DISTRIBUTION FUNCTIONS AND THE RIEMANN ZETA FUNCTION*

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1. Introduction

The present paper starts with a systematic study of distribution functions in k-dimensional space and in particular of their infinite convolutions representing, in the language of the calculus of probability, the distributions arising by addition of an infinite number of independent random variables. The results are applied to almost periodic functions and in particular to the Riemann zeta function.

The proper method in dealing with distribution functions and their convolutions ("Faltungen") is the method of Fourier transforms, first applied systematically by Lévy in his book on the calculus of probability [40].† The theorems concerning Fourier transforms which we need are collected at the beginning; for proofs we refer to papers of Bochner [2] and Haviland [28, 29]. These authors use Riemann-Radon integrals; we prefer for several reasons to work with Lebesgue-Radon integrals for which the proofs are simpler. Using these results on Fourier transforms we develop a general theory of infinite convolutions and in particular their convergence theory. This theory is completed at the end of the paper, where it is shown, by means of integrals in infinitely many dimensions, that the convergence problem of infinite convolutions is identical with the convergence problem of infinite series the terms of which are independent random variables, as considered by Khintchine and Kolmogoroff [37], Kolmogoroff [38], and Lévy [41]; incidentally we obtain a new treatment of the latter problem.

The dominating feature of the convolution process is its smoothing effect, although it is hardly possible to formulate a single theorem covering the whole situation. In the cases in which we are interested an appraisal of the Fourier transforms is the natural approach to the treatment of the question. This method has recently been applied in the case of circular equidistributions by Wintner [55]; in the present paper it will be applied to the more general case of distributions on convex curves, fundamental for the treatment of the zeta function. The results thus obtained are essentially finer than those obtained through geometrical considerations by Bohr and Jessen [19].

These results are then applied to the almost periodic functions of Bohr

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[†] Numbers in brackets refer to the Bibliography at the end of this paper.

and their generalizations. Distribution problems for almost periodic functions have been considered from various points of view by several authors. Historically, we first mention the investigations of Bohr [4-14], Bohr and Courant [18], Bohr and Jessen [19, 20] and Jessen [31, 32] concerning Dirichlet series and in particular the Riemann zeta function, which are based on the theory of diophantine approximations (more particularly on the Kronecker-Weyl theorem). These investigations are methodically independent of the general theory of almost periodic functions which is, in the main, of a later date. Distribution functions for arbitrary real functions x = x(t), almost periodic in the Bohr sense, were treated by Wintner [50–54] by transforming t-averages into x-averages and then applying the moment method of the calculus of probability. It was shown by Haviland [27] that the same method is valid also if x(t) is complex-valued. In the special case of linearly independent exponents as considered by Wintner [53-55] it was essential to work not only with moments but also with Fourier transforms. It was shown by Bochner and Jessen [3] that the whole problem may be treated without applying the moment theory and considering only Fourier transforms, a method which holds in the case of generalized almost periodic functions also.

Applying this method in the present paper to the Riemann zeta function $\zeta(s) = \zeta(\sigma + it)$ we obtain with regard to the functions $\log \zeta(s)$ and $\zeta(s)$ results which are in their kind essentially more precise than those obtained so far. The distribution function of $x(t) = \log \zeta(\sigma + it)$ for a fixed $\sigma > \frac{1}{2}$ is obtained in the form of an infinite convolution. This expression for the distribution function of $\log \zeta(\sigma + it)$ occurs in a geometrical form in the papers of Bohr and Jessen [19, 20], who have proved by elementary considerations that it possesses a continuous density. In the present paper it will be shown without recourse to this result that there exists a density possessing continuous partial derivatives of arbitrarily high order. In the case $\frac{1}{2} < \sigma < 1$ it will even be shown that the density is a regular analytic function of the coordinates (which cannot be the case for $\sigma > 1$). The distribution function of $x(t) = \zeta(\sigma + it)$ itself is obtained from that of $x(t) = \log \zeta(\sigma + it)$ by an exponential mapping. The method would enable us to discuss the dependence of the densities upon σ also. In this direction we prove that the density of the distribution function of $x(t) = \log \zeta(\sigma + it)$ tends uniformly to zero as $\sigma \to \frac{1}{2}$ and we also prove an analogous result with regard to the density of the distribution function of $x(t) = \zeta(\sigma + it)$. It may be mentioned that the presentation is independent of the theory of diophantine approximations, which is replaced by a direct argument (using, of course, the same ideas as those in the proof of the Kronecker-Weyl theorem [48]).

In order to make the present paper independent of the papers mentioned

above we have included, often with simplified proofs, some of the results of these papers. There is one aspect of the distribution problem regarding almost periodic functions and the zeta function not considered in the present paper, namely the problem of the a-points, studied by Bohr, Bohr and Jessen, Favard, and Jessen. We mention only that the methods of the present paper admit of applications to this problem also. The Bibliography at the end of the paper is intended to be complete as far as distribution problems for almost periodic functions are concerned.

2. Distribution functions

Let R_x be a k-dimensional euclidean space with $x = (\xi_1, \dots, \xi_k)$ as variable point. A completely additive, non-negative set function $\phi(E)$ defined for all Borel sets E in R_x and having the value 1 for $E = R_x$ will be called a distribution function in R_x . The notation for an integral with respect to ϕ will be

$$\int_{E} f(x)\phi(dR_x).$$

All integrals are understood in the Lebesgue-Radon sense (Radon [45], pp. 1324-1329). Our notation for ordinary Lebesgue integrals will be

$$\int_E f(x)m(dR_x).$$

A set E is called a *continuity set of* ϕ if $\phi(E') = \phi(E'')$ where E' denotes the set formed by all interior points of E and E'' is the closure of E. There exists an at most enumerable set of real numbers such that at least those intervals $\alpha_i < \xi_i < \beta_i$ $(j = 1, \dots, k)$ for which the numbers α_i , β_i do not belong to this set are continuity sets of ϕ .

A sequence of distribution functions ϕ_n is said to be *convergent* if there exists a distribution function ϕ such that $\phi_n(E) \rightarrow \phi(E)$ for all continuity sets E of the limit function ϕ , which is then unique. The symbol $\phi_n \rightarrow \phi$ will be used only in this sense.

We have $\phi_n \rightarrow \phi$ if and only if the relation

$$\int_{R_x} f(x)\phi_n(dR_x) \to \int_{R_x} f(x)\phi(dR_x)$$

holds for all bounded continuous functions f(x) in R_x . Furthermore, if $\phi_n \rightarrow \phi$ then

(2.1)
$$\int_{R_x} f(x)\phi(dR_x) \leq \lim \inf \int_{R_x} f(x)\phi_n(dR_x)$$

holds for every non-negative, continuous function f(x) in R_x .

If ϕ_1 , ϕ_2 is a pair of distribution functions, a new distribution function ϕ is defined by

$$\phi(E) = \int_{R_x} \phi_1(E-x)\phi_2(dR_x).$$

Here E-x denotes the set obtained from E by the translation -x; the function $\phi_1(E-x)$ is a bounded Baire function so that the integral exists.* We call ϕ the convolution (Faltung) of ϕ_1 and ϕ_2 and denote it by $\phi = \phi_1 * \phi_2$. It may be proved directly that $\phi_1 * \phi_2 = \phi_2 * \phi_1$ and $\phi_1 * (\phi_2 * \phi_3) = (\phi_1 * \phi_2) * \phi_3$, relations which also follow from the connection with the Fourier transforms discussed in §3. For later application we notice that if $\psi_n = \phi_1 * \cdots * \phi_n$ where ϕ_1, \cdots, ϕ_n are distribution functions in R_x , and if h(x) is a non-negative Baire function in R_x then \dagger

$$(2.2) \int_{R_x} h(x) \psi_n(dR_x) = \int_{R_{x_n}} \phi_n(dR_{x_n}) \cdot \cdot \cdot \int_{R_{x_1}} h(x_1 + \cdot \cdot \cdot + x_n) \phi_1(dR_{x_1}).$$

By the spectrum $\ddagger S = S(\phi)$ of a distribution function ϕ we understand the set of those points x of R_x for which $\phi(E) > 0$ holds for any set E containing x as an interior point. S is always a closed set containing at least one point. The point spectrum $P = P(\phi)$ is defined as the set of those points x for which $\phi(x) > 0$, where x is to be understood as the Borel set consisting of the point x alone. P is at most enumerable and may be empty.

The vectorial sum A+B of two point sets A and B in R_x is defined as the set of those points in R_x which may be represented in at least one way as a vector sum a+b where a and b are points of A and B respectively. We agree to let A+B denote the empty set if at least one of the sets A and B is empty. If A and B are both closed and bounded then so is A+B. We have A+B=B+A and A+(B+C)=(A+B)+C.

$$g_n(x) = \int_{R_n} h_n(u+x)\phi_1(dR_u) \to \phi_1(E-x) = g(x)$$

for all x. Since every $g_n(x)$ is continuous it follows that g(x) is a Baire function.

^{*} That $g(x) = \phi_1(E-x)$ is a Baire function for any Borel set E follows thus: The system of sets E for which g(x) is a Baire function is a Borel field; hence it is sufficient to consider the case where E is an interval $\alpha_i < \xi_i < \beta_j$ $(j=1, \dots, k)$. Let now $h_1(x)$, $h_2(x)$, \dots be a sequence of continuous functions such that $h_n(x) = 0$ when x does not belong to E and $h_n(x) \to 1$ when x belongs to E, finally $0 \le h_n(x) \le 1$. Then

[†] It is sufficient to verify (2.2) for n=2. In this case (2.2) is trivial if h(x) is =1 in a Borel set E and =0 elsewhere. Hence (2.2) holds for any h(x) taking on but an enumerable number of values which implies that (2.2) holds for any Baire function $h(x) \ge 0$. The relation (2.2) is understood in the sense that the finiteness of either side implies that of the other.

[‡] The above terminology, proposed by Wintner [57], is in accordance with that of Wirtinger and Hilbert and is therefore not identical with that of Wiener.

Using this notation, we have for the spectrum and the point spectrum of a convolution the addition rules $S(\phi_1 * \phi_2) = S(\phi_1) + S(\phi_2)$ and $P(\phi_1 * \phi_2) = P(\phi_1) + P(\phi_2)$.

By the limit $\lim B_n$ of a sequence of point sets B_n in R_x we understand the set of those points in R_x which may be represented in at least one way as the limit of a sequence of points x_n , where x_n belongs to B_n . This limit (which may be empty) always exists and is a closed set. By the vectorial sum $A_1+A_2+\cdots$ of an infinite sequence of sets A_1, A_2, \cdots (in this order) we mean the set $\lim (A_1+\cdots+A_n)$.

If $\phi_n \rightarrow \phi$ the spectrum $S(\phi)$ is contained in $\lim S(\phi_n)$ but the two sets need not coincide. Between $P(\phi)$ and $\lim P(\phi_n)$ there is no connection.

A distribution function ϕ will be called continuous or discontinuous according as $P(\phi)$ is or is not empty. We shall say that ϕ is purely discontinuous if $\phi(P(\phi)) = 1$. A distribution function ϕ will be called singular if it is continuous and there exists a Borel set E of measure zero for which $\phi(E) = 1$. Finally, a distribution function ϕ is called absolutely continuous if $\phi(E) = 0$ for every Borel set E of measure zero; this is the case if and only if there exists in R_x a Lebesgue integrable point function D(x) such that

$$\phi(E) = \int_{E} D(x) m(dR_x)$$

for any Borel set E; we call D(x) the density of ϕ .

Any distribution function ϕ may be written (Radon [45], pp. 1321-1322) in the form $\phi(E) = \alpha_1 \phi_1(E) + \alpha_2 \phi_2(E) + \alpha_3 \phi_3(E)$ where α_1 , α_2 , α_3 are nonnegative numbers having the sum 1 and ϕ_1 , ϕ_2 , ϕ_3 are distribution functions such that ϕ_1 is purely discontinuous, ϕ_2 is singular, and ϕ_3 is absolutely continuous; the three components $\alpha_1 \phi_1$, $\alpha_2 \phi_2$, $\alpha_3 \phi_3$ are uniquely determined by ϕ .

3. Fourier transforms

Let R_y be the k-dimensional space with $y = (\eta_1, \dots, \eta_k)$ as variable point and let xy denote the scalar product of the vectors $x = (\xi_1, \dots, \xi_k)$ and $y = (\eta_1, \dots, \eta_k)$. If ϕ is a distribution function in R_x then the integral

$$\Lambda(y;\phi) = \int_{R_x} e^{ixy} \phi(dR_x)$$

defines in R_{ν} a function $\Lambda(y; \phi)$ which is uniformly continuous and bounded, the maximum of its absolute value being $\Lambda(0; \phi) = 1$. We call $\Lambda(y; \phi)$ the Fourier transform of ϕ . If $\Lambda(y; \phi) \equiv \Lambda(y; \psi)$ then $\phi = \psi$, that is, the correspond-

[†] We notice that there exist continuous distribution functions ϕ such that not every interval $\alpha_j < \xi_j < \beta_j \ (j=1,\cdots,k)$ is a continuity set of ϕ in the sense defined above.

ence between the class of all distribution functions and the class of their Fourier transforms is a one-one correspondence.

If $\phi_n \to \phi$ then $\Lambda(y; \phi_n) \to \Lambda(y; \phi)$ holds uniformly in every sphere $|y| \leq a$; conversely, if a sequence of Fourier transforms $\Lambda(y; \phi_n)$ is uniformly convergent in every sphere $|y| \leq a$ then the limit function also is the Fourier transform $\Lambda(y; \phi)$ of a distribution function ϕ and $\phi_n \to \phi$. We may formulate this fact by saying that the one-one correspondence between the class of all distribution functions and their Fourier transforms is a *continuous correspondence*.

Finally we have for the Fourier transform of a convolution the *multiplication rule* $\Lambda(y; \phi_1 * \phi_2) = \Lambda(y; \phi_1)\Lambda(y; \phi_2)$. This, together with the uniqueness of the correspondence, implies immediately the relations $\phi_1 * \phi_2 = \phi_2 * \phi_1$ and $\phi_1 * (\phi_2 * \phi_3) = (\phi_1 * \phi_2) * \phi_3$ mentioned in §2.

Let χ_c denote the distribution function whose spectrum consists of the single point c in R_x so that $\chi_c(E) = 1$ or 0 according as c is or is not contained in E; we have $\Lambda(y; \chi_c) = e^{icy}$ and in particular $\Lambda(y; \chi_0) \equiv 1$. If ψ is the distribution function $\psi(E) = \phi(E - c)$ then $\psi = \phi * \chi_c$; in particular, $\phi = \phi * \chi_0$ for every ϕ . For later application we notice that if $\phi_n \rightarrow \phi$ and $\phi_n * \psi_n \rightarrow \phi$ then $\psi_n \rightarrow \chi_0$.

If the integral

$$\int_{R_{y}} |y|^{p} |\Lambda(y;\phi) |m(dR_{y})$$

is finite for an integer $p \ge 0$ then ϕ is absolutely continuous and its density $D(x) = D(\xi_1, \dots, \xi_k)$, determined by the inversion formula

$$D(x) = (2\pi)^{-k} \int_{R_y} e^{-ixy} \Lambda(y; \phi) m(dR_y),$$

is continuous, approaches zero when $|x| \to \infty$, and possesses in the case p > 0 continuous partial derivatives of order $\leq p$ which may be obtained by differentiation under the integral sign and approach zero when $|x| \to \infty$. This is in particular the case if for some $\epsilon > 0$

(3.1)
$$\Lambda(y;\phi) = O(|y|^{-(k+p+\epsilon)}) \text{ as } |y| \to \infty.$$

[†] This is proved in the following way: We know that $\Lambda(y; \phi_n) \to \Lambda(y; \phi)$ and $\Lambda(y; \phi_n) \Lambda(y; \psi_n) \to \Lambda(y; \phi)$ hold uniformly in every sphere $|y| \leq a$ and wish to prove that $\Lambda(y; \psi_n) \to \Lambda(y; \chi_0) \equiv 1$ holds uniformly in every sphere $|y| \leq a$. This is obvious if $\Lambda(y; \phi) \neq 0$ for all y. Otherwise, since $\Lambda(0; \phi) = 1$, we know at least that $\Lambda(y; \psi_n) \to 1$ holds uniformly in a sufficiently small sphere $|y| \leq a$. Now it is clear from the definition of the Fourier transform that if for an arbitrary distribution function ψ and for some y the value $\Lambda(y; \psi)$ is near to 1 then the value $\Lambda(2y; \psi)$ is also near to 1; for that $\Lambda(y; \psi)$ is near to 1 means that e^{ixy} is near to 1 in a set E in R_x for which $\psi(E)$ is near to 1 and in this set e^{2ixy} is then also near to 1. Since $\Lambda(y; \psi_n) \to 1$ holds uniformly in $|y| \leq a$ it follows that it holds uniformly in $|y| \leq 2^m a$ which proves the theorem.

A necessary condition for the absolute continuity of ϕ is that $\Lambda(y; \phi) \rightarrow 0$ as $|y| \rightarrow \infty$ (Riemann-Lebesgue lemma).

If the estimate

(3.2)
$$\Lambda(y;\phi) = O(e^{-A|y|}) \text{ as } |y| \to \infty$$

holds for some A>0, it follows from the inversion formula by calculating the partial derivatives of $D(x)=D(\xi_1,\cdots,\xi_k)$ at an arbitrary point $x^0=(\xi_1^0,\cdots,\xi_k^0)$ of R_x that D(x) may be developed according to the powers of $\xi_1-\xi_1^0,\cdots,\xi_k-\xi_k^0$ into a power series convergent if $|\xi_1-\xi_1^0|< A/k^{1/2},\cdots,|\xi_k-\xi_k^0|< A/k^{1/2}$ so that D(x) is regular analytic in the whole real space R_x . If in particular (3.2) holds for arbitrarily large A then D(x) is an entire function of the k variables ξ_1,\cdots,ξ_k . Cf. Wintner [59].

If ϕ is such that for an integer p>0 the integral

$$M_{p}(\phi) = \int_{R_{-}} |x|^{p} \phi(dR_{x})$$

is finite, then $\Lambda(y; \phi) = \Lambda(\eta_1, \dots, \eta_k; \phi)$ possesses in R_y continuous partial derivatives of order $\leq p$ which may be obtained from the formula defining $\Lambda(y; \phi)$ by differentiation under the integral sign. These derivatives become at y=0 the *moments*

$$\mu_{q_1,\ldots,q_k}(\phi) = \int_{R_x} \xi_1^{q_1} \cdots \xi_k^{q_k} \phi(dR_x)$$

of ϕ of order $q = q_1 + \cdots + q_k \le p$, multiplied by the factor i^q . For q = 1 and q = 2 we shall use the shorter notations

$$\mu_h(\phi) = \int_{R_x} \xi_h \phi(dR_x)$$
 and $\mu_{h,j}(\phi) = \int_{R_x} \xi_h \xi_j \phi(dR_x)$.

The existence of $\mathbf{M}_{p}(\phi)$ for one value of p implies of course its existence for all smaller values of p. If $\mathbf{M}_{p}(\phi_{1})$ and $\mathbf{M}_{p}(\phi_{2})$ are finite and $\phi = \phi_{1} * \phi_{2}$, then $\mathbf{M}_{p}(\phi)$ also is finite for the inequality $|x_{1}+x_{2}|^{p} \leq 2^{p}(|x_{1}|^{p}+|x_{2}|^{p})$ implies by (2.2)

$$M_{p}(\phi) = \int_{R_{x}} |x|^{p} \phi(dR_{x}) = \int_{R_{x_{2}}} \phi_{2}(dR_{x_{1}}) \int_{R_{x_{1}}} |x_{1} + x_{2}|^{p} \phi_{1}(dR_{x_{1}})$$

$$\leq 2^{p} (M_{p}(\phi_{1}) + M_{p}(\phi_{2})).$$

If $M_1(\phi)$ is finite we denote by $c = c(\phi)$ the point in R_x having the moments of the first order $\mu_1(\phi)$, \cdots , $\mu_k(\phi)$ as its coordinates so that $c(\phi)$ is the center of gravity of the mass distribution determined by ϕ . We denote by $\tilde{\phi}$ the distribution function $\tilde{\phi}(E) = \phi(E + c(\phi))$ so that $c(\tilde{\phi}) = 0$ and $\Lambda(y; \phi)$

 $=e^{ic(\phi)} {}^{\nu}\Lambda(y;\tilde{\phi});$ the spectrum of $\tilde{\phi}$ is $S(\tilde{\phi})=S(\phi)-c(\phi)$. If $M_1(\phi_1)$ and $M_1(\phi_2)$ are finite and $\phi=\phi_1*\phi_2$, then $c(\phi)=c(\phi_1)+c(\phi_2)$ and $\tilde{\phi}=\tilde{\phi}_1*\tilde{\phi}_2$.

If $M_2(\phi)$ is finite we have $M_2(\phi) = \mu_{1,1}(\phi) + \cdots + \mu_{k,k}(\phi)$ and $M_2(\phi) = M_2(\tilde{\phi}) + |c(\phi)|^2$, hence $M_2(\tilde{\phi}) \leq M_2(\phi)$. If $M_2(\phi_1)$ and $M_2(\phi_2)$ are finite and $\phi = \phi_1 * \phi_2$ then $M_2(\tilde{\phi}) = M_2(\tilde{\phi}_1) + M_2(\tilde{\phi}_2)$.

A point set, a set function, or a point function in R_x or R_y is said to be of radial symmetry if it is invariant under all rotations about the origin. A distribution function ϕ is of radial symmetry if and only if $\Lambda(y;\phi)$ is of radial symmetry. Furthermore, if R_ξ denotes a line through x=0 and ω the distribution function in R_ξ defined by $\omega(F) = \phi(E)$, where E consists of those x of R_x the projection of which on R_ξ belongs to the given Borel set F in R_ξ , then ω is of radial symmetry and $\Lambda(y;\phi) = \Lambda(\eta,\omega)$ where $\eta = \pm |y|$. If the distribution function ϕ of radial symmetry is absolutely continuous then its density D(x) also is of radial symmetry so that $D(x) = \delta(r)$ where r = |x|. Furthermore,

$$\Lambda(y;\phi) = 2\pi (2\pi/|y|)^{k/2-1} \int_0^\infty \delta(r) r^{k/2} J_{k/2-1}(r|y|) dr$$

(Cauchy-Poisson). As to the explicit connection between ϕ and ω in the case k=2, cf. Wintner [55].

4. Convergence criteria for infinite convolutions

If ϕ_1, ϕ_2, \cdots is a sequence of distribution functions we say that the infinite convolution $\phi_1 * \phi_2 * \cdots$ is *convergent* if on placing $\psi_n = \phi_1 * \cdots * \phi_n$ there exists a distribution function ψ such that $\psi_n \to \psi$ as $n \to \infty$; we write then $\psi = \phi_1 * \phi_2 * \cdots$. Necessary and sufficient for the existence of the infinite convolution is that the infinite product $\Lambda(y; \phi_1)\Lambda(y; \phi_2) \cdots$ converges ψ uniformly in every sphere $\psi = \psi$ we have then χ we have χ as χ we have χ as χ we have

THEOREM 1. A necessary and sufficient condition for the convergence of the infinite convolution $\phi_1 * \phi_2 * \cdots$ is that $\rho_{n,p} \rightarrow \chi_0$ as $n \rightarrow \infty$ where $\rho_{n,p} = \phi_{n+1} * \cdots * \phi_{n+p}$ and p depends on n in an arbitrary way.

On placing $\psi_n = \phi_1 * \cdots * \phi_n$ we have $\psi_{n+p} = \psi_n * \rho_{n,p}$. Consequently if $\psi_n \rightarrow \psi$ we have also $\psi_n * \rho_{n,p} \rightarrow \psi$, hence $\rho_{n,p} \rightarrow \chi_0$ by a result of §3. Conversely, if $\rho_{n,p} \rightarrow \chi_0$ then $\Lambda(y; \rho_{n,p}) = \Lambda(y; \phi_{n+1}) \cdots \Lambda(y; \phi_{n+p}) \rightarrow 1$ uniformly in every sphere $|y| \leq a$, hence $\Lambda(y; \phi_1)\Lambda(y; \phi_2) \cdots$ converges uniformly in every sphere $|y| \leq a$.

 $[\]dagger$ Throughout the paper convergence of an infinite product is meant in the sense that the product of the n first factors approaches a limit so that the vanishing of the limit is not excluded.

THEOREM 2. If $\psi = \phi_1 * \phi_2 * \cdots$ is convergent, then so is $\rho_n = \phi_{n+1} * \phi_{n+2} * \cdots$ for every n and $\rho_n \rightarrow \chi_0$ as $n \rightarrow \infty$.

The convergence of $\phi_{n+1} * \phi_{n+2} * \cdots$ follows from Theorem 1. Also, $\psi_n * \rho_n = \psi$ and $\psi_n \rightarrow \psi$, hence $\rho_n \rightarrow \chi_0$.

These theorems enable us to prove that the addition rule for spectra holds for infinite convolutions also:

THEOREM 3. If $\psi = \phi_1 * \phi_2 * \cdots$ is convergent then $S(\psi) = S(\phi_1) + S(\phi_2) + \cdots$.

The theorem states that $S(\psi) = \lim S(\psi_n)$ where $\psi_n = \phi_1 * \cdots * \phi_n$. We know from §2 that $S(\psi)$ is contained in $\lim S(\psi_n)$ and shall prove that $\lim S(\psi_n)$ is contained in $S(\psi)$. Let x_0 be a point of $\lim S(\psi_n)$ and let C_{ϵ} denote the sphere $|x| < \epsilon$ where $\epsilon > 0$ is arbitrary; then $\psi_n(x_0 + C_{\epsilon}) > 0$ for n sufficiently large. Now $\psi = \psi_n * \rho_n$, hence

$$\psi(x_0 + C_{2\epsilon}) = \int_{R_x} \psi_n(x_0 + C_{2\epsilon} - x) \rho_n(dR_x) \ge \int_{C_{\epsilon}} \psi_n(x_0 + C_{2\epsilon} - x) \rho_n(dR_x)$$

$$\ge \psi_n(x_0 + C_{\epsilon}) \int_{C_{\epsilon}} \rho_n(dR_x) = \psi_n(x_0 + C_{\epsilon}) \rho_n(C_{\epsilon}).$$

Since $\rho_n \to \chi_0$ we have $\rho_n(C_{\epsilon}) \to 1$ as $n \to \infty$ for any fixed ϵ . Hence $\psi(x_0 + C_{2\epsilon}) > 0$ for any ϵ which means that x_0 belongs to $S(\psi)$.

The above proof is a generalization of a proof in Bohr and Jessen [19]. On imposing conditions on the distribution functions we obtain convergence criteria which will be used later on.

Theorem 4. If $M_2(\phi_n)$ is finite for every n then the convergence of the two series

$$c(\phi_1) + c(\phi_2) + \cdots$$
 and $M_2(\tilde{\phi}_1) + M_2(\tilde{\phi}_2) + \cdots$

implies the convergence of $\psi = \phi_1 * \phi_2 * \cdots$. Furthermore, $M_2(\psi)$ is finite; finally,

$$c(\psi) = c(\phi_1) + c(\phi_2) + \cdots$$
 and $M_2(\tilde{\psi}) = M_2(\tilde{\phi}_1) + M_2(\tilde{\phi}_2) + \cdots$.

Since $M_2(\tilde{\phi}_n) \leq M_2(\phi_n)$ is finite, $\Lambda(y; \tilde{\phi}_n)$ possesses continuous partial derivatives of order ≤ 2 and those of the first order vanish at y=0 in virtue of $c(\tilde{\phi}_n)=0$. Hence

$$\Lambda(y; \widetilde{\phi}_n) = 1 + \sum_{h=1}^k \sum_{j=1}^k \left[\Re \Lambda_{\eta_h, \eta_j}(\theta' y; \widetilde{\phi}_n) + i \Im \Lambda_{\eta_h, \eta_j}(\theta'' y; \widetilde{\phi}_n) \right] \eta_h \eta_j$$

where the subscripts denote partial differentiations and $0 < \theta' < 1$, $0 < \theta'' < 1$.

Since every partial derivative of second order of $\Lambda(y; \tilde{\phi}_n)$ has an absolute value $\leq M_2(\tilde{\phi}_n)$ we have

$$|\Lambda(y; \widetilde{\phi}_n) - 1| \leq 2k^2 \operatorname{M}_2(\widetilde{\phi}_n) |y|^2$$

which proves the convergence of $\omega = \tilde{\phi}_1 * \tilde{\phi}_{2*} \cdots$. The relation $M_2(\tilde{\phi}_1 * \cdots * \tilde{\phi}_n) = M_2(\tilde{\phi}_1) + \cdots + M_2(\tilde{\phi}_n)$ implies by (2.1) that $M_2(\omega)$ is finite, namely $\leq M_2(\tilde{\phi}_1) + M_2(\tilde{\phi}_2) + \cdots$. Now it follows from (4.1) that the derivatives of the first and second order of $\Lambda(y;\omega)$ at y=0 are the limits of the corresponding derivatives of $\Lambda(y;\tilde{\phi}_1 * \cdots * \tilde{\phi}_n)$ as $n \to \infty$, so that $c(\omega) = 0$, i.e., $\omega = \tilde{\omega}$, and $M_2(\omega) = M_2(\tilde{\phi}_1) + M_2(\tilde{\phi}_2) + \cdots$. Finally, the relation $\Lambda(y;\phi_n) = e^{ic(\phi_n)} {}^{\nu}\Lambda(y;\tilde{\phi}_n)$ and the convergence of $c(\phi_1) + c(\phi_2) + \cdots$ implies the convergence of $\psi = \phi_1 * \phi_2 * \cdots$ and also gives $c(\psi) = c(\phi_1) + c(\phi_2) + \cdots$ and $\tilde{\psi} = \omega$.

Examples show that the converse of Theorem 4 is false. We have, however, the following theorem:

THEOREM 5. If all spectra $S(\phi_n)$ are contained in a fixed sphere $|x| \leq K$ then the convergence of the two series

$$c(\phi_1) + c(\phi_2) + \cdots$$
 and $M_2(\tilde{\phi}_1) + M_2(\tilde{\phi}_2) + \cdots$

is necessary and sufficient for the convergence of $\psi = \phi_1 * \phi_2 * \cdots$.

The sufficiency is implied by Theorem 4. In order to prove the necessity we first show that the convergence of $\psi = \phi_1 * \phi_2 * \cdots$ implies the convergence of $M_2(\tilde{\phi}_1) + M_2(\tilde{\phi}_2) + \cdots$. For suppose that $M_2(\tilde{\phi}_1) + M_2(\tilde{\phi}_2) + \cdots$ is divergent; then it follows from $M_2(\tilde{\phi}_n) = \mu_{1,1}(\tilde{\phi}_n) + \cdots + \mu_{k,k}(\tilde{\phi}_n)$ that for some value of j the series $\mu_{j,j}(\tilde{\phi}_1) + \mu_{j,j}(\tilde{\phi}_2) + \cdots$ is divergent. We choose $y = (0, \dots, 0, \eta_j, 0, \dots, 0)$ so that

$$\Lambda(y; \widetilde{\phi}_n) = \int_{R_x} e^{i\xi_j \eta_j} \widetilde{\phi}_n(dR_x).$$

Instead of integrating over R_x it is sufficient to integrate over the sphere $|x| \le 2K$ which contains $S(\tilde{\phi}_n) = S(\phi_n) - c(\phi_n)$. Choose now an $\epsilon > 0$ so small that for $|t| < 2K\epsilon$

$$0 \le \cos t \le 1 - t^2/4$$
 and $\sin t = t + h(t)$ where $|h(t)| \le t^2/8$.

Then $|\xi_i \eta_i| < 2K\epsilon$ in $|x| \le 2K$ if $|\eta_i| < \epsilon$, hence

$$0 \le \Re \Lambda(y; \widetilde{\phi}_n) \le 1 - \eta_i^2 \mu_{i,i}(\widetilde{\phi}_n)/4 \text{ and } \left| \Im \Lambda(y; \widetilde{\phi}_n) \right| \le \eta_i^2 \mu_{i,i}(\widetilde{\phi}_n)/8$$

so that

$$|\Lambda(y;\phi_n)| = |\Lambda(y;\widetilde{\phi}_n)| \le 1 - \eta_j^2 \mu_{j,j}(\widetilde{\phi}_n)/8.$$

Hence the divergence of $\mu_{i,i}(\tilde{\phi}_1) + \mu_{i,i}(\tilde{\phi}_2) + \cdots$ implies that $\Lambda(y; \psi) = \Lambda(y; \phi_1)\Lambda(y; \phi_2) \cdots = 0$ for points y arbitrarily near to y = 0 and thus leads to a contradiction. Consequently $M_2(\tilde{\phi}_1) + M_2(\tilde{\phi}_2) + \cdots$ is convergent. In order to prove that $c(\phi_1) + c(\phi_2) + \cdots$ also converges we observe that by the proof of Theorem 4 the convergence of $M_2(\tilde{\phi}_1) + M_2(\tilde{\phi}_2) + \cdots$ implies the convergence of $\tilde{\phi}_1 * \tilde{\phi}_2 * \cdots$. Since $\Lambda(y; \phi_1 * \cdots * \phi_n) = e^{ic_n y} \Lambda(y; \tilde{\phi}_1 * \cdots * \tilde{\phi}_n)$ where $c_n = c(\phi_1) + \cdots + c(\phi_n)$, we conclude that $e^{ic_n y}$ tends in a sufficiently small sphere $|y| \leq a$ to a limit as $n \to \infty$. This is only possible if $c(\phi_1) + c(\phi_2) + \cdots$ converges.

The infinite convolution $\psi = \phi_1 * \phi_2 * \cdots$ will be called absolutely convergent if it is convergent in any order of the terms; the connection with the Fourier transforms shows that ψ is then also independent of the order of the terms. From Theorems 4 and 5 follows immediately

Theorem 6. If $M_2(\phi_n)$ is finite for every n, then the convergence of the two series

$$|c(\phi_1)| + |c(\phi_2)| + \cdots$$
 and $M_2(\tilde{\phi}_1) + M_2(\tilde{\phi}_2) + \cdots$

implies the absolute convergence of $\phi_1 * \phi_2 * \cdots$. If all spectra $S(\phi_n)$ are contained in a fixed sphere $|x| \leq K$ then the converse is also true.

We notice that, since $M_2(\phi_n) = M_2(\tilde{\phi}_n) + |c(\phi_n)|^2$, the convergence of the two series is equivalent to the convergence of the series

$$|c(\phi_1)| + |c(\phi_2)| + \cdots$$
 and $M_2(\phi_1) + M_2(\phi_2) + \cdots$.

Further theorems on infinite convolutions will be given in §16.

5. Convolutions of spherical equidistributions

Let the dimension number k be >1 and let S denote the sphere |x|=r where r>0. As equidistribution on S we denote the distribution function $\phi(E)$ which for a given Borel set E is the (k-1)-dimensional measure of ES, divided by that of S itself. We have $S(\phi)=S$, $c(\phi)=0$ and $M_2(\phi)=r^2$. Let S_1, S_2, \cdots denote the spheres $|x|=r_1, |x|=r_2, \cdots$, and ϕ_1, ϕ_2, \cdots the corresponding equidistributions. If $\phi_1 * \phi_2 * \cdots$ is convergent then $\phi_n \to \chi_0$ in virtue of Theorem 1, hence $r_n \to 0$. From Theorems 5 and 6 follows therefore

THEOREM 7. The convergence of the series $r_1^2 + r_2^2 + \cdots$ is necessary and sufficient both for the convergence and for the absolute convergence of the infinite convolution $\phi_1 * \phi_2 * \cdots$.

The Fourier transform $\Lambda(y; \phi)$ of the spherical equidistribution ϕ is the mean value of e^{ixy} on S. If y is fixed and x varies on S we may write $xy = r|y|\cos\theta$, $0 \le \theta \le \pi$; then $\phi(dS) = A_k \sin^{k-2}\theta d\theta$, where dS is the portion

of S corresponding to the interval $(\theta, \theta + d\theta)$ and $A_k = \pi^{-1/2} \Gamma(\frac{1}{2}k) / \Gamma(\frac{1}{2}k - \frac{1}{2})$. Hence

$$\Lambda(y;\phi) = A_k \int_0^{\tau} e^{ir|y|\cos\theta} \sin^{k-2\theta} d\theta = B_k J_{k/2-1}(r|y|)/(r|y|)^{k/2-1}$$

where $B_k = 2^{k/2-1}\Gamma(\frac{1}{2}k)$. Since $J_{\nu}(u) = O(u^{-1/2})$ as $u \to \infty$ we have

(5.1)
$$\Lambda(y;\phi) = O(|y|^{1/2-k/2}) \text{ as } |y| \to \infty.$$

Let now ϕ_1, ϕ_2, \cdots be the spherical equidistributions considered above. It follows from (5.1) that $\Lambda(y; \phi_1 * \cdots * \phi_n)$ satisfies (3.1) if n > 2(k+p)/(k-1) and that in the case of convergence $\Lambda(y; \phi_1 * \phi_2 * \cdots)$ satisfies (3.1) for every p in virtue of $|\Lambda(y; \phi_n)| \le 1$. Hence we have

THEOREM 8. The convolution $\psi_n = \phi_1 * \cdots * \phi_n$ of n spherical equidistributions is absolutely continuous with a continuous density $D_n(x)$ whenever n > 2k/(k-1), and $D_n(x) = D_n(\xi_1, \cdots, \xi_k)$ possesses continuous partial derivatives of order $\leq p$ whenever n > 2(k+p)/(k-1). If $\psi = \phi_1 * \phi_2 * \cdots$ is convergent, it is absolutely continuous and its density $D(x) = D(\xi_1, \cdots, \xi_k)$ is continuous and possesses continuous partial derivatives of all orders.

The above argument is that applied by Wintner [55] in the case k=2.

Remark. In view of the fact that the functions $\Lambda(y; \phi_1 * \cdots * \phi_n)$ are estimated by (3.1) uniformly for all n > 2(k+p)/(k-1), it follows from the uniform convergence of $\Lambda(y; \phi_1 * \cdots * \phi_n)$ to $\Lambda(y; \phi_1 * \phi_2 * \cdots)$ in any sphere $|y| \leq a$ in the case where $\phi_1 * \phi_2 * \cdots$ converges that

$$\int_{R_y} |y|^p |\Lambda(y; \phi_1 * \cdots * \phi_n) - \Lambda(y; \phi_1 * \phi_2 * \cdots) | m(dR_y) \to 0 \text{ as } n \to \infty.$$

This implies that $D_n(x)$ and its partial derivatives converge uniformly to D(x) and its partial derivatives when $n \to \infty$. In the case where the series $r_1^2 + r_2^2 + \cdots$ is divergent it may easily be shown that $\Lambda(y; \phi_1 * \cdots * \phi_n) \to 0$ uniformly for $|y| \ge \epsilon$ where $\epsilon > 0$ is arbitrarily small. This implies that

$$\int_{R_y} |y|^p |\Lambda(y; \phi_1 * \cdots * \phi_n) |m(dR_y) \to 0 \text{ as } n \to \infty,$$

so that in this case $D_n(x)$ and its partial derivatives tend uniformly to zero when $n \to \infty$. This is a more precise statement than merely saying that the infinite convolution $\phi_1 * \phi_2 * \cdots$ does not converge.

Since all ϕ_n are of radial symmetry, the same property holds for their convolutions and hence for the densities $D_n(x)$ and D(x). For the spectra $S(\phi_1 * \cdots * \phi_n) = S_1 + \cdots + S_n$ and $S(\phi_1 * \phi_2 * \cdots) = S_1 + S_2 + \cdots$ one easily finds (cf. Bohr [6])

THEOREM 9. $S(\phi_1 * \cdots * \phi_n)$ is the set $a_n \leq |x| \leq b_n$ where $b_n = r_1 + \cdots + r_n$ and $a_n = 0$ unless one of the r's in $r_1 + \cdots + r_n$, say r_1 , is larger than the sum of the other r's, in which case $a_n = r_1 - (r_2 + \cdots + r_n)$. If $r_1 + r_2 + \cdots$ is convergent then $S(\phi_1 * \phi_2 * \cdots)$ is the set $a \leq |x| \leq b$ where $b = r_1 + r_2 + \cdots$ and a = 0 unless one of the r's, say r_1 , is larger than the sum of all other r's, in which case $a = r_1 - (r_2 + r_3 + \cdots)$. If $r_1 + r_2 + \cdots$ is divergent (but $r_1^2 + r_2^2 + \cdots$ is convergent) then $S(\phi_1 * \phi_2 * \cdots)$ is the whole R_x .

Remark. It is not difficult to determine the points x for which $D_n(x)$ or D(x) is positive. We prove in this direction only that in the case where $r_1+r_2+\cdots$ is divergent D(x) is positive for all x (from $S(\phi_1*\phi_2*\cdots)=R_x$ follows only that D(x) is not identically zero in any sphere). On denoting by D'(x) and D''(x) the densities of $\phi_1*\phi_3*\cdots$ and $\phi_2*\phi_4*\cdots$ we have

$$D(x) = \int_{R_u} D'(x-u)D''(u)m(dR_u).$$

At least one of the two functions D'(x) and D''(x) is not identically zero in any sphere; since the other function is positive in some sphere, we have D(x) > 0 for every x.

For later reference we collect the main results for the case k=2 as a particular theorem.

THEOREM 10. If ϕ_n is the circular equidistribution on $|x| = r_n$ then $\psi_n = \phi_1 * \cdots * \phi_n$ is absolutely continuous with a continuous density $D_n(x)$ if n > 4 and $D_n(x) = D_n(\xi_1, \xi_2)$ possesses continuous partial derivatives of order $\leq p$ if n > 4 + 2p. The convergence of $r_1^2 + r_2^2 + \cdots$ is necessary and sufficient both for the convergence and for the absolute convergence of the infinite convolution $\phi_1 * \phi_2 * \cdots * \text{ and } \psi = \phi_1 * \phi_2 * \cdots * \text{ is then absolutely continuous and its density } D(x) = D(\xi_1, \xi_2)$ is continuous and possesses continuous partial derivatives of arbitrarily high order. Finally, D(x) > 0 for all x if $r_1 + r_2 + \cdots + c$ diverges.

Finer results regarding D(x) are contained in Theorems 15 and 16.

The results of this section could also be stated in terms of the so-called random walk problem; cf. Lord Rayleigh [46], Lüneburg [42].

6. Infinite convolutions of symmetric Bernoulli distributions

Let the dimension number k be =1. Let S denote the set consisting of the two points $x = \pm r$ where r > 0 and let $\phi(E)$ be the distribution function which is $0, \frac{1}{2}$ or 1 according as E contains neither, one or both of these points so that $\Lambda(y; \phi) = \frac{1}{2}(e^{-iry} + e^{iry}) = \cos ry$ and $S(\phi) = P(\phi) = S$. This ϕ is the analogue for k = 1 of the spherical equidistribution. We have $c(\phi) = 0$ and $M_2(\phi) = r^2$.

Hence if S_1, S_2, \cdots denote the sets $x = \pm r_1, x = \pm r_2, \cdots$ and ϕ_1, ϕ_2, \cdots the corresponding distribution functions, Theorem 7 holds again. On placing $\psi_n = \phi_1 * \cdots * \phi_n$ we have $\psi_n(E) = h/2^n$ if E contains h of the 2^n points $\pm r_1 \pm \cdots \pm r_n$ which form the spectrum $S(\psi_n) = P(\psi_n) = S_1 + \cdots + S_n$. It follows therefore from Theorem 3 that if $r_1^2 + r_2^2 + \cdots$ is convergent, so that $\psi = \phi_1 * \phi_2 * \cdots$ exists, then $S(\psi)$ is either a bounded set or the whole R_x according as $r_1+r_2+\cdots$ is convergent or divergent. Furthermore, $P(\psi)$ is always empty. For suppose that there exists a point x so that $\psi(x) > 0$. Let us write $\psi = \sigma_n * \phi_n$ where $\sigma_n = \phi_1 * \cdots * \phi_{n-1} * \phi_{n+1} * \cdots$; then $\psi(x)$ $= \frac{1}{2}(\sigma_n(x-r_n) + \sigma_n(x+r_n)) \text{ and similarly } \psi(x-2r_n) = \frac{1}{2}(\sigma_n(x-3r_n) + \sigma_n(x-r_n)),$ $\psi(x+2r_n) = \frac{1}{2}(\sigma_n(x+r_n) + \sigma_n(x+3r_n))$ so that $\psi(x-2r_n) + \psi(x+2r_n) \ge \psi(x)$. We choose a positive integer p such that $\psi(x) > 1/p$ and determine then pnumbers n_1, \dots, n_p such that $r_{n_1} > \dots > r_{n_p}$ which is possible in virtue of $r_n \rightarrow 0$. Then the numbers $x \pm r_{n_1}, \cdots, x \pm r_{n_p}$ are all distinct and the sum of the corresponding values $\psi(x-2r_{n_1})+\psi(x+2r_{n_2}), \cdots, \psi(x-2r_{n_p})+\psi(x+2r_{n_p})$ is $\geq p\psi(x) > 1$ which is impossible. This proves that $P(\psi)$ is empty, i.e., that ψ is continuous. From Theorem 35, to be proved later, we conclude therefore that ψ is either singular or absolutely continuous. On collecting our results we have

THEOREM 11. The infinite convolution $\phi_1 * \phi_2 * \cdots$, where $\phi_n(E) = 0, \frac{1}{2}$, or 1 according as E contains neither, one, or both of the points $x = \pm r_n$, is convergent, and then also absolutely convergent, if and only if the series $r_1^2 + r_2^2 + \cdots$ is convergent. The Fourier transform of $\psi = \phi_1 * \phi_2 * \cdots$ is then $\Lambda(y; \psi) = \cos(r_1 y) \cdot \cos(r_2 y) \cdot \cdots$. The spectrum $S(\psi)$ is a bounded set or the whole R_x according as the series $r_1 + r_2 + \cdots$ converges or diverges; the point spectrum $P(\psi)$ is empty and ψ is either singular or absolutely continuous.

A necessary condition for the absolute continuity of ψ is $\Lambda(y; \psi) \rightarrow 0$ as $|y| \rightarrow \infty$. It is clear that ψ is always of radial symmetry. We illustrate Theorem 11 by the following examples:

Example 1. $r_n = 3^{-n}$. Here $S(\psi)$ is the Cantor null-set in $|x| \leq \frac{1}{2}$ obtained in the usual way by successive trisections and ψ is the singular function discussed by Lebesgue. We have $\Lambda(y; \psi) = \cos(y/3) \cos(y/3^2) \cdots$, hence $\Lambda(2\pi 3^n; \psi) = \cos(2\pi/3) \cos(2\pi/3^2) \cdots \neq 0$ for all n. This is, perhaps, the simplest example of a continuous ψ for which $\Lambda(y; \psi)$ does not approach zero. With regard to this example cf. Carleman [22], pp. 223–226, Hille and Tamarkin [30].

Example 2. $r_{2n-1} = r_{2n} = 3^{-n}$. Here ψ is the convolution of the previous infinite convolution with itself. This implies that $\Lambda(y; \psi)$ does not approach zero, hence ψ is singular. The spectrum $S(\psi)$ is the interval $|x| \leq 1$. This is,

perhaps, the simplest example of a singular ψ having an interval as spectrum.

Example 3. $r_n = 2^{-n}$. Here $S(\psi)$ is the interval $|x| \le 1$ and ψ is absolutely continuous, its density D(x) being $=\frac{1}{2}$ for |x| < 1 and = 0 for |x| > 1 so that D(x) is not continuous. Placing $s(y) = (\sin y)/y$ we have

$$\Lambda(y;\psi) = \cos(y/2)\cos(y/2^2)\cdots = s(y).$$

Example 4. $r_{2n-1} = r_{2n} = 2^{-n}$. Here ψ is the convolution of the previous infinite colvolution with itself. Hence $S(\psi)$ is the interval $|x| \le 2$ and ψ is absolutely continuous, its density D(x) being $= \frac{1}{2} - \frac{1}{4} |x|$ for $|x| \le 2$ and = 0 for |x| > 2 so that D(x) is continuous.

Example 5. r_1, r_2, \cdots is a rearrangement of the double sequence $2^{-(l+m)}$ where $l, m=1, 2, \cdots$. Here $S(\psi)$ is the interval $|x| \le 1$ and $\Lambda(y; \psi) = s(y/2)s(y/2^2) \cdots$ by Example 3. Hence $\Lambda(y; \psi)$ satisfies (3.1) for every p so that ψ is absolutely continuous with a continuous density D(x) possessing continuous derivatives of arbitrarily high order.

Example 6. r_1, r_2, \cdots consists of the numbers $2^{-m!}$ where $m=1, 2, \cdots$, and contains $2^{-m!}$ exactly $2^{m!}$ times. Here $r_1^2 + r_2^2 + \cdots$ is convergent and $r_1 + r_2 + \cdots$ is divergent so that ψ exists and $S(\psi) = R_x$. It is easy to see from

$$\Lambda(2\pi 2^{m!}; \psi) = \prod_{n>m} (\cos (2\pi 2^{m!-n!}))^{2^{n!}}$$

that $\Lambda(y; \psi)$ does not approach zero; hence ψ is singular.

Example 7. $r_n = 1/n$. This is a rearrangement of the double sequence $2^{-l}/(2m+1)$ where $l, m=0,1,2,\cdots$. Hence $\Lambda(y;\psi)=s(y)s(y/3)\cdots$ by Example 3 (cf. Lévy [41], p. 154). Thus we have the same situation as in Example 5 except that $S(\psi)$ is now the whole R_x . Furthermore, the density D(x) is regular analytic in R_x (which cannot be the case in Example 5); in fact, $|s(y)| \leq \min (1, |y|^{-1})$, hence on writing $t=\frac{1}{2}|y|$ we have

$$|\Lambda(y;\psi)| \le \prod_{m=1}^{\infty} \min (1, (2m-1)|y|^{-1}) \le \prod_{m=1}^{\infty} \min (1, 2m|y|^{-1}) = \prod_{m \le t} m t^{-1}$$

so that $\Lambda(y; \psi) = O(t^{1/2}e^{-t})$, by Stirling's formula. It follows therefore from $t = \frac{1}{2} |y|$ that $\Lambda(y; \psi)$ satisfies (3.2) with every $A < \frac{1}{2}$.

Example 8. $r_n = 2^{-n}/n - 2^{-(n+1)}/(n+1)$. Here $S(\psi)$ is the null-set obtained from the interval $|x| \leq \frac{1}{2}$ by a construction identical with that leading to the Cantor null-set except that in the *n*th step the length of each of the omitted intervals is 1/(n+1) times the length of each of the 2^{n-1} intervals obtained in the (n-1)th step. The interest of this example is due to the fact that $\Lambda(y;\psi)$ approaches zero although ψ is singular. Cf. Menchoff [43].

For further results cf. Wintner [60].

The results of this section could also be stated in terms of the Rade-macher functions.

7. Fourier transforms of distributions on convex curves

Let the dimension number k be 2 and let S be a closed curve in R_x given by a parametric representation $x = x(\theta) = (\xi_1(\theta), \xi_2(\theta))$ such that $x(\theta)$ has the primitive period 1. This parametric representation of S determines in R_x a distribution function ϕ where $\phi(E)$ for a given Borel set E is the θ -measure of ES; we have $S(\phi) = S$. We call ϕ the distribution function determined by the parametric representation $x = x(\theta)$ of S. If S is the circle |x| = r given in the parametric representation $x = x(\theta) = (r \cos 2\pi\theta, r \sin 2\pi\theta)$ then ϕ is the circular equidistribution on S. In this case we know from §5 that $\Lambda(y; \phi) = O(|y|^{-1/2})$ as $|y| \to \infty$. We shall now prove that this appraisal holds for a general class of convex curves. In the case of a circular equidistribution, $\Lambda(y; \phi)$ is a function of |y| only; in the present case we have

(7.1)
$$\Lambda(y;\phi) = \int_{s} e^{ig_{\tau}(\theta)|y|} d\theta$$

where $y = (|y| \cos \tau, |y| \sin \tau)$ and $g_{\tau}(\theta) = \xi_1(\theta) \cos \tau + \xi_2(\theta) \sin \tau$.

THEOREM 12. Let $x = x(\theta) = (\xi_1(\theta), \xi_2(\theta))$ be a parametric representation of a convex curve S, such that

- (i) $\xi_1(\theta)$ and $\xi_2(\theta)$ possess continuous second derivatives $\xi_1^{\prime\prime}(\theta)$ and $\xi_2^{\prime\prime}(\theta)$;
- (ii) the second derivative $g_{\tau}^{\prime\prime}(\theta)$ with respect to θ of the function $g_{\tau}(\theta) = \xi_1(\theta) \cos \tau + \xi_2(\theta) \sin \tau$ has for every fixed value of τ exactly two zeros θ on S.

Then for the Fourier transform of the distribution function ϕ determined by the parametric representation $x = x(\theta)$ of S we have, uniformly in τ ,

$$\Lambda(y;\phi) = O(|y|^{-1/2}) \ as \ |y| \to \infty.$$

The geometrical meaning of $g_{\tau}(\theta)$ implies that $g_{\tau}'(\theta)$ has for every fixed value of τ at least two zeros on S; since between any two zeros of $g_{\tau}'(\theta)$ we find at least one zero of $g_{\tau}''(\theta)$ it follows that $g_{\tau}'(\theta)$ also has exactly two zeros which separate those of $g_{\tau}''(\theta)$ for every fixed τ .

The zeros of $g_{\tau}'(\theta)$ and $g_{\tau}''(\theta)$ depend continuously on τ . For if $\tau_n \to \tau$, every limit point of zeros of $g_{\tau_n}''(\theta)$ or $g_{\tau_n}''(\theta)$ will, by the continuity of $g_{\tau}'(\theta)$ and $g_{\tau}''(\theta)$ as functions of θ and τ together, be a zero of $g_{\tau}'(\theta)$ or $g_{\tau}''(\theta)$. Furthermore, the two zeros of $g_{\tau_n}'(\theta)$ cannot tend to the same point on S as $n \to \infty$, for then this point would also be a limit point of zeros of $g_{\tau_n}''(\theta)$, hence $g_{\tau}'(\theta)$ and $g_{\tau}''(\theta)$ would have a common zero, which is, as we saw, impossible. The same argument shows that the two zeros of $g_{\tau_n}''(\theta)$ cannot tend to the same point on S as $n \to \infty$.

We now consider, for every fixed τ , the mid-points of the four arcs on S determined by the zeros of $g_{\tau}'(\theta)$ and $g_{\tau}''(\theta)$; these mid-points also depend continuously on τ and divide S into four arcs A_{τ} , B_{τ} , C_{τ} , D_{τ} such that A_{τ} and C_{τ} each contain one of the zeros of $g_{\tau}''(\theta)$ and B_{τ} and D_{τ} each contain one of the zeros of $g_{\tau}''(\theta)$. Since the end points of A_{τ} , B_{τ} , C_{τ} , D_{τ} depend continuously on τ there exists a constant $\alpha > 0$ such that

$$(7.2) |g_{\tau}^{\prime\prime}(\theta)| \ge \alpha \text{ on } A_{\tau} \text{ and } C_{\tau} \text{ and } |g_{\tau}^{\prime}(\theta)| \ge \alpha \text{ on } B_{\tau} \text{ and } D_{\tau}.$$

Now if $f(\theta)$, $\gamma \le \theta \le \delta$, is a real-valued function possessing a continuous monotone derivative $f'(\theta)$ which is nowhere zero, then

(7.3)
$$\left| \int_{\gamma}^{\delta} e^{if(\theta)} d\theta \right| \leq 4/\min \left| f'(\theta) \right|.$$

Furthermore, if $f(\theta)$, $\gamma \le \theta \le \delta$, is a real-valued function possessing a continuous second derivative $f''(\theta)$ which is nowhere zero, then

(7.4)
$$\left| \int_{\gamma}^{\delta} e^{if(\theta)} d\theta \right| \leq 8/\min |f''(\theta)|^{1/2}.$$

The inequality (7.3) follows from the identity

$$\left| \int_{\gamma}^{\delta} e^{if(\theta)} d\theta \right| = \left| \int_{\gamma}^{\delta} \frac{\left(e^{if(\theta)} \right)'}{f'(\theta)} d\theta \right|$$

in virtue of the second mean-value theorem and (7.4) is, according to van der Corput and Landau, a consequence of (7.3); cf. Landau [39], p. 60.

On applying (7.3) and (7.4) to the four integration domains A_{τ} , B_{τ} , C_{τ} , D_{τ} and to the function $f(\theta) = g_{\tau}(\theta) |y|$, it follows from (7.1) and (7.2) that

$$|\Lambda(y;\phi)| \le 16\alpha^{-1/2} |y|^{-1/2} + 16\alpha^{-1} |y|^{-1},$$

which proves Theorem 12. Since $\alpha^{-1}|y|^{-1} \le \alpha^{-1/2}|y|^{-1/2}$ when $\alpha|y| \ge 1$, and $|\Lambda(y;\phi)| \le 1$, we find also

(7.5)
$$|\Lambda(y;\phi)| \leq 32\alpha^{-1/2}|y|^{-1/2}.$$

Let $F(z) = a_1z + a_2z^2 + \cdots$ be a power series convergent in a circle $|z| < \rho$ ($\leq \infty$) and such that $a_1 \neq 0$. Let S denote the curve $x = x(\theta) = \xi_1(\theta) + i\xi_2(\theta) = F(r e^{2\pi i \theta})$ where $0 < r < \rho$ and let ϕ be the distribution function in R_x determined by this parametric representation of S. Then $c(\phi) = 0$, i.e., $\phi = \tilde{\phi}$, and $M_2(\phi) = |a_1|^2 r^2 + |a_2|^2 r^4 + \cdots$. It is known that S is a convex curve if r is sufficiently small; condition (i) of Theorem 12 is satisfied for all r; finally if $a_n = |a_n| e^{2\pi i \gamma_n}$ we have

$$(7.6) g_{\tau}(\theta) = |a_1| r \cos 2\pi (\theta + \gamma_1 - \tau) + |a_2| r^2 \cos 2\pi (2\theta + \gamma_2 - \tau) + \cdots,$$

showing that if r is sufficiently small then condition (ii) of Theorem 12 also is satisfied. Hence there exists a positive $\rho_0(\leq \rho)$ such that all conditions of Theorem 12 are satisfied for $0 < r < \rho_0$. Finally, there exists for any given $\rho_1 < \rho_0$ a constant c > 0 such that the number $\alpha > 0$ defined by (7.2) and occurring in (7.5) may be chosen > cr if $0 < r \leq \rho_1$. This is clear from (7.6) if ρ_1 is sufficiently small; on the other hand if $\rho_1 < \rho_0$ and $\epsilon > 0$ are arbitrary then the same argument which was applied in the proof of Theorem 12 shows that the zeros of $g_r'(\theta)$ and $g_r''(\theta)$ depend continuously on τ and r together if $\epsilon \leq r \leq \rho_1$. On collecting the results we have

THEOREM 13. Let $F(z) = a_1 z + a_2 z^2 + \cdots$, where $a_1 \neq 0$, be convergent for $|z| < \rho$ ($\leq \infty$). Let S denote the curve $x = x(\theta) = F(re^{2\pi i\theta})$ where $0 < r < \rho$, and let ϕ be the distribution function in R_x determined by this parametric representation of S. Then there exists a positive ρ_0 ($\leq \rho$) such that S is convex and $\Lambda(y; \phi) = O(|y|^{-1/2})$ if $0 < r < \rho_0$. Furthermore, if $0 < \rho_1 < \rho_0$, there exists a constant β such that

$$\Lambda(\gamma; \phi) \mid \leq \beta r^{-1/2} \mid \gamma \mid^{-1/2}$$

if $0 < r \leq \rho_1$.

8. A type of infinite convolution

As an application of previous results we prove

THEOREM 14. Let $F(z) = a_1z + a_2z^2 + \cdots$, where $a_1 \neq 0$, be convergent for $|z| < \rho$ ($\leq \infty$). Let $r < \rho$ be given and let r_1, r_2, \cdots be a sequence of positive numbers such that $r_n \leq r$ for all n. Let S_n denote the curve $x = x_n(\theta) = F(r_n e^{2\pi i \theta})$ and ϕ_n the distribution function in R_x determined by this parametric representation of S_n . Then the convergence of $r_1^2 + r_2^2 + \cdots$ is necessary and sufficient for both the convergence and the absolute convergence of $\phi_1 * \phi_2 * \cdots$. The spectrum $S(\psi)$ of $\psi = \phi_1 * \phi_2 * \cdots$ is then either a bounded set or the whole R_x according as $r_1 + r_2 + \cdots$ is convergent or divergent. The distribution function ψ is always absolutely continuous with a continuous density $D(x) = D(\xi_1, \xi_2)$ possessing continuous partial derivatives of arbitrarily high order. Finally D(x) > 0 for all x if $r_1 + r_2 + \cdots$ diverges.

Since $r_n \le r < \rho$, all $S(\phi_n)$ are contained in a sufficiently large circle $|x| \le K$. Furthermore, $c(\phi_n) = 0$ so that Theorems 5 and 6 give as a necessary and sufficient condition for both the convergence and the absolute convergence of $\phi_1 * \phi_2 * \cdots$ the convergence of the series

$$\sum_{n=1}^{\infty} M_2(\phi_n) = \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} |a_m|^2 r_n^{2m}.$$

This proves the first part of the theorem. Since $r < \rho$, there exists a constant C such that $|F(z)| \le C|z|$ and $|F(z) - a_1 z| \le C|z|^2$ for $|z| \le r$. Hence if $r_1 + r_2 + \cdots$ converges, $S(\psi)$ is a bounded set. Suppose now that $r_1 + r_2 + \cdots$ diverges and let x_0 be any point of R_x . For a given $\epsilon > 0$, let p be so large that $r_{p+1}^2 + r_{p+2}^2 + \cdots < \epsilon/C$. Let x_1 be an arbitrary point of the form $F(r_1 e^{2\pi i\theta_1}) + \cdots + F(r_p e^{2\pi i\theta_p})$; then if n > p is large enough we have $|a_1|(r_{p+1} + \cdots + r_n) > |x_0 - x_1|$ and none of the numbers r_{p+1}, \cdots, r_n is larger than the sum of the n-p-1 others. As in Theorem 9 we may therefore choose $\theta_{p+1}, \cdots, \theta_n$ such that $a_1(r_{p+1}e^{2\pi i\theta_p+1} + \cdots + r_n e^{2\pi i\theta_n}) = x_0 - x_1$, implying that $|F(r_1 e^{2\pi i\theta_1}) + \cdots + F(r_n e^{2\pi i\theta_n}) - x_0| < \epsilon$. Hence the circle $|x - x_0| < \epsilon$ contains for sufficiently large n points of $s_1 + \cdots + s_n$, which means by Theorem 3 that $s_1 + s_2 + s_3 + s_4 + s_4 + s_5 + s_$

Remark. An analogous reasoning shows that if $r_n \to 0$ then $\psi_n = \phi_1 * \cdots * \phi_n$ is absolutely continuous with a continuous density $D_n(x)$ if $n > n_0$ and $D_n(x) = D_n(\xi_1, \xi_2)$ possesses continuous partial derivatives of order $\leq p$ if $n > n_p$. If $r_1^2 + r_2^2 + \cdots$ converges then $D_n(x)$ and its partial derivatives converge uniformly to D(x) and its partial derivatives, whereas they tend uniformly to zero as $n \to \infty$ if $r_1^2 + r_2^2 + \cdots$ diverges; for a proof cf. the Remark following Theorem 8.

If $r_1+r_2+\cdots$ is convergent then the density $D(x)=D(\xi_1, \xi_2)$ cannot be regular analytic in every point of the real plane R_x since $D(x)\equiv 0$ outside of the bounded set $S(\psi)$. We have, however, the following theorem:

THEOREM 15. If $r_n^{-1} = O(n)$, then the density $D(x) = D(\xi_1, \xi_2)$ defined in Theorem 14 is regular analytic in every point of the real plane R_x . If $r_n^{-1} = o(n)$, then D(x) is an entire function of the two variables ξ_1, ξ_2 .

Let $\rho_1 < \rho_0$ be fixed and let β denote the corresponding constant defined in Theorem 13. Suppose first that all $r_n \le \rho_1$. We have then $|\Lambda(y; \phi_n)| \le \beta r_n^{-1/2} |y|^{-1/2}$ for every n. Since $r_n^{-1} \le an$ for some a > 0 and $|\Lambda(y; \phi_n)| \le 1$, it follows that

$$|\Lambda(y;\phi_n)| \leq \min (1, \beta a^{1/2} n^{1/2} |y|^{-1/2}).$$

Thus on placing $t = \beta^{-2}a^{-1}|y|$ we have

$$\left| \Lambda(y; \phi_n) \right| \leq \min (1, n^{1/2}t^{-1/2}).$$

It follows therefore from

$$|\Lambda(y;\psi)| = \prod_{n=1}^{\infty} |\Lambda(y;\phi_n)| \le \prod_{n \le t} |\Lambda(y;\phi_n)|$$

that

$$|\Lambda(y;\psi)| \leq \prod_{n \leq t} \min(1, n^{1/2}t^{-1/2}) = \prod_{n \leq t} n^{1/2}t^{-1/2}$$

for every t. Hence $\Lambda(y; \psi) = O(t^{1/4}e^{-t/2})$, by Stirling's formula. We see therefore from $t = \beta^{-2}a^{-1}|y|$ that $\Lambda(y; \psi)$ satisfies (3.2) with every $A < \frac{1}{2}\beta^{-2}a^{-1}$. Let us now drop the assumption $r_n \leq \rho_1$ and let $b = \lim \sup_{n \to \infty} r_n^{-1}/n$. Then if a > b there exists an n_0 such that $r_n \leq \rho_1$ and $r_n^{-1} \leq a(n-n_0)$ for all $n > n_0$. Hence $\Lambda(y; \psi)$ satisfies again (3.2) with every $A < \frac{1}{2}\beta^{-2}a^{-1}$, which proves the first part of the theorem. If b = 0 we may take a arbitrarily small; hence $\Lambda(y; \psi)$ satisfies (3.2) for arbitrarily large A which proves the second part of the theorem.

Returning to the case of general r_n we shall now give an appraisal for the density D(x) occurring in Theorem 14.

THEOREM 16. For any $\lambda > 0$ the density D(x) defined in Theorem 14 is $= O(e^{-\lambda |x|^2})$ as $|x| \to \infty$ and each of its partial derivatives also is $= O(e^{-\lambda |x|^2})$ as $|x| \to \infty$.

The proof is based upon an argument of Paley and Zygmund [44]. Let λ be fixed, let q be a fixed positive integer so large that

$$d = 1 - 2\lambda \left| a_1 \right|^2 (r_{q+1}^2 + r_{q+2}^2 + \cdots)$$

is positive, and let n be a variable integer >q. Placing

$$s_n(\theta_1, \dots, \theta_n) = F(r_1 e^{2\pi i \theta_1}) + \dots + F(r_n e^{2\pi i \theta_n})$$

and

$$t_n(\theta_{q+1}, \cdots, \theta_n) = a_1 r_{q+1} e^{2\pi i \theta_{q+1}} + \cdots + a_1 r_n e^{2\pi i \theta_n}$$

we have

$$|s_n(\theta_1, \dots, \theta_n) - t_n(\theta_{q+1}, \dots, \theta_n)| \leq A$$

where A is a constant independent of n in virtue of the convergence of $r_1^2 + r_2^2 + \cdots$. Hence from $|s_n|^2 \le 2|s_n - t_n|^2 + 2|t_n|^2$

$$\int_{c_n} d\theta_n \cdot \cdot \cdot \int_{c_1} e^{\lambda |s_n(\theta_1, \dots, \theta_n)|^2} d\theta_1 \leq e^{2\lambda A^2} \int_{c_n} d\theta_n \cdot \cdot \cdot \int_{c_{q+1}} e^{2\lambda |t_n(\theta_{q+1}, \dots, \theta_n)|^2} d\theta_{q+1}$$

where c_r denotes the circle of length 1 on which θ_r is the variable point. Now it is known (cf., for a detailed proof, Jessen [35], pp. 290–291) that the integral on the right is

$$\leq (1-2\lambda(|a_1|^2r_{q+1}^2+\cdots+|a_1|^2r_n^2))^{-1}\leq d^{-1}$$

so that

$$\int_{c_n} d\theta_n \cdot \cdot \cdot \int_{c_1} e^{\lambda |s_n(\theta_1, \dots, \theta_n)|^2} d\theta_1 \leq K$$

where $K = e^{2\lambda A^2} d^{-1}$. Placing $h(x) = e^{\lambda |x|^2}$ in (2.2) and using the relation

$$\int_{R_{z_n}} \phi_n(dR_{z_n}) \cdot \cdot \cdot \int_{R_{z_1}} e^{\lambda |z_1 + \cdot \cdot \cdot + z_n|^2} \phi_1(dR_{z_1}) = \int_{c_n} d\theta_n \cdot \cdot \cdot \int_{c_1} e^{\lambda |s_n(\theta_1, \cdot \cdot \cdot, \theta_n)|^2} d\theta_1,$$

which is clear from the definition of ϕ_r , one obtains

$$\int_{R_x} e^{\lambda |x|^2} \psi_n(dR_x) \leq K.$$

It follows therefore from (2.1) by letting $n \rightarrow \infty$ that

$$\int_{R_x} e^{\lambda |x|^2} \psi(dR_x) \leq K.$$

Consequently if E is a bounded Borel set in R_x then $\psi(x-E) = O(e^{-\lambda |x|^2})$ as $|x| \to \infty$; in fact, if E lies in the circle of radius r about the origin then $e^{\lambda(|x|-r)^2}\psi(x-E) \le K$ if |x| > r. Similarly, if n is arbitrary and $\rho_n = \phi_{n+1} * \phi_{n+2} * \cdots$ then $\rho_n(x-E) = O(e^{-\lambda |x|^2})$ as $|x| \to \infty$ for any bounded Borel set E. Now ψ_n is by the Remark following the proof of Theorem 14 absolutely continuous with a continuous density $D_n(x)$ if $n > n_0$; hence from $\psi = \psi_n * \rho_n$

$$(8.1) D(x) = \int_{R_u} D_n(x-u) \rho_n(dR_u),$$

so that $D(x) \leq M_n \rho_n(x - S(\psi_n))$ where M_n is the maximum of $D_n(x)$. Since $S(\psi_n)$ is a bounded set it follows that $D(x) = O(e^{-\lambda |x|^2})$ as $|x| \to \infty$. Also, if p > 0 is given, $D_n(x)$ has continuous partial derivatives of order $\leq p$ for $n > n_p$ and the corresponding partial derivatives of D(x) may be obtained from (8.1) by differentiation under the integral sign. This implies that each partial derivative of D(x) is $=O(e^{-\lambda |x|^2})$ as $|x| \to \infty$.

Remark. Theorem 16 implies that $M_p(\psi)$ is finite for every p so that all moments $\mu_{q_1,q_2}(\psi)$ of ψ exist; furthermore, these moments belong to a *determined* moment problem (cf. Haviland [29]). This remark applies in particular to the infinite convolution ψ_{σ} occurring in Theorem 19.

9. VECTORIAL ADDITION OF CONVEX CURVES

In order to determine the spectrum $S(\psi)$ of the distribution function $\psi = \phi_1 * \phi_2 * \cdots$, occurring in Theorem 14, in the case where $r_1 + r_2 + \cdots$

converges and all S_n are convex, we first prove a theorem concerning the vectorial sum of n convex curves. If C is a convex curve we shall denote by I(C) and E(C) the two open domains into which C divides R_x , such that I(C) is the interior and E(C) the exterior domain, and we shall denote by I(C) and $\overline{E}(C)$ the closures of I(C) and E(C).

THEOREM 17. If S_1, \dots, S_n are n convex curves, then their vectorial sum $T_n = S_1 + \dots + S_n$ is either the closed convex domain $I(B_n)$ determined by a convex curve B_n or it is a ring-shaped domain, namely a closed convex domain $I(B_n)$ minus an open convex domain $I(A_n)$.

For n=1 the theorem is true with $B_1=A_1=S_1$. Suppose that it is true for n and let us prove it for n+1. The complementary set T_n' of T_n consists either of a single domain $E(B_n)$ or of two domains $E(B_n)$ and $I(A_n)$. Now in order that a point x shall belong to the complementary set T_{n+1}' of T_{n+1} it is necessary and sufficient that the curve $x-S_{n+1}$ belongs to T_n' . This may happen in three different ways:

- (i) it may belong to $I(A_n)$;
- (ii) it may belong to $E(B_n)$ and contain B_n in its interior;
- (iii) it may belong to $E(B_n)$ without containing B_n in its interior.
- (i) occurs only when A_n exists; it means that $I(x-S_{n+1})$ is contained in $I(A_n)$; (ii) means that $\overline{E}(x-S_{n+1})$ is contained in $E(B_n)$ and (iii) means that $I(x-S_{n+1})$ is contained in $E(B_n)$. There are always points x for which (iii) occurs whereas (i) and (ii) need not occur and are mutually exclusive. Hence it is sufficient to prove that the set of points x for which (iii) occurs is of the type $E(B_{n+1})$ where B_{n+1} is a convex curve and that the set of points x for which (i) or (ii) occurs (if such points exist) is of the type $I(A_{n+1})$ where A_{n+1} is a convex curve. This is trivial as far as (i) and (ii) are concerned; in fact if (i) is true for both $x=x_1$ and $x=x_2$ it is obviously true for any x on the segment x_1x_2 and the same holds for (ii). We therefore only need to consider the case (iii). The complementary set H to the set of points x for which (iii) occurs is the set of points for which $I(x-S_{n+1})$ and $I(B_n)$ have at least one point in common. Now $I(x-S_{n+1})=x-I(S_{n+1})$. Hence H is simply the vectorial sum of the two closed convex domains $I(B_n)$ and $I(S_{n+1})$ which is known to be a closed convex domain $I(B_{n+1})$. This completes the proof of Theorem 17.

THEOREM 18. If S_1, S_2, \cdots are convex curves surrounding the origin such that the diameter d_n of S_n tends to zero as $n \to \infty$ then the vectorial sum $T = S_1 + S_2 + \cdots$ is a bounded set if and only if the series $d_1 + d_2 + \cdots$ is convergent and T is then either a closed convex domain I(B) or a ring-shaped domain, namely a closed convex domain I(B) minus an open convex domain I(A).

With the previous notation it is clear from the proof of Theorem 17 that the curves B_1 , B_2 , \cdots all surround the origin and that B_{n+1} surrounds B_n . Hence, if n is sufficiently large B_n surrounds S_{n+1} so that the possibility (ii) is excluded. This implies that from a certain n on the existence of A_n is necessary for the existence of A_{n+1} which is then surrounded by A_n . Since the diameters of the curves B_n remain bounded if and only if the series $d_1+d_2+\cdots$ is convergent, Theorem 18 follows from $T=\lim_n T_n$.

Remark. The supporting function (Stützfunktion) of B is the sum of the supporting functions of S_1, S_2, \cdots . There is no corresponding rule for the supporting function of A and there is not even a simple rule enabling us to decide whether A exists. If, however, one of the given curves, say S_1 , surrounds all the others we have the rule that A exists if and only if there exist points x such that $x-(S_2+S_3+\cdots)$ belongs to $I(S_1)$ and these x form then the domain I(A).

Theorem 18 applies in particular to the spectrum $S(\psi)$ of the infinite convolution $\psi = \phi_1 * \phi_2 * \cdots$, occurring in Theorem 14, in the case where $r_1 + r_2 + \cdots$ is convergent and every $S(\phi_n)$ is convex.

The problem considered in this section has been studied in greater detail by Bohr [7]; cf. also Bohr and Jessen [19] and Haviland [26].

10. Distribution functions occurring in the theory of the zeta function

later application we consider the case $F(z) = z + \frac{1}{2}z^2 + \cdots$ $=-\log (1-z)$ where |z|<1. The curve S defined by the parametric representation $x = x(\theta) = \xi_1(\theta) + i\xi_2(\theta) = -\log(1 - re^{2\pi i\theta})$, where 0 < r < 1, is convex since the angle between the tangent of S at the point θ and a horizontal line through this point is, in virtue of the conformity, equal to the angle between the tangent of the circle $z = 1 - re^{2\pi i\theta}$ at the point θ and the line joining the origin with this point. Furthermore, if τ is arbitrary, the function $g_{\tau}^{\prime\prime}(\theta)$ has exactly two zeros θ on S since $g'_{\tau}(\theta)$ is a trigonometrical polynomial in $2\pi\theta$ of the first order multiplied by a non-vanishing factor. Thus the number ρ_0 defined in Theorem 13 is =1. It may be mentioned that S surrounds the origin and that its diameter d tends to zero as $r\rightarrow 0$. Also, the distribution function determined by the parametric representation of S is symmetrical with respect to the line $\xi_2 = 0$. Applying the results of §8 and §9 we prove the following theorem:

THEOREM 19. Let p_1, p_2, \cdots denote the prime numbers 2, 3, \cdots , and let $\sigma > 0$ be fixed. Let $S_{n,\sigma}$ denote the curve $x = x_{n,\sigma} = -\log (1 - p_n^{-\sigma} e^{2\pi i\theta})$ and $\phi_{n,\sigma}$ the distribution function determined by this parametric representation of $S_{n,\sigma}$. Then the infinite convolution $\phi_{1,\sigma} * \phi_{2,\sigma} * \cdots$ is convergent and also absolutely

convergent if and only if $\sigma > \frac{1}{2}$, and $\psi_{\sigma} = \phi_{1,\sigma} * \phi_{2,\sigma} * \cdots$ is then symmetric with respect to the line $\xi_2 = 0$. If $\frac{1}{2} < \sigma \le 1$, the spectrum $S(\psi_{\sigma})$ is $= R_x$; if $\sigma > 1$, it is either a closed convex domain $I(B_{\sigma})$ or a ring-shaped domain, namely a closed convex domain $I(B_{\sigma})$ minus an open convex domain $I(A_{\sigma})$. The distribution function ψ_{σ} is always absolutely continuous and its density $D_{\sigma}(x) = D_{\sigma}(\xi_1, \xi_2)$ is continuous and possesses continuous partial derivatives of all orders. If $\frac{1}{2} < \sigma \le 1$, then $D_{\sigma}(x) > 0$ for all x. For any fixed $\lambda > 0$ we have $D_{\sigma}(x) = O(e^{-\lambda |x|^2})$ as $|x| \to \infty$ and every partial derivative of $D_{\sigma}(x)$ also is $= O(e^{-\lambda |x|^2})$ as $|x| \to \infty$. Finally, if $\frac{1}{2} < \sigma < 1$, then $D_{\sigma}(x)$ is an entire function of the two variables ξ_1, ξ_2 .

The first part of the theorem follows from Theorem 14 since $\sigma > \frac{1}{2}$ is necessary and sufficient for the convergence of $p_1^{-3\sigma} + p_2^{-2\sigma} + \cdots$. The symmetry of ψ_{σ} with respect to the line $\xi_2 = 0$ is obvious. Since the condition $\sigma > 1$ is necessary and sufficient for the convergence of $p_1^{-\sigma} + p_2^{-\sigma} + \cdots$, it follows from Theorem 14 that $S(\psi_{\sigma})$ is $= R_x$ if $\sigma \le 1$ and is a bounded set if $\sigma > 1$; the description of $S(\psi_{\sigma})$ for $\sigma > 1$ follows from Theorem 18. The absolute continuity of ψ_{σ} and the properties of $D_{\sigma}(x)$ including the appraisals follow from Theorems 14 and 16. Finally, the last part of the theorem follows from Theorem 15 since $p_n^{\sigma} = o(n)$ for every $\sigma < 1$ (this is an elementary property of the prime numbers).

It is clear that $D_{\sigma}(x)$ is not regular analytic in every point of R_x if $\sigma > 1$; we do not know what is the situation if $\sigma = 1$.

Remark. By means of the Remark following the proof of Theorem 18 it is easy to obtain a more detailed description of $S(\psi_{\sigma})$ for $\sigma > 1$. The set $I(B_{\sigma})$ always contains the origin; it decreases when σ increases and the limits of $I(B_{\sigma})$ for $\sigma \to 1$ and $\sigma \to \infty$ are R_x and the point x = 0 respectively. Furthermore, A_{σ} does not exist if σ is sufficiently near to 1, say $\sigma \le \sigma_1$, while A_{σ} exists if σ is sufficiently large, say $\sigma > \sigma_2$. It is not known whether or not $\sigma_1 = \sigma_2$. Finally, $S(\psi_{\sigma})$ is symmetric not only with respect to the line $\xi_2 = 0$ but also with respect to the line $\xi_1 = -\frac{1}{2} \log (1 - p_1^{-2\sigma}) - \frac{1}{2} \log (1 - p_2^{-2\sigma}) - \cdots = \frac{1}{2} \log \zeta(2\sigma)$; this line is not a symmetry axis of ψ_{σ} .

The explicit expression for the density $D_{\sigma}(x)$ as given by the inversion formula enables us to discuss $D_{\sigma}(x)$ as a function of σ . We give only one result in this direction:

THEOREM 20. The function $D_{\sigma}(x)$ and each of its partial derivatives tend uniformly to zero as $\sigma \to \frac{1}{2}$.

The Fourier transforms $\Lambda(y; \psi_{\sigma})$ satisfy (3.1) uniformly for $\frac{1}{2} < \sigma < \sigma_0$ where $\sigma_0 > \frac{1}{2}$ is arbitrary but fixed. It is therefore sufficient to prove that $\Lambda(y; \psi_{\sigma}) \to 0$ as $\sigma \to \frac{1}{2}$ uniformly for $|y| \ge \epsilon$ where $\epsilon > 0$ is arbitrary and this is a

simple consequence of the divergence of $p_1^{-1}+p_2^{-1}+\cdots$. Cf. the Remark following Theorem 8.

Remark. It may be mentioned that since $\rho_0 = 1$, the distribution function $\psi_{n,\sigma} = \phi_{1,\sigma} * \cdots * \phi_{n,\sigma}$ is for every $\sigma > 0$ absolutely continuous with a continuous density $D_{n,\sigma}(x)$ whenever n > 4, and $D_{n,\sigma}(x) = D_{n,\sigma}(\xi_1, \xi_2)$ possesses continuous partial derivatives of order $\leq p$ whenever n > 4 + 2p. If $\sigma > \frac{1}{2}$ then $D_{n,\sigma}(x)$ and its partial derivatives tend uniformly to $D_{\sigma}(x)$ and its partial derivatives, whereas they tend uniformly to zero as $n \to \infty$ if $0 < \sigma \leq \frac{1}{2}$.

Let $x = \xi_1 + i\xi_2$ and let R_x be mapped on itself by the transformation e^x ; every point $x \neq 0$ is then the image of the enumerable set of points $\log x$. If E is an arbitrary set in R_x we denote by e^E the set of all points e^x where x belongs to E and by $\log E$ the set of all points x such that e^x belongs to E; we notice that $\log (e^E)$ is not necessarily E. If E is a Borel set, then so are the sets e^E and $\log E$. If ϕ is a distribution function in R_x , a new distribution function $\overline{\phi}$ is defined by the relation $\overline{\phi}(E) = \phi(\log E)$; the spectrum $S(\overline{\phi})$ is the closure of $e^{S(\phi)}$. The set $\log E$ being a null-set if and only if E is a null-set, the absolute continuity of one of the distribution functions ϕ and $\overline{\phi}$ implies that of the other. If D(x) and $\overline{D}(x)$ denote the densities of ϕ and $\overline{\phi}$ and if we write

$$\Delta(x) = \sum_{\mu=-\infty}^{\infty} D(x + 2\pi i\mu),$$

we have $\overline{D}(x) = |x|^{-2}\Delta(\log x)$; it does not matter that in this expression x = 0 is excluded, D(x) and $\overline{D}(x)$ being determined only up to null-functions. We have now the following theorem:

Theorem 21. Let $\overline{\psi}_{\sigma}$ be the distribution function defined by $\overline{\psi}_{\sigma}(E) = \psi_{\sigma}(\log E)$, where $\sigma > \frac{1}{2}$ and ψ_{σ} denotes the distribution function defined in Theorem 19. Then $\overline{\psi}_{\sigma}$ is symmetric with respect to the line $\xi_2 = 0$. If $\frac{1}{2} < \sigma \leq 1$ the spectrum $S(\psi_{\sigma})$ is $= R_x$; if $\sigma > 1$ then $S(\overline{\psi}_{\sigma}) = e^{S(\psi_{\sigma})}$ which is a closed bounded set not containing x = 0. The distribution function $\overline{\psi}_{\sigma}$ is always absolutely continuous and its density $\overline{D}_{\sigma}(x)$ is continuous and possesses continuous partial derivatives of any order. For $\frac{1}{2} < \sigma \leq 1$ we have $\overline{D}_{\sigma}(x) > 0$ for all $x \neq 0$, while $\overline{D}_{\sigma}(0) = 0$. Furthermore, if $\lambda > 0$ is arbitrary then $\overline{D}_{\sigma}(x) = O(e^{-\lambda(\log|x|)^2})$ as $|x| \to \infty$ or $|x| \to 0$, and every partial derivative of $\overline{D}_{\sigma}(x)$ also is $= O(e^{-\lambda(\log|x|)^2})$ as $|x| \to \infty$ or $|x| \to 0$. Finally, if $\frac{1}{2} < \sigma < 1$ then $\overline{D}_{\sigma}(e^x)$ is an entire function of the two variables ξ_1, ξ_2 .

The statements concerning $S(\overline{\psi}_{\sigma})$ and the absolute continuity of $\overline{\psi}_{\sigma}$ are obvious consequences of Theorem 19. For the density $\overline{D}_{\sigma}(x)$ we find $\overline{D}_{\sigma}(x)$ = $|x|^{-2}\Delta_{\sigma}(\log x)$ where

$$\Delta_{\sigma}(x) = \sum_{\mu=-\infty}^{\infty} D_{\sigma}(x + 2\pi i\mu).$$

From Theorem 19 we conclude that $\Delta_{\sigma}(x)$ is a continuous function of x possessing continuous partial derivatives of arbitrarily high order. Also, if $\lambda > 0$ then $\Delta_{\sigma}(x) = O(e^{-\lambda \xi_1^2})$ as $|\xi_1| \to \infty$ and every partial derivative of $\Delta_{\sigma}(x)$ also is $= O(e^{-\lambda \xi_1^2})$ as $|\xi_1| \to \infty$. This proves the continuity of $\overline{D}_{\sigma}(x)$ and the existence and continuity of its partial derivatives for $x \neq 0$. Furthermore,

$$\overline{D}_{\sigma}(x) = O(|x|^{-2}e^{-\lambda(\log|x|)^2})$$

as $|x| \to \infty$ or $|x| \to 0$, while every partial derivative of $\overline{D}_{\sigma}(x)$ of order p is $= O(|x|^{-2-p}e^{-\lambda(\log|x|)^2})$ as $|x| \to \infty$ or $|x| \to 0$. Since $\lambda > 0$ is arbitrary the factors $|x|^{-2}$ and $|x|^{-2-p}$ may be omitted. These appraisals imply the continuity of $\overline{D}_{\sigma}(x)$ and its partial derivatives at x = 0 also, at which point all these functions vanish. That $\overline{D}_{\sigma}(x) > 0$ for $x \neq 0$ if $\frac{1}{2} < \sigma \leq 1$ is clear from Theorem 19.

Placing $\psi'_{\sigma} = \phi_{1,\sigma} * \phi_{3,\sigma} * \cdots$ and $\psi'_{\sigma} = \phi_{2,\sigma} * \phi_{4,\sigma} * \cdots$ we have $\Lambda(y; \psi_{\sigma}) = \Lambda(y; \psi'_{\sigma}) \Lambda(y; \psi'_{\sigma})$, hence

$$\frac{\partial}{\partial \eta_2} \Lambda(y; \psi_{\sigma}) = \Lambda(y; \psi_{\sigma}') \frac{\partial}{\partial \eta_2} \Lambda(y; \psi_{\sigma}'') + \Lambda(y; \psi_{\sigma}'') \frac{\partial}{\partial \eta_2} \Lambda(y; \psi_{\sigma}'),$$

the existence and continuity of the partial derivatives being implied by the finiteness of $M_1(\psi_{\sigma})$, $M_1(\psi_{\sigma}')$, $M_1(\psi_{\sigma}')$, which is assured by Theorem 16. The finiteness of these numbers also implies the boundedness of the partial derivatives. Hence

$$\frac{\partial}{\partial \eta_2} \Lambda(y; \psi_{\sigma}) = O(|y|^{-q})$$

for every q. Since by the inversion formula we have for every n

$$\sum_{\mu=-n}^{n} D_{\sigma}(x+2\pi i\mu) = (2\pi)^{-2} \int_{R_{y}} e^{-ixy} \Lambda(y;\psi_{\sigma}) \frac{\sin(2n+1)\pi\eta_{2}}{\sin\pi\eta_{2}} m(dR_{y}),$$

where $y = \eta_1 + i\eta_2$, it is clear that

(10.1)
$$\Delta_{\sigma}(x) = (2\pi)^{-2} \int_{-\infty}^{\infty} \sum_{\nu=-\infty}^{\infty} e^{-ix(\eta_1+i\nu)} \Lambda(\eta_1+i\nu;\psi_{\sigma}) d\eta_1.$$

From this representation of $\Delta_{\sigma}(x)$ as a combined Fourier series and Fourier integral follows, in particular, by an argument exactly like the one applied in §3, that $\Delta_{\sigma}(x)$ is an entire function of the two variables ξ_1 , ξ_2 if $\frac{1}{2} < \sigma < 1$. This completes the proof of Theorem 21.

The last statement of Theorem 21 implies that if $\frac{1}{2} < \sigma < 1$, then $\overline{D}_{\sigma}(x)$ is regular analytic at every point $x \neq 0$ of the real plane R_x ; the point x = 0 is

actually an exception since at this point $\overline{D}_{\sigma}(x)$ and all its partial derivatives vanish.

By means of (10.1) it is easy to discuss $\overline{D}_{\sigma}(x)$ as a function of σ . We give only one result in this direction, which corresponds to Theorem 20:

THEOREM 22. The function $\overline{D}_{\sigma}(x)$ multiplied by $|x|^2$ and each of its partial derivatives of order ρ multiplied by $|x|^{2+p}$ tend uniformly to zero as $\sigma \rightarrow \frac{1}{2}$.

The theorem is equivalent to the statement that $\Delta_{\sigma}(x)$ and each of its partial derivatives tend uniformly to zero as $\sigma \to \frac{1}{2}$, which follows from (10.1) by the argument used in the proof of Theorem 20.

We do not know whether Theorem 22 holds if the factors $|x|^2$ and $|x|^{2+p}$ are omitted; we do not even know whether $\overline{\psi}_{\sigma}(E) \rightarrow 0$ as $\sigma \rightarrow \frac{1}{2}$ for any bounded set E.

11. Asymptotic distribution functions

Let G be an abstract space with t as variable point and in G let there be defined a measure m such that the system of sets A for which m(A) is defined is a Borel field and m is non-negative and completely additive; we suppose that G belongs to the system and that $m(G) = \infty$. The sets A for which m(A) is defined are called measurable sets. Lebesgue integrals with respect to m will be denoted by

$$\int_A f(t)m(dG).$$

We suppose that certain sequences A_1, A_2, \cdots consisting of measurable sets of positive finite measure such that $m(A_n) \to \infty$ have been selected and call these sequences admissible sequences. A real or complex function f(t) which is measurable in G is said to have the mean value M(f) = M(f(t)) if

$$M(f) = \lim_{n \to \infty} \frac{1}{m(A_n)} \int_{A_n} f(t) m(dG)$$

for each admissible sequence. A measurable set A in G is said to have the relative measure $\rho(A)$ if

$$\rho(A) = \lim_{n \to \infty} \frac{m(A A_n)}{m(A_n)}$$

for each admissible sequence. If $f(t) \ge 0$ is measurable in G its upper mean value $\overline{M}(f) = \overline{M}(f(t))$ is the least upper bound of

$$\lim \sup_{n \to \infty} \frac{1}{m(A_n)} \int_{A_n} f(t) m(dG)$$

for all admissible sequences. Similarly, if A is a measurable set in G its upper relative measure $\bar{\rho}(A)$ is the least upper bound of

$$\limsup_{n\to\infty}\frac{m(A\ A_n)}{m(A_n)}$$

for all admissible sequences. These notions depend, of course, on the definition of admissible sequences, which is supposed to be fixed once for all. It is clear when for a class of functions or sets the mean values or relative measures shall be said to exist uniformly for all functions or sets of the class.

Let x(t) be a measurable vector function with k components defined in G. Then if E is a Borel set in R_x , the set A_E of those points t in G for which x(t) belongs to E is measurable. We say that x(t) has an asymptotic distribution function if there exists in R_x a distribution function ϕ such that for each continuity set E of ϕ the relative measure $\rho(A_E)$ exists and is $=\phi(E)$. It is clear that there exists at most one such distribution function ϕ . The restriction imposed on E that it should be a continuity set for ϕ is essential as will be seen from later examples. Another form of the definition is the following: For a measurable set A in G of positive finite measure, let ϕ_A denote the distribution function defined by

$$\phi_A(E) = \frac{m(A_E A)}{m(A)};$$

then x(t) possesses an asymptotic distribution function ϕ if and only if $\phi_{A_n} \rightarrow \phi$ for any admissible sequence.

THEOREM 23. The vector function x(t) possesses an asymptotic distribution function ϕ if and only if the mean value $M(e^{ix(t)}v)$ exists and

(11.1)
$$M(e^{ix(t)y}) = \lim_{n \to \infty} \frac{1}{m(A_n)} \int_{A_n} e^{ix(t)y} m(dG)$$

holds uniformly in every sphere $|y| \le a$ in R_v for any admissible sequence, and we have then $\Lambda(y;\phi) = M(e^{ix(t)y})$.

For any measurable set A in G of positive finite measure we have

$$\Lambda(y;\phi_A) = \frac{1}{m(A)} \int_A e^{ix(t)u} m(dG);$$

the theorem follows therefore from §3.

A sequence of vector functions $x_1(t)$, $x_2(t)$, \cdots is said to be *convergent* in relative measure to the limit function x(t) if $\overline{p}(|x(t)-x_n(t)|>\epsilon)\to 0$ as $n\to\infty$ for every fixed $\epsilon>0$. From §3 and Theorem 23 follows immediately

THEOREM 24. If $x_1(t)$, $x_2(t)$, \cdots is a sequence of measurable vector functions which converges in relative measure to the vector function x(t) and if every $x_n(t)$ has an asymptotic distribution function ϕ_n , then x(t) also possesses an asymptotic distribution function ϕ and $\phi_n \rightarrow \phi$.

The existence of a distribution function ϕ of x(t) implies immediately the existence of the mean value M(F(x(t))) for any bounded continuous function F(x) in R_x and also gives the formula

(11.2)
$$M(F(x(t))) = \int_{R_{-}} F(x)\phi(dR_{x}).$$

Hence we conclude that if the mean value M(F(x(t))) exists for the function $F(x) = e^{ixy}$ where y is arbitrary, and if the limit relation (11.1) holds uniformly in every sphere $|y| \le a$ for any admissible sequence, then M(F(x(t))) exists for any bounded continuous function F(x) in R_x . One may start, of course, with other systems than the system of the functions $F(x) = e^{ixy}$ in order to obtain conditions for the existence of ϕ . In this direction we mention the theorem that if |x(t)| is bounded then the existence of M(F(x(t))) for any $F(x) = \xi_1^{q_1} \cdots \xi_k^{q_k}$ is necessary and sufficient for the existence of ϕ . This condition is equivalent to the one that every moment $\mu_{q_1, \dots, q_k}(\phi_A)$ approaches for any admissible sequence a limit which is then $\mu_{q_1, \dots, q_k}(\phi)$. This method still applies when |x(t)| is not bounded but such that the limits of the moments belong to a determined moment problem (cf. Wintner [49], [54] and Fréchet and Shohat [25]). Hence the moment method applies only under restrictive conditions regarding x(t) while the method of the Fourier transform applies whenever x(t) has an asymptotic distribution function.

It is sometimes of interest to establish the existence of the mean value M(F(x(t))) also for unbounded functions F(x). In this direction we have the theorem (cf. Bohr and Jessen [21]) that if x(t) has an asymptotic distribution function ϕ and if for some continuous function $H(x) \ge 0$ the upper mean value $\overline{M}(H(x(t)))$ is finite, then M(F(x(t))) exists for any continuous function F(x) satisfying the condition F(x) = o(H(x)) as $|x| \to \infty$ and (11.2) is valid.

12. Asymptotic distribution functions of almost periodic functions

Let G be the real axis $-\infty < t < \infty$ and m the Lebesgue measure on it. Two cases will be considered; in the first case an admissible sequence is an arbitrary sequence of intervals (a_n, b_n) where $b_n - a_n \to \infty$; in the second case we allow only sequences $(0, b_n)$ where $b_n \to \infty$ and sequences $(a_n, 0)$ where $a_n \to -\infty$. We shall refer to the two cases as the *unrestricted* case and the restricted case, but we shall not distinguish the two cases by the use of different

notations for mean values, relative measures, etc. The existence of an asymptotic distribution function in the unrestricted case implies of course the existence in the restricted case also.

A vector function x(t) is called almost periodic if each of its k components is almost periodic. Our notations will be those used by Besicovitch [1] so that in particular a u.a.p. function means a function almost periodic in the original sense of Bohr.

Theorem 25. Any u.a.p. vector function x(t) possesses an asymptotic distribution function in the unrestricted case.

The functions $e^{ix(t)y}$ form for $|y| \le a$ a majorisable class of u.a.p. functions; consequently the mean value

$$M(e^{ix(t)y}) = \lim_{n\to\infty} \frac{1}{b_n - a_n} \int_{a_n}^{b_n} e^{ix(t)y} dt$$

exists uniformly for $|y| \le a$ for any admissible sequence.

THEOREM 26. The spectrum $S(\phi)$ of the asymptotic distribution function ϕ of a u.a.p. vector function x(t) is the closure of the range of x(t).

Since the range of x(t) is defined as the set of those points x_0 of R_x for which $x_0 = x(t_0)$ holds for some t_0 it is clear that any point of $S(\phi)$ belongs to the closure of the range of x(t). Conversely, if $x_0 = x(t_0)$ for some t_0 then x_0 belongs to $S(\phi)$, which means that $\bar{\rho}(|x(t) - x(t_0)| < \epsilon) > 0$ for every $\epsilon > 0$. This is an easy consequence of the uniform continuity of x(t) and the fact that $|x(t) - x(t_0)| < \epsilon/2$ for a relatively dense set of values t.

A measurable vector function x(t) is Wa.p. if and only if there exists a sequence $x_1(t)$, $x_2(t)$, \cdots of u.a.p. vector functions such that

(12.1)
$$\overline{M}(|x(t) - x_n(t)|) \to 0 \text{ as } n \to \infty$$

where the upper mean value belongs to the unrestricted case. A measurable vector function x(t) is B a.p. if and only if the same holds with the sole difference that the upper mean value belongs to the restricted case.

THEOREM 27. Any W a.p. vector function x(t) possesses an asymptotic distribution function in the unrestricted case. Any B a.p. vector function possesses an asymptotic distribution function in the restricted case.

Let x(t) be W a.p.; from (12.1) and the inequality

$$\overline{p}(\mid x(t) - x_n(t) \mid > \epsilon) \leq \epsilon^{-1} \overline{M}(\mid x(t) - x_n(t) \mid)$$

we deduce

$$\bar{p}(|x(t)-x_n(t)|>\epsilon)\to 0$$
 as $n\to\infty$

where the upper relative measure belongs to the unrestricted case. Hence the result follows from Theorem 24. If x(t) is B a.p, the proof is the same with the sole difference that the upper relative measure belongs to the restricted case.

Let x(t) be an almost periodic vector function (of one of the types considered) and ϕ its asymptotic distribution function; let E be a Borel set in R_x ; then if A_E denotes the set of those points t for which x(t) belongs to E we know that $\rho(A_E)$ exists and is $=\phi(E)$ for any continuity set E of ϕ , the relative measure belonging to the unrestricted case if x(t) is W a.p. and to the restricted case if x(t) is B a.p. If E is not a continuity set of ϕ the relative measure $\rho(A_E)$ need not exist and even when it exists it need not be $=\phi(E)$. A simple example (for k=1) of the first behavior was given by Bohr [17] who constructed a u.a.p. function x(t) for which $\rho(A_E)$ does not exist (not even in the restricted case) for a certain interval E. An example of the second behavior (for k=2) is the function $x(t) = \log \zeta(\sigma + it)$ where $\sigma > 1$ is fixed; this function is u.a.p. and its asymptotic distribution function is absolutely continuous (§14); on the other hand, the range of x(t) is a null-set; hence if we take E to be the range of x(t), we have $\rho(A_E) = 1$ and $\phi(E) = 0$.

Let now E be a continuity set of ϕ and let f(t) denote the function which is 1 or 0 according as x(t) does or does not belong to E. Then we know that M(f(t)) exists and is $=\phi(E)$. It is natural to ask if f(t) is also almost periodic (in some sense). We shall prove that f(t) is W a.p. if x(t) is W a.p. and B a.p. if x(t) is B a.p. We prove this as follows: The fact that E is a continuity set of ϕ makes it possible, corresponding to any given $\epsilon > 0$, to find two continuous functions F(x) and G(x) in R_x such that $0 \le F(x) \le G(x) \le 1$ for all x, F(x) = 0 when x does not belong to E, G(x) = 1 when x belongs to E, and finally

$$\int_{R_x} (G(x) - F(x))\phi(dR_x) < \epsilon.$$

This implies $F(x(t)) \le f(t) \le G(x(t))$ and also

$$M(G(x(t)) - F(x(t))) < \epsilon$$

where the mean value belongs to the unrestricted or to the restricted case according as x(t) is W a.p. or B a.p. Now F(x(t)) and G(x(t)) are W a.p. if x(t) is W a.p. and B a.p. if x(t) is B a.p. This leads to the desired conclusion.

If x(t) is u.a.p, we find that f(t) is W a.p, and we cannot say more than this; in particular we cannot say that f(t) is S a.p. This is shown (for k=1) by the following example: Let $x_1(t)$ denote the periodic function with period 4 which is =0 for $|x| \le 1$ and = |x|-1 for $1 \le |x| \le 2$ and let $x_n(t)$ denote the function $x_n(t) = 2^{-n}x_1(2^{-n}t)$. Let x(t) be the u.a.p, function defined by the

uniformly convergent series $x(t) = x_1(t) + x_2(t) + \cdots$. Then the set x = 0 is a continuity set of the asymptotic distribution function ϕ of x(t). The corresponding function f(t) is =1 for $|x| \le 1$ and =0 elsewhere; hence f(t) is not S a.p.

The methods of this section may be extended to functions of two or more variables; for a result in this direction cf. Wintner [58].

13. Independent moduli

By the modul of a B a.p. vector function is understood the smallest modul containing the Fourier exponents of each of the k components $\xi_1(t), \dots, \xi_k(t)$ of x(t). The B a.p vector functions $x_1(t), x_2(t), \dots$ are said to have independent moduli if a finite sum $\alpha_1 + \dots + \alpha_n$, where α_r belongs to the modul of $x_r(t)$, is equal to zero only when all $\alpha_r = 0$.

THEOREM 28. If $x_1(t), \dots, x_n(t)$ are B a.p. vector functions with independent moduli then the asymptotic distribution function ϕ of $x(t) = x_1(t) + \dots + x_n(t)$ is $\phi_1 * \dots * \phi_n$ where ϕ_1, \dots, ϕ_n are the asymptotic distribution functions of $x_1(t), \dots, x_n(t)$ respectively.

The statement is that $\Lambda(y;\phi) = \Lambda(y;\phi_1) \cdots \Lambda(y;\phi_n)$ which may be written according to Theorem 23 in the form

$$M(e^{i(x_1(t)+\cdots+x_n(t))y}) = M(e^{ix_1(t)y})\cdot\cdot\cdot M(e^{ix_n(t)y})$$

where the mean values belong to the restricted case. In virtue of the approximation theorem for B a.p. functions it is enough to verify the last relation in the case where all components of $x_1(t), \dots, x_n(t)$ are exponential polynomials in which case it follows by a direct calculation.

With regard to this argument cf. Wintner [53-55], Bochner and Jessen [3]; this is the point where the explicit use of the theory of diophantine approximations is avoided as pointed out in §1.

The conditions of Theorem 28 are in particular satisfied if $x_1(t), \dots, x_n(t)$ are periodic vector functions with periods $2\pi/\lambda_1, \dots, 2\pi/\lambda_n$ where $\lambda_1, \dots, \lambda_n$ are linearly independent.

For k = 2 we have as a simple application

THEOREM 29. Let r_1, r_2, \cdots be positive, $\lambda_1, \lambda_2, \cdots$ linearly independent, and $\delta_1, \delta_2, \cdots$ real. Then the asymptotic distribution function of $s_n(t) = r_1 e^{i(\lambda_1 t + \delta_1)} + \cdots + r_n e^{i(\lambda_n t + \delta_n)}$ is the distribution function $\psi_n = \phi_1 * \cdots * \phi_n$ described in Theorem 10. If $r_1 e^{i(\lambda_1 t + \delta_1)} + r_2 e^{i(\lambda_2 t + \delta_2)} + \cdots$ is the Fourier series of a B a.p. function s(t), then $r_1^2 + r_2^2 + \cdots$ is convergent and the asymptotic distribution function of s(t) is the distribution function $\psi = \phi_1 * \phi_2 * \cdots$ described in Theorem 10. Finally, if s(t) is bounded then $r_1 + r_2 + \cdots$ converges.

The first part of the theorem is an immediate consequence of Theorem 28 since the asymptotic distribution function of a pure oscillation $re^{i(\lambda t + \delta)}$ is the circular equidistribution on |x| = r. The second part of the theorem is clear from the relation

$$M(\mid s(t) - s_n(t) \mid) \to 0$$
 as $n \to \infty$

where the mean value belongs to the restricted case; this relation is a consequence of the approximation theorem for B a.p. functions .Use is made of the linear independence of the exponents. Finally, the last part of the theorem follows from Theorem 10 since the boundedness of s(t) implies the boundedness of $S(\psi)$. In this last part of the theorem is contained the classical theorem of Bohr that the Fourier series of a u.a.p. function with linearly independent exponents is absolutely convergent; it is interesting that the original proof of Bohr [16], without using the notion of a distribution function, was built precisely on the same ideas as the present proof.

It is interesting that the smoothness of the asymptotic distribution function ψ of s(t) established by Theorem 29 does not imply any smoothness for s(t) itself. In fact (cf. Wintner [56]), if $r_n = a^n$, $\lambda_n = b^n$ and $\delta_n = 0$ where 0 < a < 1, $ab \ge 1$ and b is a transcendental number, then s(t) is u.a.p. with linearly independent exponents but is nowhere differentiable.

14. THE RIEMANN ZETA FUNCTION

We now consider the Riemann zeta function $\zeta(s) = \zeta(\sigma + it)$. In the halfplane $\sigma > 1$ we have

$$\zeta(s) = \prod_{n=1}^{\infty} (1 - p_n^{-s})^{-1}$$

where p_1, p_2, \cdots denote the primes 2, 3, \cdots ; in particular, $\zeta(s) \neq 0$ for $\sigma > 1$. We write

$$\zeta_n(s) = \prod_{\nu=1}^n (1 - p_{\nu}^{-s})^{-1};$$

 $\zeta_n(s)$ is regular and $\neq 0$ for $\sigma > 0$. By $\log \zeta(s)$ and $\log \zeta_n(s)$ we denote the functions

$$\log \zeta(s) = \sum_{n=1}^{\infty} -\log (1 - p_n^{-s})$$

and

$$\log \zeta_n(s) = \sum_{n=1}^n -\log (1-p_n^{-s}),$$

where in each term on the right $-\log (1-z) = z + \frac{1}{2}z^2 + \cdots$. The function $\log \zeta(s)$ is regular for $\sigma > 1$ and $\log \zeta_n(s)$ for $\sigma > 0$. By H we denote the domain obtained from the half-plane $\sigma > \frac{1}{2}$ by leaving out the segment $\frac{1}{2} < \sigma \le 1$, t = 0, and all segments $\frac{1}{2} < \sigma \le \sigma_0$, $t = t_0$, where $\sigma_0 + it_0$ denote the zeros (if any) of $\zeta(s)$ in $\sigma > \frac{1}{2}$; by $\log \zeta(s)$ for $\sigma > \frac{1}{2}$ we understand the analytic continuation of $\log \zeta(s)$ in H. For any fixed $\sigma > 1$ the functions $\zeta(\sigma + it)$ and $\log \zeta(\sigma + it)$ are both u.a.p.; similarly, $\zeta_n(\sigma + it)$ and $\log \zeta_n(\sigma + it)$ are u.a.p. for any fixed $\sigma > 0$ and tend uniformly to $\zeta(\sigma + it)$ and $\log \zeta(\sigma + it)$ if $\sigma > 1$. For any fixed $\sigma > \frac{1}{2}$ the function $\zeta(\sigma + it)$ is B^2 a.p. and

$$M(|\zeta(\sigma+it)-\zeta_n(\sigma+it)|^2)\to 0 \text{ as } n\to\infty$$
,

where the mean value belongs to the restricted case. This follows, e.g., from a result of Besicovitch [1], pp. 163–169, but is in the main of an older date. In the case $\sigma = 1$ it is necessary in all integrations to leave out a vicinity of the pole t = 0. Finally, it was proved by Bohr [12] that if $\sigma > \frac{1}{2}$ is fixed then

$$\bar{\rho}(|\log \zeta(\sigma+it) - \log \zeta_n(\sigma+it)| > \epsilon) \to 0 \text{ as } n \to \infty$$

for any $\epsilon > 0$; the upper relative measure belongs to the restricted case.

Using our previous results we can now prove very easily

THEOREM 30. The function $\log \zeta(\sigma+it)$ possesses an asymptotic distribution function in the unrestricted case if $\sigma > 1$ and in the restricted case if $\frac{1}{2} < \sigma \le 1$. This asymptotic distribution function is the distribution function $\psi_{\sigma} = \phi_{1,\sigma} * \phi_{2,\sigma} * \cdots$ described in Theorems 19 and 20. The closure of the range of $\log \zeta(\sigma+it)$ is $S(\psi_{\sigma})$.

The first part of the theorem follows from Theorems 25 and 24. In order to prove the second part of the theorem we first observe that if S denotes the curve $x=x(\theta)=-\log (1-re^{2\pi i\theta})$ where 0 < r < 1, and if ϕ is the distribution function in R_x determined by this parametric representation of S, then ϕ is also for an arbitrary $\lambda \neq 0$ the asymptotic distribution function of the function $-\log (1-re^{i\lambda t})$. Now if $\sigma>0$ then

$$\log \zeta_n(\sigma + it) = \sum_{\nu=1}^n -\log (1 - p_{\nu}^{-\sigma} e^{-i\log p_{\nu}t});$$

since the numbers $\log p_1, \dots, \log p_n$ are linearly independent it follows from Theorem 28 that $\log \zeta_n(\sigma+it)$ has the asymptotic distribution function $\phi_{1,\sigma} * \cdots * \phi_{n,\sigma}$. The second part of the theorem follows then by Theorem 24. Finally, the last part of the theorem is a consequence of Theorem 26 if $\sigma > 1$ and is clear if $\frac{1}{2} < \sigma \le 1$ since $S(\psi_{\sigma})$ is then the whole R_x .

For $\zeta(s)$ itself we have a corresponding result:

THEOREM 31. The function $\zeta(\sigma+it)$ possesses an asymptotic distribution function in the unrestricted case if $\sigma>1$ and in the restricted case if $\frac{1}{2}<\sigma\leq 1$. This asymptotic distribution function is the distribution function ψ_{σ} described in Theorems 21 and 22. The closure of the range of $\zeta(\sigma+it)$ is $S(\psi_{\sigma})$.

The first part of the theorem follows from Theorems 25 and 27; the second part is an immediate consequence of the definition of $\overline{\psi}_{\sigma}$; finally, the last part of the theorem is a consequence of Theorem 26 if $\sigma > 1$ and is clear if $\frac{1}{2} < \sigma \le 1$ since $S(\overline{\psi}_{\sigma})$ is then the whole R_x .

It is clear that the relations

$$\bar{D}_{\sigma}(0) = 0; \quad \bar{D}_{\sigma}(x) > 0, \quad x \neq 0$$
 $(\frac{1}{2} < \sigma \le 1)$

may be interpreted as an illustration to the Riemann hypothesis.

15. Measure and integration in product spaces

We obtain further results concerning infinite convolutions by using the theory of measure and integration in product spaces of an infinite number of spaces. In the present section we collect some of the results of this theory. These results are proved for a special case in Jessen [35] where references to the literature are to be found. The proofs for the general case will be given by Jessen in a forthcoming paper.

Let Q be an abstract space with t as variable point and let there be defined in Q a measure m such that the system of sets A for which m(A) is defined is a Borel field and m is non-negative and completely additive. We suppose that Q itself belongs to the field and that m(Q) = 1. The sets A for which m(A) is defined are called measurable sets; Lebesgue integrals with respect to m are denoted by

$$\int_A f(t)m(dQ).$$

It is well known that if q_1 and q_2 are two spaces of the type described before, with τ_1 and τ_2 as variable points and with μ_1 and μ_2 as measures, then these measures generate in the product space $Q = (q_1, q_2)$ with the variable point $t = (\tau_1, \tau_2)$ a measure $m = (\mu_1, \mu_2)$ in the following way. The system of sets in Q for which m is defined is the smallest Borel field containing all sets $A = (a_1, a_2)$ of Q where a_1 and a_2 are measurable sets in q_1 and q_2 respectively and m is characterized by the property that if $A = (a_1, a_2)$ then $m(A) = \mu_1(a_1)\mu_2(a_2)$. For integrals with respect to m we have Fubini's theorem

(15.1)
$$\int_{Q} f(t)m(dQ) = \int_{a} \mu_{2}(dq_{2}) \int_{a} f(\tau_{1}, \tau_{2})\mu_{1}(dq_{1}).$$

Let q_1, q_2, \cdots be a finite or infinite sequence of abstract spaces of the type described above, with τ_1, τ_2, \cdots as variable points and μ_1, μ_2, \cdots as measures. Let Q denote the space $Q = (q_1, q_2, \cdots)$ where $t = (\tau_1, \tau_2, \cdots)$ is the variable point; then the measures μ_1, μ_2, \cdots generate a measure $m = (\mu_1, \mu_2, \cdots)$ in Q in the following way. The system of sets in Q for which m is defined is the smallest Borel field containing all sets $A = (a_1, a_2, \cdots)$, where a_1, a_2, \cdots are measurable sets in q_1, q_2, \cdots respectively and m is characterized by the property that for sets of this type we have $m(A) = \mu_1(a_1)\mu_2(a_2) \cdots$.

Suppose now that the sequence q_1, q_2, \cdots is infinite; then we may for every n consider the space $Q_n = (q_1, \dots, q_n)$ with $t_n = (\tau_1, \dots, \tau_n)$ as variable point and with $m_n = (\mu_1, \dots, \mu_n)$ as measure and the space $Q_{n,\omega} = (q_{n+1}, q_{n+2}, \dots)$ with $t_{n,\omega} = (\tau_{n+1}, \tau_{n+2}, \dots)$ as variable point and $m_{n,\omega} = (\mu_{n+1}, \mu_{n+2}, \dots)$ as measure. Then $Q = (q_1, q_2, \dots) = (Q_n, Q_{n,\omega}), t = (\tau_1, \tau_2, \dots) = (t_n, t_{n,\omega})$ and it is easily seen that $m = (\mu_1, \mu_2, \dots) = (m_n, m_{n,\omega})$. Hence if f(t) is integrable in Q we have

$$\int_{Q} f(t)m(dQ) = \int_{Q_{n}} m_{n}(dQ_{n}) \int_{Q_{n,\omega}} f(t_{n}, t_{n,\omega})m_{n,\omega}(dQ_{n,\omega})$$

$$= \int_{Q_{n,\omega}} m_{n,\omega}(dQ_{n,\omega}) \int_{Q_{n}} f(t_{n}, t_{n,\omega})m_{n}(dQ_{n})$$

for every n. We have now the following theorems:

THEOREM A. Let f(t) be integrable in Q and let $f_n(t)$ denote the function

$$f_n(t) = \int_{Q_{n,\omega}} f(t_n, t_{n,\omega}) m_{n,\omega}(dQ_{n,\omega})$$

so that $f_n(t)$ depends only on t_n . Then $f_n(t) \rightarrow f(t)$ almost everywhere in Q as $n \rightarrow \infty$.

THEOREM B. Let A be a measurable set in Q with the property that two points $t' = (\tau_1', \tau_2', \cdots)$ and $t'' = (\tau_1'', \tau_2'', \cdots)$ such that $\tau_n' = \tau_n''$ when $n > n_0 = n_0(t', t'')$ always either both belong to A or both do not belong to A. Then m(A) is either 0 or 1.

THEOREM C. Let f(t) be integrable in Q and let $f_{n,\omega}(t)$ denote the function

$$f_{n,\omega}(t) = \int_{Q_n} f(t_n, t_{n,\omega}) m_n(dQ_n)$$

so that $f_{n,\omega}(t)$ depends only on $t_{n,\omega}$. Then $f_{n,\omega}(t) \to I$ almost everywhere in Q as $n \to \infty$ where I is the constant

$$I = \int_{Q} f(t)m(dQ).$$

16. The convergence problem of infinite convolutions

Let Q be an abstract space of the type considered at the beginning of §15 and let x(t) be a measurable vector function with k components defined on Q. Then if E is a Borel set in R_x the set A_E of those points t for which x(t) belongs to E is a measurable set in Q. The distribution function ϕ in R_x defined by $\phi(E) = m(A_E)$ will be called the distribution function of x(t) in Q. For the Fourier transform of ϕ we have

(16.1)
$$\Lambda(y;\phi) = \int_{Q} e^{ix(t)y} m(dQ).$$

For later application we notice that any distribution function ϕ in R_x is the distribution function of a measurable vector function x(t) in a suitable abstract space Q. The simplest possibility is to choose Q as R_x itself, except for the change in the notation for the variable point, and to choose ϕ as measure in Q. Then x(t) = t is a measurable vector function in Q and ϕ is its distribution function.

Let $Q = (q_1, q_2)$ and let $x_1(\tau_1)$ and $x_2(\tau_2)$ be measurable vector functions with k components in q_1 and q_2 and having the distribution functions ϕ_1 and ϕ_2 . Then the distribution function ϕ of $x(t) = x_1(\tau_1) + x_2(\tau_2)$ in Q is $\phi = \phi_1 * \phi_2$. This follows readily from the definitions and is obvious also from (15.1) and (16.1) which imply $\Lambda(y; \phi) = \Lambda(y; \phi_1)\Lambda(y; \phi_2)$. We shall now prove that a corresponding theorem holds for infinite convolutions also:

THEOREM 32. A necessary and sufficient condition for the convergence of the infinite convolution $\phi_1 * \phi_2 * \cdots$ is that if q_1, q_2, \cdots are abstract spaces and $x_1(\tau_1), x_2(\tau_2), \cdots$ measurable functions in q_1, q_2, \cdots having the distribution functions ϕ_1, ϕ_2, \cdots , then the series $x_1(\tau_1) + x_2(\tau_2) + \cdots$ is convergent almost everywhere in $Q = (q_1, q_2, \cdots)$. The distribution function of $s(t) = x_1(\tau_1) + x_2(\tau_2) + \cdots$ is then $\psi = \phi_1 * \phi_2 * \cdots$.

The sum $s_n(t) = x_1(\tau_1) + \cdots + x_n(\tau_n)$ is for every n a measurable vector function in Q and its distribution function is $\psi_n = \phi_1 * \cdots * \phi_n$. Similarly, the distribution function of $r_{n,p}(t) = x_{n+1}(\tau_{n+1}) + \cdots + x_{n+p}(\tau_{n+p})$ is $\rho_{n,p} = \phi_{n+1} * \cdots * \phi_{n+p}$. From Theorem 1 a necessary and sufficient condition for the convergence of $\phi_1 * \phi_2 * \cdots$ is that $\rho_{n,p} \to \chi_0$ as $n \to \infty$, which means that $r_{n,p}(t) \to 0$ in measure (en mesure) as $n \to \infty$. Hence the convergence in measure of the series $x_1(\tau_1) + x_2(\tau_2) + \cdots$ is necessary and sufficient for the convergence of $\phi_1 * \phi_2 * \cdots$, and it is also seen from (16.1) that the sum $s(t) = x_1(\tau_1) + x_2(\tau_2) + \cdots$ has then $\psi = \phi_1 * \phi_2 * \cdots$ as distribution function. Since convergence almost everywhere implies convergence in measure, it remains only to prove that for series of the type $x_1(\tau_1) + x_2(\tau_2) + \cdots$ con-

vergence in measure implies convergence almost everywhere. If $s(t) = x_1(\tau_1) + x_2(\tau_2) + \cdots$ is convergent in measure then

$$e^{is(t)y} = e^{ix_1(\tau_1)}ye^{ix_2(\tau_2)}y \cdot \cdot \cdot$$

also holds in the sense of convergence in measure for every y in R_y . For a fixed y we write $f(t) = e^{is(t)y}$; then f(t) is measurable and bounded, hence integrable, so that we may apply Theorem A. We find

$$f_n(t) = e^{ix_1(\tau_1)y} \cdot \cdot \cdot e^{ix_n(\tau_n)y}a_n$$

where the constant $a_n \rightarrow 1$ as $n \rightarrow \infty$; hence

$$e^{is(t)y} = e^{ix_1(\tau_1)}y_e^{ix_2(\tau_2)}y \dots$$

holds in the sense of convergence almost everywhere for every y, which shows that $x(t) = x_1(\tau_1) + x_2(\tau_2) + \cdots$ is convergent almost everywhere.

Since the set A of points t in Q in which a series of the form $x_1(\tau_1) + x_2(\tau_2) + \cdots$ is convergent satisfies the conditions of Theorem B, we have also

THEOREM 33. An infinite series $x_1(\tau_1) + x_2(\tau_2) + \cdots$ whose terms are measurable vector functions is always either convergent almost everywhere or divergent almost everywhere.

Theorems 32 and 33 together give, when translated into the language of the calculus of probability, a new solution of the convergence problem for series $x_1+x_2+\cdots$ whose terms are independent random variables; this problem (for k=1) was first treated by Khintchine and Kolmogoroff [37] and later by Kolmogoroff [38] and Lévy [41]. Theorem 33 states that the probability for convergence is always either 0 or 1 and Theorem 32 shows that the probability is 1 if and only if the distribution function ψ_n of $s_n=x_1+\cdots+x_n$ tends to a distribution function ψ when $n\to\infty$. Combining Theorem 5 with a remark due to Khintchine and Kolmogoroff, we find also the main result of these authors, which we formulate as a convergence criterion for infinite convolutions. Denoting by C_K the sphere $|x| \le K$ and by $\phi_{n,K}$ the distribution function for which $\phi_{n,K}(E)$ is $=\phi_n(EC_K)+1-\phi_n(C_K)$ or $=\phi_n(EC_K)$ according as E does or does not contain the point x=0, we have

THEOREM 34. A necessary and sufficient condition for the convergence of the infinite convolution $\phi_1 * \phi_2 * \cdots$ is the convergence of the three series

$$(1 - \phi_1(C_K)) + (1 - \phi_2(C_K)) + \cdots,$$

$$c(\phi_{1,K}) + c(\phi_{2,K}) + \cdots \quad and \quad M_2(\tilde{\phi}_{1,K}) + M_2(\tilde{\phi}_{2,K}) + \cdots$$

for a fixed K>0 (or for all K>0).

With the notation of Theorem 32, let $x_{n,K}(\tau_n)$ be $=x_n(\tau_n)$ when $|x_n(\tau_n)| \le K$ and =0 when $|x_n(\tau_n)| > K$ so that $x_{n,K}(\tau_n)$ has $\phi_{n,K}$ as distribution function. On combining Theorems 5 and 32 we see that the convergence of the series $c(\phi_{1,K}) + c(\phi_{2,K}) + \cdots$ and $M_2(\tilde{\phi}_{1,K}) + M_2(\tilde{\phi}_{2,K}) + \cdots$ is necessary and sufficient for the convergence almost everywhere of $x_{1,K}(\tau_1) + x_{2,K}(\tau_2) + \cdots$. On the other hand, $x_1(\tau_1) + x_2(\tau_2) + \cdots$ converges almost everywhere if and only if $(1 - \phi_1(C_K)) + (1 - \phi_2(C_K)) + \cdots$ is convergent and $x_{1,K}(\tau_1) + x_{2,K}(\tau_2) + \cdots$ converges almost everywhere.

As an application of Theorem B we finally prove

THEOREM 35. If $\psi = \phi_1 * \phi_2 * \cdots$ is a convergent infinite convolution of distribution functions ϕ_n each of which is purely discontinuous, then ψ is either purely discontinuous or singular or absolutely continuous.

Using the notation of Theorem 32, we may suppose that each $x_n(\tau_n)$ takes on an at most enumerable set of values $x_{n,1}, x_{n,2}, \cdots$. Let M denote the smallest modul in R_x containing all points $x_{n,m}$ so that for an arbitrary set E in R_x the vectorial sum E+M is at most enumerable if E is at most enumerable and E+M is a null-set if E is a null-set. If E is a Borel set then the set E of those points E in E for which E for which E for which E for which set E for the set E for the set E for the set E for which set E for the set E for the set E for which set E for the set E for

Theorem 35 has been used already in §6. Further infinite convolutions of the type considered in Theorem 35 have recently been investigated by Schoenberg [47] in connection with distribution problems for arithmetical functions.

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