803 + 0.02568 \frac{x - 1.300}{1.300}} \right)^2 + \left( \frac{y - y_s}{0.05877 - 0.03358 \frac{x - 1.300}{1.300}} \right)^2 = 1.$$

For  $1.300 \leq x \leq 1.360$

$$\left( \frac{z - z_s}{0.11803} \right)^2 + \left( \frac{y - y_s}{0.05877} \right)^2 = 1.$$

The far-field RCS is computed at 2 GHz for the two polarizations  $\theta\theta$  and  $\phi\phi$  from  $-10^\circ$  to  $45^\circ$ . The largest dimension of this case is  $9\lambda$  (33 078 unknowns). Next, we introduce a fictitious surface  $\Gamma_1$  separating  $V_0$  and  $V_{\text{Int}}$ .  $\Gamma_1$  is located at 0.075 m from the aperture. In this validation  $V_0$  has been computed with the EFIE (19 353 unknowns) and the interior domain  $V_{\text{Int}}$  has been evaluated in various different ways. First,  $V_{\text{Int}}$  has been computed as a single volume and the scattering matrix  $S_{\text{Int}}$  is computed with the EFIE (13 752 unknowns) or the FEM (87 512 unknowns). In a second step,  $V_{\text{Int}}$  is split in five domains, each scattering matrix is computed with the EFIE solver and  $S_{\text{Int}}$  is obtained with the connection algorithm. The tangent fields on the fictitious surface  $\Gamma_1$  are expanded in seven propagating modes. The two subdomains are assembled by solving a  $(7 \times 7)$  linear system of equation (15). Numerical validations of this coupling scheme have been obtained by comparison with a direct EFIE computation of the complete target. The agreement between the direct EFIE and our method is excellent (Figs. 3 and 4).

The second validation is obtained at 3 GHz. We have introduced a spherical incident wave emitted at 8.73 m from the point (0.592, 0, 0) so as to reproduce the measurement conditions (Appendix B). The target is split in two volumes  $V_0$  (39 627 unknowns) and  $V_{\text{Int}}$  (33 316 unknowns) each one computed with the EFIE. The tangent fields on  $\Gamma_1$  are expanded with 13 propagating modes. Figs. 5 and 6 show the RCS versus the angle

Fig. 3. Comparison of the far-field RCS computed for the air intake,  $\phi\phi$  polarization,  $F = 2$  GHz.Fig. 4. Comparison of the far-field RCS computed for the air intake,  $\theta\theta$  polarization,  $F = 2$  GHz.Fig. 5. Comparison of measured and computed near-field RCS for the air intake,  $\phi\phi$  polarization, and  $F = 3$  GHz.

of incidence in the  $\phi\phi$  and  $\theta\theta$  polarizations. The results are in agreement with the measurements.

The third frequency studied is 4 GHz. The largest dimension is  $18\lambda$ . A spherical incident wave is again emitted at 8.73 m away from the point (0.592, 0, 0). The mesh of the exte-

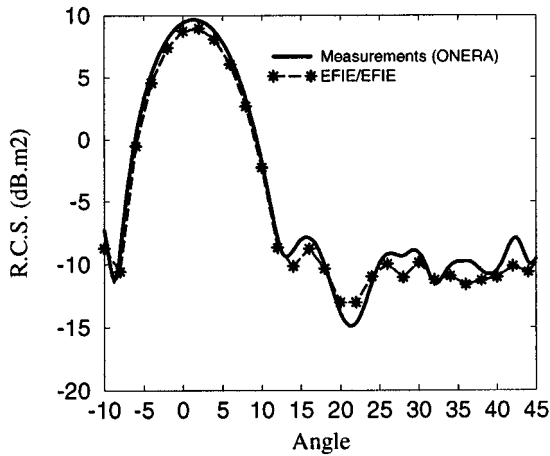


Fig. 6. Comparison of measured and computed near-field RCS for the air intake,  $\theta\theta$  polarization, and  $F = 3$  GHz.

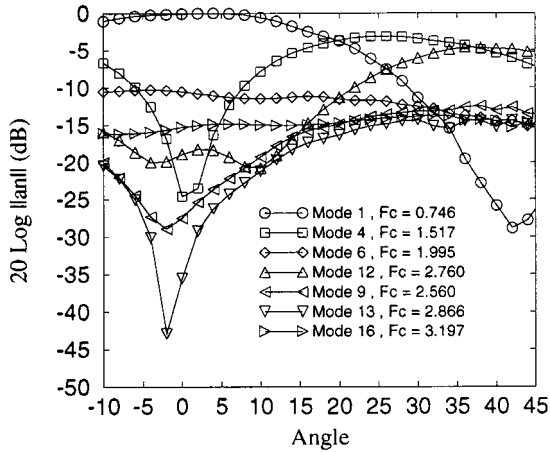


Fig. 7. "CHANNEL,"  $\phi\phi$  polarization,  $F = 4$  GHz modal decomposition on the fictitious surface  $\Gamma_1$ .

rior domain  $V_0$  leads to 64 470 surface unknowns and the scattering matrix  $S_0$  is computed with the EFIE solver. The interior inlet domain has been evaluated first with the EFIE with one volume (59 016 surface unknowns), and secondly with 20 subdomains computed with the FEM method. The total number of volume unknowns processed with the FEM is 882 465. The tangent fields on  $\Gamma_1$  were expanded with 24 propagating modes. The modal decomposition of the total electromagnetic field on  $\Gamma_1$  is obtained through equation (15) and is plotted on the Figs. 7 and 8 for all the incidence angles. These coefficients are very useful for understanding the coupling phenomena and analyzing the field propagation in the air intake. The Figs. 9 and 10 show the RCS versus the angle of incidence in the  $\phi\phi$  and  $\theta\theta$  polarizations, the agreement with the measures is again very good.

#### B. Air Intake-Engine Geometry: "CHANNEL 16 Blades"

The geometry of this case is an evolutive inlet engine enclosed in a circular cylinder. The entry of the channel has an elliptic section, the end of the channel has a circular section, which is the fictitious surface between the end of the channel and a volume containing a 16 blades rotating structure. The object is perfectly conducting. The geometry is defined by the Figs. 11(a) and (b) and 12. The wave vector of the incident wave is directed along

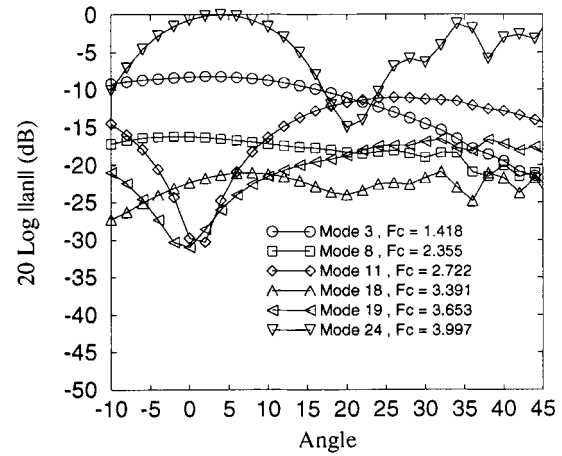


Fig. 8. "CHANNEL,"  $\theta\theta$  polarization,  $F = 4$  GHz modal decomposition on the fictitious surface  $\Gamma_1$ .

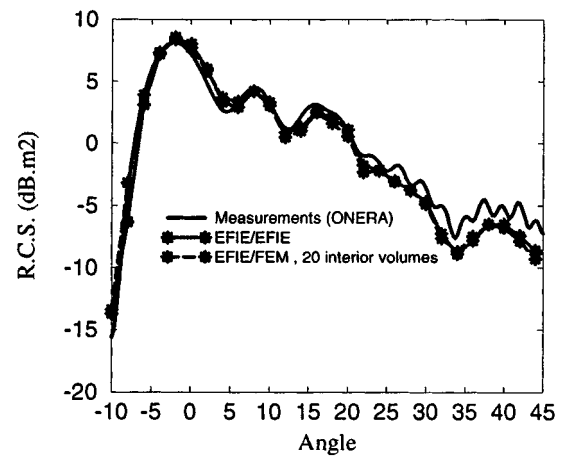


Fig. 9. Comparison of measured and computed near-field RCS for the air intake,  $\theta\theta$  polarization, and  $F = 4$  GHz.

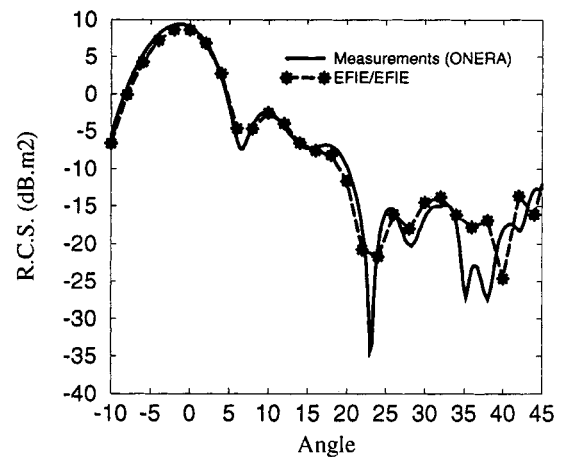


Fig. 10. Comparison of measured and computed near-field RCS for the air intake,  $\phi\phi$  polarization, and  $F = 4$  GHz.

$-X$ , and the electric field is parallel to  $Y$  ( $\phi\phi$  polarization) or to  $Z$  ( $\theta\theta$  polarization). We have introduced a spherical incident wave generated at 8.355 m from the point (0.642, 0, 0) so as to reproduce the measurement conditions. The target is split into three volumes.  $V_0$  is the exterior domain (25 806 unknowns),

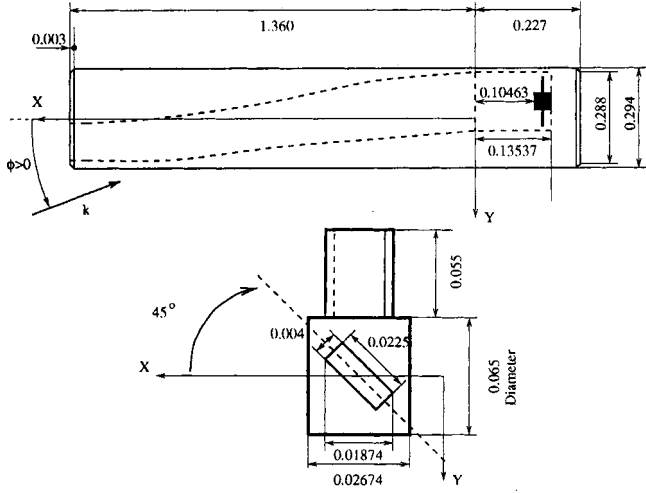


Fig. 11. (a) Geometry of the air-intake problem (all dimensions are in meters). (b) Geometry of the engine (only two blades of the 16 are shown).

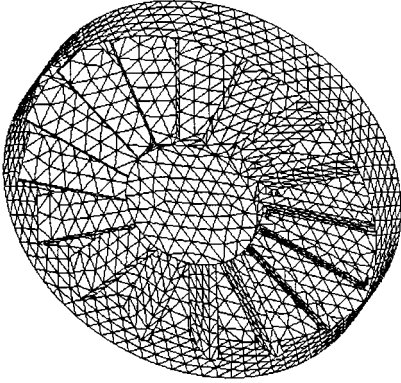


Fig. 12. Mesh of the engine volume  $V_2$ .

$V_1$  is the channel (26 850 unknowns) and  $V_2$  the engine volume (6564 unknowns). All of them are computed with the EFIE. The tangent fields on  $\Gamma_1$  are expanded with 13 propagating modes on  $\Gamma_1$  and 17 on the circular surface  $\Gamma_2$  between  $V_1$  and  $V_2$ . Figs. 13 and 14 show the RCS versus the angle of incidence in the  $\phi\phi$  and  $\theta\theta$  polarizations. The results are in agreement with the measurements.

### C. Antenna Geometry: “DENE”

The geometry of this case is a rectangular horn enclosed in a circular cylinder. The horn is fed by an electronic network. The object is perfectly conducting. The geometry is defined by Fig. 15.

The frequency of interest is 4.5 GHz. The spherical incident wave is generated at 8.71 m from the point (0, 0, 0.251) (Appendix B). The mesh of  $V_0$  leads to 32 904 surface unknowns and the scattering matrix  $S_0$  is computed with the EFIE formulation. The interior horn domain  $V_1$  has also been computed with the EFIE solver (7161 surface unknowns). The fictitious surface  $\Gamma_1$  between  $V_0$  and  $V_1$  is located at 0.033 33 m from the aperture. The tangent fields on  $\Gamma_1$  are expanded with 30 propagating modes. The vertical fundamental mode (electric field parallel to  $Y$ ) is used on the second fictitious surface  $\Gamma_2$  localized in the rectangular waveguide  $V_2$  at 0.033 33 m from the junction with

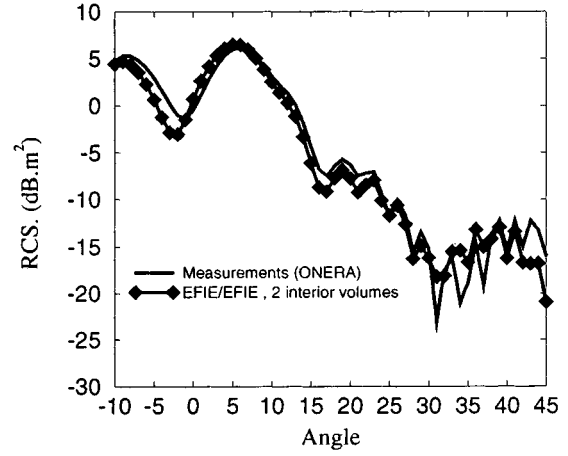


Fig. 13. Comparison of measured and computed far-field RCS for the air inlet engine,  $\phi\phi$  polarization, and  $F = 3$  GHz.

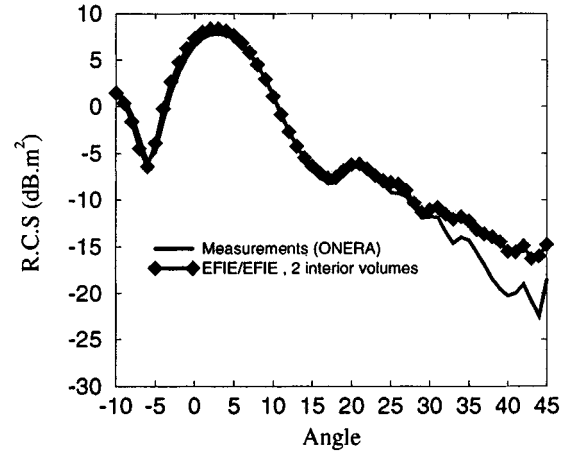


Fig. 14. Comparison of measured and computed far-field RCS for the air inlet engine,  $\theta\theta$  polarization, and  $F = 3$  GHz.

the rectangular horn. The scattering matrix  $S_2$  of  $V_2$  is measured for 23 states of the electronic network. These parameters are defined on the reference plane localized at the junction between the horn and the rectangular waveguide, i.e., at 0.0763 m from the termination of the cavity.

Fig. 16 shows the comparison between the computed and measured RCS versus the varying parameters of the electronic alimentation for an incidence angle of zero degree in the  $\theta\theta$  polarization. The results are in agreement with the measurements.

## IV. EFFICIENCY

We shall now evaluate the computational savings of this method applied to 3-D inlet-engine domains. In this particular application, the cavity has one dimension much larger than the other two. In this evaluation, we suppose that each domain is computed with a standard integral equation and that the dense linear system is factorized with a direct solver.

The total computational time is the sum of the time for the matrix generation, factorization, and solution phases. If the mesh leads to  $n_{\text{edges}}$  unknowns, the computation time  $T_0$  for  $n_{\text{incid}}$  incident waves is:  $T_0 = (C_1/2)n_{\text{edges}}^2 + (4C_2/3)n_{\text{edges}}^3 + 8C_3n_{\text{incid}}n_{\text{edges}}^2$ .

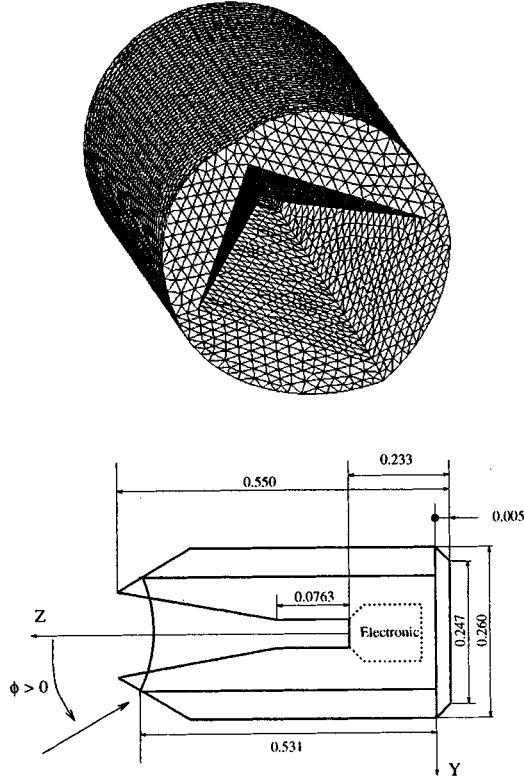


Fig. 15. Geometry of the DENEb problem (all dimensions are in meters).

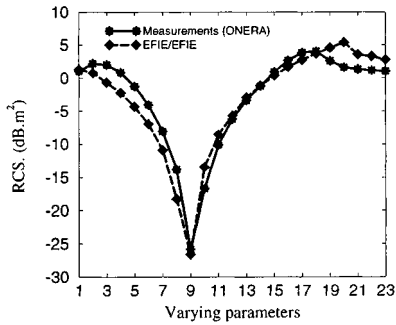


Fig. 16. Comparison of measured and computed modulated RCS for DENEb, Incidence zero degree,  $\theta\theta$  polarization, and  $F = 4.5$  GHz.

Suppose that the inlet is decomposed in  $P$  interior volumes each one possessing  $n_{\text{modes}}$  eigenmodes and  $n_f$  unknowns per fictitious surface. If the inlet is a circular cylinder of length  $L$  and radius  $R$ , we have  $n_f \simeq (3/2)(\pi R^2/\sigma)$  with  $\sigma = (\sqrt{3}/4)(\lambda/7)^2$ , and  $n_{\text{modes}} \simeq \pi(2R/\lambda)^2 + (4R/\lambda)$ . The total CPU required is approximately

$$T_P \simeq P \left\{ \frac{C_1}{2} \frac{n_{\text{edges}}^2}{P^2} + \frac{C_4}{2} \frac{n_{\text{edges}} n_f}{P} \right\} + P \left\{ \frac{4C_2}{3} \frac{n_{\text{edges}}^3}{P^3} \right\} + P \left\{ 8C_3(n_{\text{incid}} + n_{\text{modes}}) \frac{n_{\text{edges}}^2}{P^2} \right\}. \quad (18)$$

The coefficients  $C_1$ ,  $C_2$ ,  $C_3$  and  $C_4$  depend on the computer and linear solvers used. Fig. 17 shows the evolution of

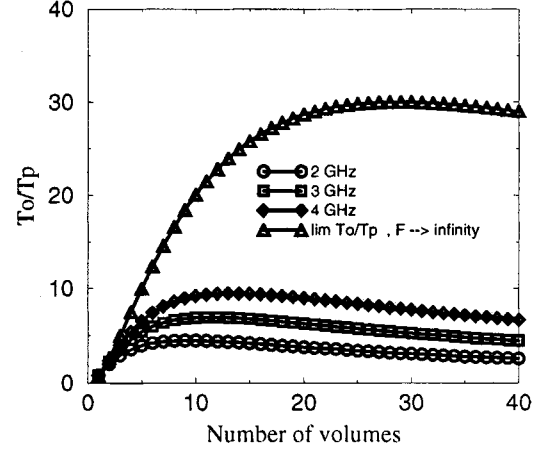


Fig. 17. Speedup of the method for inlet-engine domains.

the speedup  $T_0/T_P$  as a function of the number of internal volumes for different frequencies and with the following coefficients obtained on ONERA's NEC SX-4 supercomputer:  $C_1 = 1.1641 \cdot 10^{-9}$  h,  $C_2 = 1.4837 \cdot 10^{-13}$  h,  $C_3 = 1.5924 \cdot 10^{-13}$  h,  $C_4 = 5.6393 \cdot 10^{-9}$  h. The length and the radius of the circular cylinder are  $L = 1.363$  m and  $R = 0.9235$  m, respectively. By using waveguide modes on the fictitious surfaces, the number of right-hand sides in (6) is  $n_{\text{modes}}$  and is smaller than the fictitious surface number of unknowns  $n_f$  as in [7], [6].

In a context of parametric investigations where we need the global RCS of the target for  $K$  modifications in a volume  $V_i$ , the scattering matrices of the modified domains has to be re-evaluated, the other ones are only re-used before starting the connection step. We took advantage of this feature for all the validations proposed in this paper. Indeed, the exterior domain  $V_0$  of "CHANNEL" has been computed with the EFIE and characterized by the scattering matrix  $S_0$  only once and reused with each of the matrices  $S_{\text{Int}}$  obtained with different techniques (one EFIE domain at 2, 3, and 4 GHz, one FEM domain at 2 GHz, five EFIE domains at 2 GHz and 20 FEM domains at 4 GHz). In the "DENEb" antenna application, the exterior domain  $V_0$  and the interior horn domain  $V_1$  have been computed once and plugged into the connection scheme with the 23 measured scattering matrices of  $V_2$ . This plug and play algorithm is very efficient when using our waveguide modal expansion on the fictitious surfaces and leads to linear systems of small size both for assembling the inlet volumes and for coupling the exterior and the interior (15).

## V. CONCLUSION

In this paper, we have introduced a multidomain and multi-method technique for analyzing the electromagnetic scattering from 3-D cavities. The FEM and the EFIE are used to compute the generalized Scattering matrices of the subdomains. We have used waveguide modes for modeling the field propagation from the cavity opening down to the obstacles or the engine face. RCS patterns of various complex cavities were presented and compared to measurements to show the accuracy of this method, the reduction in computation time and the advantage of this method for parametric studies.

## APPENDIX A CONNECTION ALGORITHM

Consider two inlet-engine adjacent volumes  $V_1$  and  $V_2$  of the global decomposition (Fig. 1). The number of interfaces between these volumes is one or two. They are characterized by the scattering matrices  $[S_1]$  and  $[S_2]$

$$\begin{pmatrix} b_1^1 \\ b_1^2 \end{pmatrix} = \begin{bmatrix} S_1^{11} & S_1^{12} \\ S_1^{21} & S_1^{22} \end{bmatrix} \cdot \begin{pmatrix} a_1^1 \\ a_1^2 \end{pmatrix}$$

$$\begin{pmatrix} b_2^1 \\ b_2^2 \end{pmatrix} = \begin{bmatrix} S_2^{11} & S_2^{12} \\ S_2^{21} & S_2^{22} \end{bmatrix} \cdot \begin{pmatrix} a_2^1 \\ a_2^2 \end{pmatrix}.$$

The connection algorithm consists in eliminating the coefficients associated to the common fictitious surface. A new volume is then generated and its scattering matrix is obtained from the blocks of  $[S_1]$  and  $[S_2]$

$$S^{11} = S_1^{12} \cdot (I - S_2^{11} \cdot S_1^{22})^{-1} \cdot S_2^{11} \cdot S_1^{21} + S_1^{11} \quad (19)$$

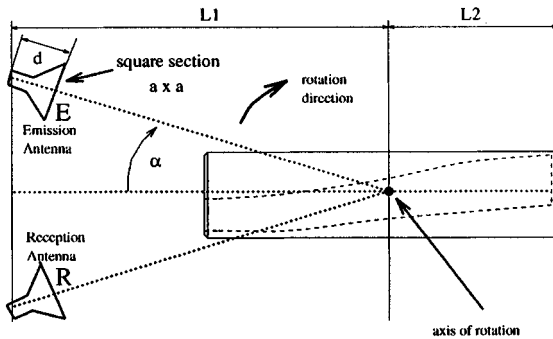
$$S^{12} = S_1^{12} \cdot (I - S_2^{11} \cdot S_1^{22})^{-1} \cdot S_2^{12} \quad (20)$$

$$S^{21} = S_2^{21} \cdot (I - S_1^{22} \cdot S_2^{11})^{-1} \cdot S_1^{21} \quad (21)$$

$$S^{22} = S_2^{21} \cdot (I - S_1^{22} \cdot S_2^{11})^{-1} \cdot S_1^{22} \cdot S_2^{12} + S_2^{22}. \quad (22)$$

## APPENDIX B

MEASUREMENT CONDITIONS (ALL DIMENSIONS ARE IN METERS)



## ACKNOWLEDGMENT

The authors would like to thank J. P. Marcellin and A. Cheraly for the definition of the CHANNEL target and the RCS measurements. They would also like to thank P. Dreuillet for the characterization of the DENEBA antenna.

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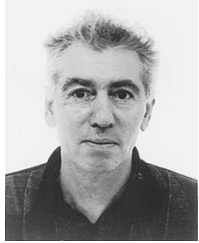
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