REMOVABLE SETS FOR POINTWISE SOLUTIONS OF ELLIPTIC PARTIAL DIFFERENTIAL EQUATIONS(1)

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Abstract. We prove that dense sets of zero newtonian capacity are removable for bounded generalized pointwise solutions of second order elliptic equations.

- 0. Introduction. A classical theorem for harmonic functions in K-space is that every closed set E of zero newtonian capacity is removable for the class of bounded harmonic functions. J. Serrin [14] has generalized this theorem to bounded solutions of linear second order elliptic partial differential equations. Our aim is to remove dense sets, i.e. F_{σ} sets, without requiring any information about the functions on the exceptional set. This necessitates introducing a notion of generalized pointwise solutions which leads to a regularity theorem (Theorem 1) for a class of elliptic equations for which the adjoint cannot necessarily be defined. This work is an extension of some of the concepts developed by V. L. Shapiro in [17]. Our theorems and more specific comments are to be found in the next section.
- 1. **Preliminaries.** We shall work in K-dimensional Euclidean space, E_K , $K \ge 3$, and shall use the following notation: $x = (x_1, \ldots, x_K)$ and B(x, r) = the open K-ball with center x and radius r. Ω will always denote an open, bounded set in E_K . |E| will denote the measure of E and Cap (E) the K-dimensional newtonian capacity, see [3, p. 16]. All functions shall have the extended reals for their range.

A function u defined on Ω is said to be in $t_{\alpha}(x_0)$, $\alpha \ge 0$, if u is in L_1 in a neighborhood of x_0 , and if there is a polynomial P(y) of degree $\le \alpha$ such that

(1)
$$|B(0,r)|^{-1} \int_{B(0,r)} |u(x_0+y)-P(y)| \ dy = o(r^{\alpha}) \quad \text{as } r \to 0.$$

For u in $t_2(x_0)$, we define the generalized partials $D_i u(x_0)$, $D_{ij} u(x_0)$ to be the coefficients of y_i , $y_i y_j/2!$ in P(y) respectively. (The class t_α was defined in [2] and since has appeared in a number of places in the literature, in particular in [17].)

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Throughout we shall consider linear second order elliptic partial differential equations of the form (the summation convention is adopted)

(2)
$$Lu = a_{ij}(x)u_{ij} + b_{ij}(x)u_{ij} + c(x)u = 0 (c(x) \le 0).$$

We also require that the coefficients of the operator L be α -Hölder continuous for some $0 < \alpha \le 1$, with Hölder constant K_1 . In addition L is uniformly elliptic, i.e. for any nonzero vector ξ and any x in Ω

(3)
$$K_2|\xi|^2 \le a_{ij}(x)\xi_i\xi_j \le K_2^{-1}|\xi|^2.$$

With such restrictions on L, the maximum principle and the solution of the Dirichlet problem hold. Furthermore we normalize the trace $\sum a_{ii}(x) = K$ for x in Ω ; since the trace is invariant under similarity transformation, the sum of the eigenvalues of the matrix $(a_{ij}(x))$ must be K. This is simply for convenience in establishing Lemma 5.

For u in $t_2(x_0)$, we say that u is a t_2 solution of (2) at x_0 if

(4)
$$a_{ij}(x_0)D_{ij}u(x_0) + b_i(x_0)D_iu(x_0) + c(x_0)u(x_0) = 0.$$

We are now ready to state two of our theorems. Theorem 1 is a regularity theorem for t_2 solutions of (2) and is used to establish Theorem 3 on removable F_{σ} sets for (2). Theorem 3 is a generalization of Serrin's Theorem 1 [14] for L_{∞} solutions and sets of capacity zero. The generalization of Carleson's Theorem 2 [3] for Lip α solutions of (2) is handled in a paper by Shapiro and Diederich in which additional restrictions are placed on the coefficients of L.

THEOREM 1. Let u be a t_2 solution of (2) at each point of Ω and let u be in L_{∞} . Then u is a classical solution of (2) in the sense that u is in $C^{2+\alpha}$ and Lu=0.

Theorem 3. Let u be a t_2 solution of (2) in $\Omega - E$, where E is an F_{σ} set, and let u be in L_{∞} . Then a necessary and sufficient condition that E be removable, i.e. that u is equal a.e. in Ω to a classical solution v of (2), is that Cap(E) = 0.

A few remarks on the above theorems are in order. First, the hypotheses do not require that the function be defined on the exceptional set E. Second, the exceptional set is allowed to be dense in Ω . (Neither the Looman-Menchoff Theorem [13, p. 199] nor Serrin's Theorem 1 [14, p. 68] satisfy both of these requirements.) Clearly, then, the classical notion of derivative cannot be employed and the global nature of weak (i.e. distribution) derivative disallows its use. Arsove, in [1, p. 98], allows the exceptional set to be dense and thereby uses the generalized Laplacian (see §2 for the definition) for his pointwise definition of operator. However, the hypothesis of continuity cannot be eliminated (see the discussion which occurs at the end of the Appendix) for this generalized operator. Hence we use the stronger notion of t_2 derivative. Also note that the notion of weak solution does not apply in general to our class of operators. Briefly, Theorem 2 is a generalization of Arsove's Theorem 6 [1, p. 98] on subharmonic functions, to functions which are subelliptic. This theorem is also used in establishing Theorem 3.

2. Generalized derivatives. Several important properties of differentiable functions carry over to functions in t_{α} . For f and g in $t_1(x_0)$, the following are easily verified: (a) f+g is in $t_1(x_0)$, (b) if g is in L_{∞} , then $f \cdot g$ is in $t_1(x_0)$, and (c) if T is a 1-1 linear transformation on E_K , then $f \cdot T$ is in $t_1(T^{-1}x_0)$ where the t_1 partials of f+g, $f \cdot g$, and $f \cdot T$ are given canonically in terms of the t_1 partials of f, g, and T. It is also clear that if f is in $t_1(x_0)$ and $f(x_0)$ is a local maximum, then $D_i f(x_0) = 0$, for $i=1,2,\ldots,K$. In E_1 , differentiability of f at x_0 ensures continuity of f at x_0 ; similarly, f in $t_1(x_0)$, even in E_K , ensures the mean continuity of f at x_0 as can be seen from (1).

Global behavior is quite different, even in E_1 . If f' and f'' exist in an interval I, then f and f' are continuous and bounded on compact subsets of I. But f in $t_2(x)$, for all x in I, does not guarantee that $D_1f(x)$ is even in L_1 on compact subsets of I. A simple example is $f(x)=x^3\sin x^{-3}$ on (-1,1), where $D_1f(0)=D_{11}f(0)=0$. Indeed, the t_α notion remains simply a pointwise generalization of differentiation. (Note that $(x-t)^3\sin (x-t)^{-3}$ is a continuous t_2 solution of the wave equation in the plane and is not a classical, i.e. C^2 , solution.)

We now consider pointwise generalizations of differentiation which are implied by the t_{α} notion. For f in $t_1(x_0)$ we observe from (1) that

$$(r^{2}|B(0,r)|)^{-1} \left| \int_{B(0,r)} f(x_{0}+y) y_{i} dy - (K+2)^{-1} r^{2} |B(0,r)| D_{i} f(x_{0}) \right|$$

$$\leq (r|B(0,r)|)^{-1} \int_{B(0,r)} |f(x_{0}+y) - P(y)| dy = o(1).$$

Hence

$$\lim_{r\to 0} d_i(r)f(x_0) = \lim_{r\to 0} (K+2)(r^2|B(0,r)|)^{-1} \int_{B(0,r)} f(x_0+y)y_i \, dy$$
$$= D_i f(x_0).$$

Likewise for f in $t_2(x_0)$ we see from (1) that

$$\lim_{r\to 0} 2(K+2)(r^2|B(0,r)|)^{-1} \int_{B(0,r)} f(x_0+y) - f(x_0) \, dy = \sum_{i} D_{ii} f(x_0),$$

which is the classical notion of generalized Laplacian.

We define the upper generalized elliptic operator L^* as follows: to each point x_0 in Ω associate the matrices $(a_{ij}(x_0))$ and $(\lambda_i(x_0))$, the latter being the matrix of eigenvalues of $(a_{ij}(x_0))$. Since the eigenvalues are positive, consider the ellipse centered at the origin with axes $\lambda_1^{1/2}(x_0), \ldots, \lambda_K^{1/2}(x_0)$. Denote the rotation of this ellipse by the transformation \mathscr{P} , where $\mathscr{P}^*(a_{ij}(x_0))\mathscr{P}=(\lambda_i(x_0))$, by El $(x_0:0,1)$. Denote the homothetic transformation r of El $(x_0:0,1)$ by El $(x_0:0,r)$.

Set for f in L_1 ,

$$L'(r)f(x_0) = 2(K+2)(r^2|\mathrm{El}(x_0;0,r)|)^{-1} \int_{\mathrm{El}(x_0;0,r)} f(x_0+y) - f(x_0) \, dy.$$

Then define $L^*f(x_0)$ to be

$$\lim \sup_{r \to 0} [L'(r)f(x_0) + \sum_{i} b_i(x_0) d_i(\delta r)f(x_0) + c(x_0)f(x_0)]$$

where δ allows $B(0, \delta r) \subseteq E(x_0; 0, r)$ for each x_0 . For $L_* f(x_0)$ we use the lim inf. Note for f in $t_2(x_0)$ that $L^* f(x_0) = L_* f(x_0) = \text{left}$ side of (4).

A function v is called subelliptic(3) in a region Ω in E_K if (1) v is upper semi-continuous and (2) for each subdomain G, if Lu=0 in G and $\limsup_{x\to y:x\in G} v(x) \le u(y)$, for every y in ∂G , then $v(x) \le u(x)$ in G.

THEOREM 2. Let u be a continuous real-valued function on Ω such that $L_*u(x) > -\infty$ holds except on an F_{σ} set E with Cap (E) = 0. Let $L_*u(x) \ge 0$ hold almost everywhere. Then u is subelliptic on Ω .

We should mention here that the notions of generalized derivatives and operators have been heavily exploited in the work of Verblunsky, Shapiro [15], [16], [17], Philipp [9], and others to establish uniqueness results in the theory of trigonometric series and partial differential equations.

3. Regularity of t_2 solutions. We shall need some definitions and lemmas in order to establish Theorem 1. $T_K = \{x : -\pi < x_j \le \pi, j = 1, ..., K\}$; m will denote an integral lattice point; for a function f in $L_1(T_K)$ we shall set

$$\hat{f}(m) = (2\pi)^{-K} \int_{T_K} f(x) e^{-i(m,x)} dx.$$

Given f in $L_1(T_K)$, we shall say that f is extended by periodicity to all of E_K if f is defined in all of E_K and is 2π -periodic in each variable. By $A_t(f, x)$ we denote the Abel sum of f, $\sum_m \hat{f}(m)e^{i(m,x)-|m|t}$, for x in E_K and t>0, which also has the integral representation

$$b_K t \int_{E_K} f(y) [t^2 + |x - y|^2]^{-(K+1)/2} dy$$

where b_K is a dimensional constant (see [15]).

LEMMA 1. Let f be in $L_1(T_K)$ and extended by periodicity to E_K . In addition, let f be in $t_2(x_0)$ with generalized partials $D_i f(x_0)$ and $D_{ij} f(x_0)$. Then

$$\lim_{t\to 0} (\partial/\partial x_i) A_t(f, x_0) = D_i f(x_0)$$

and

(5)
$$\lim_{t\to 0} (\partial^2/\partial x_i \,\partial x_j) A_t(f,x_0) = D_{ij} f(x_0).$$

⁽³⁾ The terminology "subsolution" or "subfunction" is standard. "Subelliptic" is used here in conjunction with the upper generalized elliptic operator.

Proof. We establish the lemma for (5) with $i \neq j$ and $x_0 = 0$ without loss. For t > 0, the second partial of $A_t(f, x)$ at 0 is

$$tb_K(K+1)(K+3)\int_{E_K} f(y)y_iy_j[t^2+|y|^2]^{-(K+5)/2} dy.$$

Let $P_1(x)$ be the t_2 total differential of f at 0, and let $\lambda(x)$ be a C^{∞} function which is identically 1 on B(0, 1), 0 on $B(0, \pi/2)^C$, and between 0 and 1 otherwise. Set $P(x) = P_1(x)\lambda(x)$, periodized to E_K . Then

$$(\partial^2/\partial x_i \partial x_i)A_t(f, x) = (\partial^2/\partial x_i \partial x_i)[A_t(f-P, x) + A_t(P, x)].$$

Clearly $\lim_{t\to 0} (\partial^2/\partial x_t \partial x_j) A_t(P, x)_{x=0} = D_{ij} f(0)$. We need only show that

$$\lim_{t\to 0}|I(t)|=0,$$

where $I(t) = (\partial^2/\partial x_t \partial x_j)A_t(f-P, x)_{x=0}$. Let $\varepsilon > 0$, and select r_0 such that for $r \le r_0$

$$F(r) = \int_{B(0,r)} |f(y) - P(y)| \, dy \le \varepsilon r^2 |B(0,r)|.$$

We now proceed as in [15, p. 57]:

$$|I(t)| \leq C(K)t \int_0^{r_0} r^2[t^2+r^2]^{-(K+5)/2} dF(r) + C(K)t \int_{r_0}^{\infty} r^2[t^2+r^2]^{-(K+5)/2} dF(r);$$

the second term is o(1). Integrating by parts we get

$$|I(t)| \le C(K)t \int_0^{\tau_0} rF(r)[t^2 + r^2]^{-(K+5)/2} dr + o(1)$$

$$\le \varepsilon \cdot C(K)t \int_0^{\tau_0} r^{K+1}[t^2 + r^2]^{-(K+3)/2} dr + o(1)$$

$$\le \varepsilon \cdot C(K) + o(1)$$

after using the transformations r = ts and $s = tan \theta$, completing the proof.

LEMMA 2. Let f be in $t_2(x)$ for all x in Ω . Then for each open ball $B \subseteq \Omega$, there is an open subball $B_1 \subseteq B$ in which f is continuous(4).

Proof. Without loss, $\Omega \subset T_K$ and $B \subset B(0, 1)$. Redefine f(x) to be $f(x)\lambda(x)$ where λ is the same as in Lemma 1. For t > 0, denote the Laplacian applied to $A_t(f, x)$ by $\Delta A_t(f, x)$. Then $\Delta A_t(f, x) = -\sum_{m \neq 0} |m|^2 \hat{f}(m) e^{i(m, x) - |m|t}$ converges to $\sum D_{ii} f(x)$ as $t \to 0$ by Lemma 1. Following [15, p. 67] we see that $-\sum_{m \neq 0} |m| \hat{f}(m) e^{i(m, x) - |m|t}$ and $-\sum_{m \neq 0} \hat{f}(m) e^{i(m, x) - |m|t}$ converge. By the continuity of $\Delta A_t(f, x)$ in x and t and the periodicity in x, there is a sequence $t_1 > t_2 > \cdots > t_i > \cdots$ such that $t_i \to 0$ and

(6)
$$\sup_{x \text{ in } E_K} \|\Delta A_t(f, x) - \Delta A_{t_i}(f, x)\| \leq 1 \quad \text{for } t_{i+1} \leq t \leq t_i.$$

⁽⁴⁾ B can also be a closed set; f will then be continuous in $B_1 \cap B$ in the relative topology.

The Baire category theorem yields a subball $B_1 \subset B$ on which $\Delta A_{t_i}(f, x)$ is uniformly bounded for $i = 1, 2, \ldots$ and thus by (6) for t > 0. Hence $A_t(f, x)$ converges uniformly in B_1 . Since f is mean continuous in Ω , by Theorem 2 [15, p. 55] $A_t(f, x)$ converges to f in B(0, 1). So f is continuous in B_1 completing the proof.

LEMMA 3. Let u be continuous in Ω and let $L^*u(x) \ge 0$ for x in Ω . Then u is subelliptic in Ω .

Proof. Let \overline{B} be a closed ball in Ω . Let v be the solution of (2) in B with boundary values u. Select h_n such that $Lh_n(x) \equiv 1/n$, for x in B, and $h_n \equiv 0$ on ∂B . We first show that $u_n(x) = u(x) + h_n(x) \le v(x)$ in \overline{B} . If v does not majorize u_n , then by the continuity of u there is a point x_0 in B at which $u_n - v$ takes its positive maximum.

If we show that

$$(7) 0 \geqq L^*(u_n - v)(x_0),$$

then, setting $u_n - v = U_n$,

$$0 \ge L^* U_n(x_0) = L^* u_n(x_0) = L^* u(x_0) + Lh_n(x_0) \ge 1/n;$$

thus $u_n \leq v$ in \overline{B} .

We assume that $b_i(x_0) \ge 0$ and prove (7). Since $U_n(x_0) > 0$ and $c(x_0) \le 0$, $c(x_0)U_n(x_0) \le 0$. Also

$$L'(r)U_{n}(x_{0}) + \sum b_{i}(x_{0}) d_{i}(\delta r)U_{n}(x_{0})$$

$$= 2(K+2)[r^{2}|E|(x_{0}:0,r)|]^{-1} \int_{E|(x_{0}:0,r)} U_{n}(x_{0}+y) - U_{n}(x_{0}) dy$$

$$+ \sum (K+2)[(\delta r)^{2}|B(0,\delta r)|]^{-1}b_{i}(x_{0})$$

$$\cdot \left\{ \int_{B(0,\delta r):y_{i} \geq 0} + \int_{B(0,\delta r):y_{i} \leq 0} [U_{n}(x_{0}+y) - U_{n}(x_{0})]y_{i} dy \right\}$$

which is nonpositive for r, hence $|y_i|$, satisfying

$$Kr\delta^{-(K+2)} \max_{i} \{b_{i}(x_{0})\} |B(0,r)|^{-1} \leq 2|\text{El }(x_{0};0,r)|^{-1}$$

and (7) holds.

Since $h_n \equiv 0$ on ∂B , the maximum principle gives $h_n < h_{n+1} < \cdots < 0$; also $h_n \to 0$ [7, p. 95], and therefore u_n converges monotonically up to u. Consequently $u(x) = \lim_{n \to \infty} u_n(x) \le v(x)$ in \overline{B} . Thus u is subelliptic and the proof is complete.

The following two theorems from the literature will be used in establishing the next lemma.

THEOREM a. For every K-ball $B(x_0, r)$ entirely in Ω , every C^2 solution of $\Delta u = -\omega_K f$ in $B(x_0, r)$ satisfies the relation

(8)
$$u(x_0) = |B(x_0, r)|^{-1} \int_{B(x_0, r)} u(x) dx - \int_{B(x_0, r)} \phi(r', r) f(x) dx$$

where f is continuous in $\bar{B}(x_0, r)$, ω_K is the area of $\partial B(0, 1)$, and

$$\phi(r',r) = (K-2)^{-1}(r^{2-K}-(r')^{2-K})+2^{-1}r^{2-K}(1-(r')^{2}r^{-2}),$$

$$r' = |x - x_0|$$
 (see [4, p. 277]).

THEOREM b (SCHAUDER ESTIMATES). For each C^2 solution u of (2) in B(0, 1), the following interior estimates on the first and second derivatives of u prevail in each subdomain G having positive distance d to $\partial B(0, 1)$:

(9)
$$\max_{i,j;x \text{ in } G} \left\{ d \left| (\partial/\partial x_i) u(x) \right|, \ d^2 \left| (\partial^2/\partial x_i \ \partial x_j) u(x) \right| \right\} \leq C_1 \|u\|_{\infty}$$

where C_1 depends only on K, K_1 , K_2 , and |B(0, 1)| (see [4, p. 335]).

LEMMA 4 (APPROXIMATE MEAN VALUE). Let u be a classical solution of (2) in a subregion of Ω which contains $\text{El }(x_0:x_0,r)=\{x:x=x_0+y,\ y \text{ in } \text{El }(x_0:0,r)\}$. Then the following holds:

(10)
$$\left| |\operatorname{El}(x_0; 0, r/2)|^{-1} \int_{\operatorname{El}(x_0; 0, r/2)} u(x_0 + y) \, dy - u(x_0) \right| \le C_2 ||u||_{\infty} r^{\alpha}$$

where C_2 depends on K, K_1 , K_2 , $||b_i||_{\infty}$, $||c||_{\infty}$ and $El(x_0:0,1)$.

Proof. Since L is elliptic we can assume that $a_{ij}(x_0) = \delta_{ij}$ and $x_0 = 0$, so El (0:0,r) = B(0,r). We define a new function \tilde{u} and a new operator \tilde{L} in B(0,1) as follows:

- (a) for y in B(0, 1), $\tilde{a}_{ij}(y)$, $\tilde{b}_{i}(y)$, and $\tilde{c}(y)$ equal $a_{ij}(x)$, $b_{i}(x)$, and c(x) respectively, where x = ry.
 - (b) $\tilde{L}g(y) = \tilde{a}_{ij}(y)g_{ij}(y) + r\tilde{b}_{i}(y)g_{i}(y) + r^{2}\tilde{c}(y)g(y)$.
 - (c) $\tilde{u}(y) = u(x)$, where x = ry.

The constants K_1 and K_2 may be employed for the Hölder constant and uniform ellipticity constant of \tilde{L} respectively;

$$|\tilde{a}_{ij}(y_1) - \tilde{a}_{ij}(y_2)| \leq K_1 r^{\alpha} |y_1 - y_2|^{\alpha} \leq K_1 |y_1 - y_2|^{\alpha};$$

$$K_2^{-1} |\xi|^2 \geq \tilde{a}_{ij}(y) \xi_i \xi_j = a_{ij}(x) \xi_i \xi_j \geq K_2 |\xi|^2.$$

Clearly $(\partial^2/\partial y_i \partial y_j)\tilde{u}(y) = (\partial^2/\partial x_i \partial x_j)u(x)r^2$ and $(\partial/\partial y_i)\tilde{u}(y) = (\partial/\partial x_i)u(x)r$ so that Lu = 0 gives $\tilde{L}\tilde{u} = 0$ in B(0, 1). From Theorem b, (9),

$$\max_{i,j:y \text{ in } B(0,1/2)} \left\{ \frac{1}{2} \left| (\partial/\partial y_i) \tilde{u}(y) \right|, \left(\frac{1}{2} \right)^2 \left| (\partial^2/\partial y_i \, \partial y_j) \tilde{u}(y) \right| \right\}$$

(11)
$$= \max_{i,j;x \text{ in } B(0,r/2)} \{ \frac{1}{2} | (\partial/\partial x_i) u(x) | r, (\frac{1}{2})^2 | (\partial^2/\partial x_i \partial x_j) u(x) | r^2 \}$$

$$\leq C_1 \| \tilde{u} \|_{\infty} = C_1 \| u \|_{\infty}.$$

In B(0, r) we write

$$Lu(x) = \Delta u(x) + (a_{ij}(x) - \delta_{ij})u_{ij}(x) + b_{ij}(x)u_{ij}(x) + c(x)u(x) = 0,$$

thus

$$\Delta u(x) = -(a_{ij}(x) - \delta_{ij})u_{ij}(x) - b_i(x)u_i(x) - c(x)u(x) \equiv f(x).$$

For x in B(0, r/2), from (11) and the Hölder condition

$$|f(x)| \leq [K^{2}4K_{1}C_{1}||u||_{\infty}r^{-2+\alpha} + 2K||b_{i}||_{\infty}C_{1}||u||_{\infty}r^{-1} + ||c||_{\infty}||u||_{\infty}]$$

$$\leq C'_{2}||u||_{\infty}r^{-2+\alpha}, \qquad r \leq 1.$$

Using this in Theorem a, (8),

$$\left| u(0) - |B(0, r/2)|^{-1} \int_{B(0, r/2)} u(x) \, dx \, \right| \leq C_2 \|u\|_{\infty} r^{-2 + \alpha} \int_{B(0, r/2)} |\phi(r', r)| \, dx$$

$$\leq C_2 \|u\|_{\infty} r^{-2 + \alpha} r^2 \leq C_2 \|u\|_{\infty} r^{\alpha},$$

and the lemma is established.

Proof of Theorem 1. We first prove that u is continuous. (This is accomplished by using Lemmas 1-4 in a fashion suggested by the methods in [15, pp. 65-78], which have been advanced in [17].) Assume, therefore, that the set of discontinuities Z is not empty. Let \overline{Z} be its closure in Ω . By Lemma 2 we can find an open ball B_1 such that $B_1 \cap Z \neq \emptyset$ and such that u is continuous in $\overline{B}_1 \cap \overline{Z}$ in the topology of $\overline{B}_1 \cap \overline{Z}$.

For x in $\bar{B}_1 \cap \bar{Z}$ set

$$U(x,r) = [r|E|(x;0,r)|]^{-1} \int_{E|(x;0,r)} |u(x+y) - u(x)| dy.$$

Clearly U(x, r) is continuous in $(\overline{B}_1 \cap \overline{Z}) \times (0, 1]$. Also $U(x, r) \leq M(x)$, a finite constant depending on x, since u is in $t_1(x)$ for all x. Again, as in Lemma 2, we can find $r_n > r_{n+1}$, $r_n \to 0$, such that

$$\sup_{x \text{ in } B_1 \cap Z} \sup_{r_{n+1} \le r \le r_n} |U(x, r) - U(x, r_n)| \le 1.$$

Thus by the Baire category theorem, there is a constant M and an open ball $B_2 \subset B_1$ such that $B_2 \cap Z \neq \emptyset$ and

$$(12) U(x,r) \le M+1$$

for x in $\overline{B}_2 \cap \overline{Z}$ and $0 < r \le 1$.

We select z_0 in $B_2 \cap Z$ and show that u is indeed continuous at z_0 , thus contradicting the assumption that $Z \neq \emptyset$. For $\varepsilon > 0$, there is a $\delta < \varepsilon$ such that

- (i) $B(z_0, \delta) \subseteq B_2$.
- (ii) $3|u(z_0)-u(z)| < \varepsilon$ for $|z_0-z| \le \delta$, z in $\overline{B}_2 \cap \overline{Z}$, since u is continuous in $\overline{B}_1 \cap \overline{Z}$.
- (iii) $3rU(z,r) < \varepsilon(2/K_2)^{-4K}$ for $r \le \delta$, z in $\overline{B}_2 \cap \overline{Z}$, by (12) and the definition of U(z,r).
 - (iv) $3C_2||u||_{\infty}r^{\alpha} < \varepsilon$ for $r \le \delta$ for C_2 in Lemma 4.

We need only show that for x in $B(z_0, K_2^3\delta/2)$, $|u(z_0) - u(x)| < \varepsilon$. If x is in $\overline{B}_2 \cap \overline{Z}$ it follows from (ii). If x is not in \overline{Z} , let $\text{El }(x:x,\rho)$ be the largest ellipse about x containing no points of \overline{Z} in its interior(5). Clearly, by (3), $\rho \le K_2^2\delta/2$ and

⁽⁵⁾ u is a classical solution in El $(x:x, \rho)$; see the last paragraph of the proof for details.

El $(x:x, \rho) \subset B(z_0, \delta)$. Let z^* be a point of \overline{Z} and the boundary of El $(x:x, \rho)$; z^* is in $\overline{B}(z_0, \delta) \subset \overline{B}_2$.

Thus

$$|u(z_{0}) - u(x)| \leq |u(z_{0}) - u(z^{*})| + |u(z^{*}) - u(x)| \leq \varepsilon/3 + |u(z^{*}) - u(x)| \quad \text{by (ii),}$$

$$\leq \varepsilon/3 + \left| u(x) - |\text{El }(x:0, \rho/2)|^{-1} \int_{\text{El }(x:0, \rho/2)} u(x+y) \, dy \right|$$

$$+ \left| u(z^{*}) - |\text{El }(x:0, \rho/2)|^{-1} \int_{\text{El }(x:0, \rho/2)} u(x+y) \, dy \right|$$

$$\leq 2\varepsilon/3 + \left| u(z^{*}) - |\text{El }(x:0, \rho/2)|^{-1} \int_{\text{El }(x:0, \rho/2)} u(x+y) \, dy \right|$$

$$\text{by Lemma 4 and (iv),}$$

$$\leq 2\varepsilon/3 + |\text{El }(x:0, \rho/2)|^{-1} \int_{\text{El }(z^{*}:0, \rho')} |u(z^{*}+y) - u(z^{*})| \, dy$$

where $\rho' = 2\rho K_2^{-2}$ and, by (3), El $(x: 0, \rho/2) \subseteq \text{El } (z^*: 0, \rho')$. Thus, since $\rho' \le \delta$, by (3) and (iii),

$$\leq 2\varepsilon/3 + \varepsilon/3$$
.

Thus Z is empty.

Since u is a t_2 solution of (2) we have $L^*u \equiv L_*u \equiv 0$. Since u is also continuous, by Lemma 3 u is subelliptic in Ω . -u can also be seen to be subelliptic and thus u is a classical solution of (2); the proof is complete.

4. Subelliptic functions and exceptional sets. We shall need a few lemmas in order to prove Theorem 2. For fixed y in Ω denote by L'_y the elliptic operator in Ω with constant coefficients $(a_{ij}(y))$. Denote by E(x, y) the singular solution of $L'_y u(x) = 0$ for x in $\Omega - \{y\}$ of order r^{2-K} at y, i.e. if $\mathscr{P}^*(a_{ij}(y))\mathscr{P} = \mathscr{D} = (\lambda_i(y))$, then

$$E(x, y) = |\mathscr{D}^{-1/2}\mathscr{P}^*(x-y)|^{2-K}.$$

Likewise we define $S(x, y) = |\mathcal{D}^{-1/2}\mathcal{D}^*(x-y)|^{2+\alpha-K}$. Thus if $a_{ij}(y) = \delta_{ij}$, then $E(x, y) = |x-y|^{2-K}$ and $S(x, y) = |x-y|^{2+\alpha-K}$. If we write

$$L'E(x, y) = L'_{y}E(x, y) + [L'_{y} - L']E(x, y)$$

where L' is the principal part of L and the partials are taken with respect to the first variable, a simple calculation yields, for $x \neq y$, $|LE(x, y)| \leq C_3 |x-y|^{\alpha-K}$ where C_3 is independent of x and y. Likewise

$$LS(x, y) = -C_4(x, y)|x-y|^{\alpha-K} + O(|x-y|^{2\alpha-K})$$

where $C_4(x, y)$ is positive and bounded away from 0 and ∞ . Let $C_4 = \inf C_4(x, y)$, then for some η , if $|x-y| < \eta$

$$LS(x, y) \leq -(C_4/2)|x-y|^{\alpha-K}$$
.

Whence for any $C_5 \ge 2C_3C_4^{-1}$ and setting $G_1(x, y) = E(x, y) + C_5S(x, y)$, $LG_1(x, y) \le 0$ for $0 < |x-y| < \eta$. For $|x-y| > \eta$, |LE(x, y)| and |LS(x, y)| are bounded. We can therefore find H(x) so that

- (1) $H(x) \ge 0$ and
- (2) $LH(x) \le -2 \max_{y \text{ in } \Omega} \{|LE(x, y)|, |LS(x, y)|\},$ and thus for $G(x, y) = E(x, y) + C_5S(x, y) + C_5H(x),$

(14)
$$LG(x, y) \le 0 \quad \text{for } x \ne y.$$

From (3) we see that

(15)
$$G(x, y) = O(|x-y|^{2-K})$$

independent of x and y. (G(x, y)) has previously appeared in [6, p. 317].) By (15), for f in $L_1(\Omega)$,

(16)
$$F(x) = -\omega_K^{-1} \int_{\Omega} f(y) G(x, y) \, dy$$

exists a.e. in Ω .

LEMMA 5. Let f be a nonpositive function which is bounded from below and is upper semicontinuous on Ω . Form F(x) as in (16). Then F(x) is in $C^1(\Omega)$ and

$$(17) L^*F(x) \le f(x).$$

(In the proof C_5 is taken a bit larger than $2C_3C_4^{-1}$.)

Proof. This lemma is motivated by (3.7) of [11, p. 282]. The boundedness of f ensures the continuity of F(x). By a routine modification of the proof in [7, p. 175] that the potential due to a bounded density is in class C^1 , where the partials are taken under the integral sign, we can establish the same for F(x) (this is not needed if L has no first order terms).

We first focus on the principal part L' of L and assume that x is the origin and El (0:0, r) = B(0, r). By Fubini's theorem we write

 $\omega_{\kappa}L'(r)F(0)$

$$= -2(K+2)[r^{2}|B(0,r)|]^{-1} \int_{B(0,r)} \int_{\Omega} f(Q) \{G(M,Q) - G(0,Q)\} dQ dM$$

$$= 2(K+2)r^{-2} \int_{B(0,r)} f(Q) \Big\{ G(0,Q) - |B(0,r)|^{-1} \int_{B(0,r)} G(M,Q) dM \Big\} dQ$$

$$+ 2(K+2)r^{-2} \int_{\Omega - B(0,r)} f(Q) \Big\{ G(0,Q) - |B(0,r)|^{-1} \int_{B(0,r)} G(M,Q) dM \Big\} dQ$$

$$= 2(K+2)r^{-2} [I_{1}(r) + I_{2}(r)],$$

where r is sufficiently small to allow $B(0, r) \subseteq \Omega$.

We show first that for some r_0 , if $r \le r_0$,

(18)
$$0 \le G_1(0, Q) - |B(0, r)|^{-1} \int_{B(0, r)} G_1(M, Q) dM$$

in $I_1(r)$, i.e., for Q in B(0, r), where $G_1(M, Q) = E(M, Q) + C_5S(M, Q)$. We fix Q and estimate E(M, Q). The estimate for S(M, Q) follows in the same way.

$$E(0, Q) - |B(0, r)|^{-1} \int_{B(0, r)} E(M, Q) dM$$

$$= \left\{ E(0, Q) - |\text{El}(Q:0, r')|^{-1} \int_{\text{El}(Q:0, r')} E(M, Q) dM \right\}$$

$$+ \left\{ |\text{El}(Q:0, r')|^{-1} \int_{\text{El}(Q:0, r')} E(M, Q) dM - |B(0, r)|^{-1} \int_{B(0, r)} E(M, Q) dM \right\}$$

$$= E_1(r) + E_2(r),$$

where r' is the smallest positive real number which allows $B(0, r) \subset E(Q:0, r')$. $E_1(r) \ge 0$ as can be seen by a change of variables and by the superharmonicity of the singular solution of Laplace's equation. We express

$$\begin{split} E_2(r) &= E_{21}(r) + E_{22}(r) \\ &= |B(0,r)|^{-1} \int_{\text{El}(Q:0,r') - B(0,r)} E(M,Q) \, dM + \{|B(0,r)| - |\text{El}(Q:0,r')|\} \\ &\cdot |B(0,r)|^{-1} |\text{El}(Q:0,r')|^{-1} \int_{\text{El}(Q:0,r')} E(M,Q) \, dM. \end{split}$$

 $E_{21}(r) \ge 0$ since E(M, Q) is positive.

We estimate $E_{22}(r)$, which is negative. It is easy to see using Geršgorin's disks [8, p. 197] and the Hölder continuity of the a_{ij} 's that

$$(20) |1 - \lambda_i^{1/2}(Q)| \le |1 - \lambda_i(Q)| \le C_6 |Q|^{\alpha}$$

where C_6 depends only on K, K_1 , and K_2 . If $\lambda_1(Q)$ is the smallest eigenvalue, then from normalizing the trace we have $r \le r' = r\lambda_1^{-1/2}(Q)$; let $\lambda_K(Q)$ be the largest. Hence

$$0 \ge |B(0,r)| - |\operatorname{El}(Q:0,r')| \ge |B(0,r)| - |B(0,r'\lambda_K^{1/2}(Q))|$$

= $|B(0,r)| - |B(0,r\lambda_K^{-1/2}(Q)\lambda_K^{1/2}(Q))| = |B(0,r)|(1-\lambda_1^{-K/2}(Q)\lambda_K^{K/2}(Q))$

and by (20) and the above

$$||B(0,r)| - |\text{El}(Q:0,r')|| \le C_7 |B(0,r)| |Q|^{\alpha} \le C_7 |B(0,r)| r^{\alpha}$$

where C_7 depends only on K, K_1 , and K_2 . Making the appropriate replacement of the above in $E_{22}(r)$ it follows easily that

$$|E_{22}(r)| \leq C_9 r^{2+\alpha-K},$$

 C_9 having the same dependence as C_7 .

Treating S(M, Q) in the same fashion we get

(22)
$$0 \le S_1(r), \quad 0 \le S_{21}(r), \quad \text{and} \quad |S_{22}(r)| \le C_{10}r^{2+2\alpha-K}.$$

The claim (18) follows once we show that

(23)
$$C_{11}r^{2+\alpha-K} \le S_1(r)$$

where $0 < C_{11}$ and depends only on α , K, K_1 , and K_2 . For then

(24)
$$G_{1}(0, Q) - |B(0, r)|^{-1} \int_{B(0, r)} G_{1}(M, Q) dM$$

$$= E_{1}(r) + E_{2}(r) + C_{5}S_{1}(r) + C_{5}S_{2}(r) \ge E_{22}(r) + C_{5}S_{1}(r) + C_{5}S_{22}(r)$$

$$\ge \{ -C_{9} + C_{5}[C_{11} - C_{10}r^{\alpha}] \} r^{2+\alpha-K}$$

using the estimates in (21), (22), and (23). Thus there is an r_0 such that, for $r \le r_0$, $C_{11} - C_{10}r^{\alpha} \ge 2^{-1}C_{11} > 0$. Since C_5 is independent of C_9 , C_{10} , and C_{11} , for $r \le r_0$ and $C_5 \ge \max\{2C_3C_4^{-1}, 2C_9C_{11}^{-1}\}$ we have that (24), therefore (18), is nonnegative.

But (23) follows quite nicely by a change of variables, treating α as a complex variable, and using the maximum modulus principle (see the Appendix).

Since f is upper semicontinuous, for $\varepsilon > 0$ and $|Q| \le \delta(\varepsilon) \le r_0$, $f(Q) \le f(0) + \varepsilon$. So from (18) with $r \le \delta(\varepsilon)$

$$I_1(r) \leq \{f(0) + \varepsilon\} \int_{B(0,r)} G_1(0, Q) - |B(0,r)|^{-1} \int_{B(0,r)} G_1(M, Q) dM dQ$$
$$+ \int_{B(0,r)} f(Q) \left\{ H(0) - |B(0,r)|^{-1} \int_{B(0,r)} H(M) dM \right\} dQ.$$

Since H(x) is in C^2 , the product of r^{-2} and the integrand in the second term is bounded in r and thus the second term vanishes as r tends to 0. An easy estimate shows that

$$\lim_{r\to 0} 2(K+2)r^{-2} \int_{B(0,r)} S(0,Q) - |B(0,r)|^{-1} \int_{B(0,r)} S(M,Q) \, dM \, dQ = 0$$

and that

$$\lim_{r\to 0} 2(K+2r)^{-2} \int_{B(0,r)} E(0,Q) - |B(0,r)|^{-1} \int_{B(0,r)} E(M,Q) \, dM \, dQ = \omega_K$$

using the fact that

$$2(K+2)r^{-2}\int_{B(0,r)}|Q|^{2-K}-|B(0,r)|^{-1}\int_{B(0,r)}|Q-M|^{2-K}dM\,dQ=\omega_{K}.$$

Thus

(25)
$$\limsup \omega_K^{-1} 2(K+2) r^{-2} I_1(r) \leq f(0).$$

This is almost the desired conclusion; we now consider $I_2(r)$, which can be expressed as

$$\int_{\Omega} f(Q)\chi_r(Q) \Big\{ G(0, Q) - |B(0, r)|^{-1} \int_{B(0, r)} G(M, Q) dM \Big\} dQ$$

where $\chi_r(Q)$ is the characteristic function of the set $B(0, r)^c$. If we formally pass to the limit under the integral sign we get

(26)
$$\lim_{r \to 0} 2(K+2)r^{-2}I_2(r) = -\int_{\Omega} f(Q)\Delta G(0, Q) dQ$$

where $\Delta G(0, Q)$ is the Laplacian of G with respect to the first variable evaluated at 0. For the moment we assume (26) since

$$\Delta G(0, Q) = L_{Q}'G(0, Q) + (\Delta - L_{Q}')G(0, Q) = (\Delta - L_{Q}')G(0, Q) = O(|Q|^{\alpha - K})$$

and the boundedness of f insures the existence of the integral. Consequently from (25) and (26)

$$\lim_{r \to 0} \sup L(r)F(0)$$

$$\leq f(0) - \omega_{K}^{-1} \int_{Q} f(Q) \left[\Delta G(0, Q) + \sum_{i} b_{i}(0) D_{i}G(0, Q) + c(0)G(0, Q) \right] dQ.$$

By the hypothesis the integrand is nonnegative and thus $L^*F(0) \le f(0)$. We now justify (26) and complete the lemma. We need only show that

$$\Delta(r)E(0, Q) = 2(K+2)|B(0, r)|^{-1}r^{-2}\int_{B(0, r)} E(M, Q) - E(0, Q) dQ$$

is $O(|Q|^{\alpha-K})$ in order to apply the dominated convergence theorem in (26). By a change of variables and (3)

$$\Delta(r)E(0, Q) = (K+2)|E|(Q':0, r)|^{-1}r^{-2}\int_{E|(Q':0, r)} |M'-Q'|^{2-K} + |M'+Q'|^{2-K} - 2|Q'|^{2-K} dM'$$

where $K_2|Q| \le |Q'| \le K_2^{-1}|Q|$, $r \le |Q|$, and El(Q':0, r) is the inverse ellipse of El(Q:0, r) with axes $\lambda_i^{-1/2}(Q)$. By the mean value theorem

(27)
$$\Delta(r)E(0, Q) = (K+2)|E|(Q':0, r)|^{-1}r^{-2}\int_{E|(Q':0, r) - B(0, r')} |M' - Q'|^{2-K} + |M' + Q'|^{2-K} - 2|Q'|^{2-K} dM'$$

where B(0, r') is the largest ball in El (Q':0, r); thus $r' = r\lambda_K^{-1/2}(Q)$, $\lambda_K(Q)$ being again the largest eigenvalue. It can be seen by expanding the integrand in (27), K=4 is quite easy, that

$$|\Delta(r)E(0,Q)| \leq C_{12}|Q'|^{-2}|\mathrm{El}(Q';0,r)|^{-1}\int_{\mathrm{El}(Q';0,r)-B(0,r')}|M'-Q'|^{2-K}\,dM'$$

where C_{12} depends only on K, K_1 , and K_2 , and by changing variables and (15)

$$\leq C_{13}|Q|^{-2}|B(0,r)|^{-1}\int_{B(0,r)-\mathrm{El}(Q;0,r')}|M-Q|^{2-K}dM$$

$$\leq C_{13}|Q|^{-2}|B(0,r)|^{-1}\int_{B(0,r)-B(0,r'')}|M-Q|^{2-K}dM$$

where $r'' = r' \lambda_1^{1/2}(Q) = r \lambda_1^{1/2}(Q) \lambda_K^{-1/2}(Q)$. Since $r \le |Q|$, using the mean value theorem

$$= C_{13}|Q|^{-K}\{1-|B(0,\lambda_1^{1/2}(Q)\lambda_K^{-1/2}(Q))||B(0,1)|^{-1}\} \le C_{14}|Q|^{-K+\alpha}$$

by (20); C_{14} depends only on K, K_1 , and K_2 . Thus

$$|\Delta(r)E(0, Q)| = O(|Q|^{-K+\alpha})$$

and the proof of the lemma is complete.

LEMMA 6. Let u be continuous in Ω and subelliptic on $\Omega - E$, E relatively closed and Cap (E) = 0. Then u is subelliptic on Ω .

Proof. This lemma follows easily using the technique in [14, p. 70] (see the Appendix).

LEMMA 7. Let u be continuous in Ω and subelliptic on $\Omega - E$, where E is relatively closed. Let $L^*u(x) \ge 0$ everywhere on E. Then u is subelliptic on Ω .

Proof. The lemma is easily proved along the lines of Lemma 3.

Proof of Theorem 2. $E = \bigcup E_n$ with E_n closed and $\operatorname{Cap}(E_n) = 0$. Let A be the set of all points x in Ω such that u is not subelliptic on any neighborhood of x. Clearly A is closed. If we show that A is empty we are finished.

For positive integral n, let H_n be the set of all points x in Ω such that

$$L(r)u(x) \ge -n$$
 for $0 < r < 1/n$.

Since L(r)u(x) is continuous in x for fixed r, H_n is relatively closed. By hypothesis $\Omega - E \subset \bigcup_n H_n$. Hence A is covered by $\bigcup_n H_n \cup \bigcup_n E_n$. Assuming A is not empty, we can find, by the Baire category theorem, an open ball such that $A \cap B$ is not empty and $A \cap B$ is contained in one of the covering sets.

If $A \cap B \subseteq E_{n_0}$, for some n_0 , then, by Lemma 6, u is subelliptic in B and thus $A \cap B$ is empty. Thus $A \cap B \subseteq H_{n_0}$ for some n_0 .

Define $f(x) = \min \{L_*u(x), 0\}$ for x in $A \cap B \cap H_{n_0}$ and 0 otherwise; hence, $0 \ge f(x) \ge -n_0$ for all x in B and by hypothesis f(x) = 0 a.e. in B. By the Vitali-Carathéodory theorem there are f_i with

- (i) $-n_0 \leq f_1(x) \leq f_2(x) \leq \cdots \leq f_i(x) \leq \cdots \leq f(x)$,
- (ii) f_i is upper semicontinuous,
- (iii) $f_i(x) \rightarrow f(x)$ a.e. in B.

Form $F_i(x)$ as in Lemma 5, and by Lemma 5, $L^*F_i(x) \le f_i(x)$, thus $L_*(-F_i(x)) \ge -f_i(x) \ge 0$. Clearly $u(x) - F_i(x)$ is subelliptic in B - A; for x in A

$$L^*(u(x) - F_i(x)) \ge L_*(u(x) - F_i(x)) \ge L_*u(x) + L_*(-F_i(x)) \ge f(x) - f_i(x) \ge 0.$$

By Lemma 7, $u-F_i$ is subelliptic on B. Since $u-F_i$ converge monotonically to u, which is continuous, it is easily seen that u is subelliptic on B and hence $A \cap B = \emptyset$, a contradiction. The proof is complete.

5. t_2 solutions and exceptional sets. Theorem 3 follows from Theorems 1 and 2 and the following lemma which is motivated by Lemma 6.16 [18, p. 349]. Such methods of removing dense sets have been previously employed by V. L. Shapiro in several settings as [15], [16], and [17].

LEMMA 8. Let u be a t_2 solution of (2) in $\Omega - E$, E an F_σ set and Cap (E) = 0. Let u be in L_∞ . In addition we assume that $|\Delta A_t(u, x)| \le M(x)$ for all x in Ω and $0 < t \le 1$, where M(x) is a finite constant depending on x. Then u is equal to a classical solution a.e. in Ω .

Proof. Since $\Delta A_t(u, x)$ is bounded at every point of Ω , we can argue as in Lemma 2 and show that $\lim_{t\to 0} A_t(u, x) = u_1(x)$ exists everywhere in Ω and converges on $\Omega - E$ to u. We extend $u \equiv u_1$ on E. As in Lemma 2 for each ball B, there is a subball B_1 on which u is continuous. Let Z be the nowhere dense set of discontinuities of u; let \overline{Z} denote its closure in Ω . If \overline{Z} is empty, then u is continuous and by hypothesis u is a t_2 solution of (2) on $\Omega - E$ and therefore $L_*u = L^*u = 0$ on $\Omega - E$. By Theorem 2, u is subelliptic in Ω . Since $L^*u = 0$ on $\Omega - E$, $L_*(-u) = 0$ and -u is subelliptic in Ω and consequently u must be a classical solution of (2).

Assume $\overline{Z} \neq \emptyset$; then there is a ball B_1 such that $B_1 \cap Z \neq \emptyset$ and u is continuous on $\overline{B}_1 \cap \overline{Z}$ in the topology of $\overline{B}_1 \cap \overline{Z}$. Define

$$H_n = \{z : z \in \overline{B}_1 \cap \overline{Z} \text{ and } U(z, r) \leq n, 0 < r \leq 1\}$$

with U defined as in the proof of Theorem 1.

Since u is continuous on $\overline{B}_1 \cap \overline{Z}$, H_n is relatively closed. The union $\bigcup_n H_n$ covers $\Omega - E$ since u is in t_2 , therefore t_1 , off E. So $\bigcup_n H_n$ together with $\bigcup_n E_n$ cover $\overline{B}_1 \cap \overline{Z}$. By the Baire category theorem there is a ball $B_2 \subset B_1$ such that $B_2 \cap Z \neq \emptyset$ and for some n_0 either $\overline{B}_2 \cap \overline{Z} \subset H_{n_0}$ or $\overline{B}_2 \cap \overline{Z} \subset E_{n_0}$. The latter is not possible since u would be a classical solution on $B_2 - E_{n_0}$ by Theorem 2, using the same argument as above when $\overline{Z} = \emptyset$, and therefore by Serrin's Theorem 1 [14, p. 68] for L_∞ solutions of (2), u would extend to be a classical solution v in \overline{B}_2 . Clearly $v \equiv u_1$ on $E_{n_0} \cap \overline{B}_2$ and thus $B_2 \cap Z = \emptyset$.

If $\overline{B}_2 \cap \overline{Z} \subset H_{n_0}$, then $U(z, r) \leq n_0$ for z in $\overline{B}_2 \cap \overline{Z}$, $0 < r \leq 1$, which is (12) in Theorem 1. The proof is now completed simply by following the proof of Theorem 1 from this point.

Proof of Theorem 3 (sufficiency). Define

$$J_n = \{x : |\Delta A_t(u, x)| \le n, 0 < t \le 1\}.$$

 J_n is relatively closed and $\bigcup J_n$ is an F_σ set; $G = \bigcap J_n^c$ is a G_σ set and is precisely the set of points at which $\Delta A_t(u, x)$ is unbounded for 0 < t < 1. If we show that G is empty, then the theorem will follow from Lemma 8.

By 6.17 of [18, p. 349], G is not a sum of nondense sets; by Lemma 1, since u is in t_2 on $\Omega - E$, G must be contained in E. So $G = G \cap E = \bigcup_i (E_i \cap G)$. So for some i_0 and some open ball B_1 , $B_1 \cap E_{i_0} \cap G \neq \emptyset$ and is dense in $B_1 \cap G$. Since E_{i_0} is

closed, $B_1 \cap G = B_1 \cap E_{i_0} \cap G$. Again by Lemma 8, u is a classical solution of (2) on $B_1 - E_{i_0}$, thus on B_1 . So $B_1 \cap G = \emptyset$, which is impossible. The proof of the sufficiency is complete.

Proof of Theorem 3 (necessity). We shall assume that Ω is a Dirichlet domain or more simply that $\Omega = B(0, 1)$. The following remarks are used to establish the necessity:

REMARK 1. If $Lu_n=0$ and u_n converge uniformly to u in Ω , then Lu=0.

Proof. Let B be an open ball with $\overline{B} \subseteq \Omega$. Since u is continuous on \overline{B} , let v be the solution of Lv = 0, $v \equiv u$ on ∂B . Then for n sufficiently large

$$-\varepsilon \le v - u_n \le \varepsilon$$
 on ∂B

and therefore in B by the maximum principle. So $v \equiv u$ in B.

REMARK 2. If $Lu_n=0$ and $u_n \le u_{n+1}$, then, for $u=\lim_{n\to\infty} u_n$, Lu=0 provided that $||u_n||_{\infty}$ are uniformly bounded by $M<\infty$.

Proof. If u is continuous, then the u_n converge uniformly to u by Dini's theorem and, by Remark 1, Lu=0. Fix x_0 in Ω and let $\varepsilon>0$ so that $B(x_0, 4\varepsilon K_2^{-1}) \subset \Omega$. Denote by u(x) the average of u over the ellipse E(x; x, r). We can choose δ so that $\delta \leq \varepsilon$ and

$$|\varepsilon u(x) - \varepsilon u(x_0)| < \varepsilon \quad \text{for } |x - x_0| < \delta.$$

For $|x-x_0| < \delta$,

$$|u(x)-u(x_0)| \leq |u(x)-\varepsilon u(x)|+|u(x_0)-\varepsilon u(x_0)|+|\varepsilon u(x)-\varepsilon u(x_0)|$$

$$\leq \lim_{n\to\infty} |u_n(x)-\varepsilon u_n(x)|+\lim_{n\to\infty} |u_n(x_0)-\varepsilon u_n(x_0)|+\varepsilon$$

by (28) and the dominated convergence theorem. Since $El(x_0; x_0, 2\varepsilon)$ and $El(x; x, 2\varepsilon)$ are contained in Ω , by Lemma 4 the above is $\leq 2C_2M\varepsilon^{\alpha} + \varepsilon$. Hence u is continuous in Ω and the proof is complete. Let G(x, y) be defined as in Lemma 5 and define $J(x, y) = E(x, y) - C_5(S(x, y) + H(x))$.

REMARK 3. $LG(x, y) \le 0$ and $LJ(x, y) \ge 0$ for x in $\Omega - \{y\}$ and each y in Ω .

Proof. $LG(x, y) \le 0$ has been established. Using the estimates leading to (14) for $|x-y| < \eta$,

$$LE(x, y) - C_5 LS(x, y) - C_5 LH(x) \ge LE(x, y) - C_5 LS(x, y)$$

$$\ge -C_3 + (C_5 C_4/2)|x - y|^{\alpha - K} \ge 0.$$

For $|x-y| \ge \eta$ it is also obvious.

REMARK 4. $J(x, y) \le -1$ for y in $B(0, \frac{1}{2})$ and x in $B(0, \frac{3}{4})^c$.

Proof. Both S(x, y) and H(x) are positive and we can choose C_5 as large as we wish.

REMARK 5. 0 < J(x, y) for $|x-y| < \gamma$ where γ depends on α , K_2 , and C_5 .

Proof. E(x, y) is positive and dominates S(x, y) and H(x) when |x-y| is small.

Assume that E is closed, Cap (E) > 0, and $E \subset B(0, \frac{1}{2})$; in addition we can assume without loss of generality that the diameter of E is less than $\gamma/2$. Let λ be the equilibrium distribution of E and form

$$u_{\lambda}(x) = \int_{E} J(x, y) d\lambda(y), \qquad v_{\lambda}(x) = \int_{E} G(x, y) d\lambda(y).$$

Since $\int_E |x-y|^{2-K} d\lambda(y)$ is bounded in $\Omega - E$, by (15) and the definition of J(x, y), u_{λ} and v_{λ} are bounded. By Remark 3 and Lemma 3, u_{λ} is subelliptic and v_{λ} is superelliptic in $\Omega - E$, and $u_{\lambda} < v_{\lambda}$ since J(x, y) < G(x, y).

We define

$$\mathcal{M} = \{ v : v \in C(\Omega - E), v \equiv u_{\lambda} \text{ on } \partial\Omega,$$

$$v \leq v_{\lambda} \text{ in } \Omega - E, v \text{ is subelliptic in } \Omega - E \};$$

 $\mathcal{M} \neq \emptyset$ since $u_{\lambda} \in \mathcal{M}$. Furthermore it is easy to see that

- (i) if $v_1, v_2 \in \mathcal{M}$, then sup $(v_1, v_2) \in \mathcal{M}$;
- (ii) if \overline{B} is any closed ball in ΩE and $v \in \mathcal{M}$, then the continuous function V = v off B and, satisfying LV = 0 in B, is in M.

That v_{λ} is superelliptic is needed to establish (ii). Our desired function is $u(x) = \sup_{v \in \mathcal{M}} v(x)$. Clearly $u_{\lambda}(x) \leq u(x) \leq v_{\lambda}(x)$. By a slight modification of the standard argument in the Perron method it is easy to show, using Remark 2 together with (i) and (ii), that Lu(x) = 0 in $\Omega - E$; such a modification is not needed if $c(x) \equiv 0$. Thus u is bounded and Lu = 0. We need only prove that u does not extend to be a solution of (2) on E.

By Remark 5, u_{λ} is positive if the distance from x to E is less than $\gamma/2$; so u must be positive for dist $(x, E) < \gamma/2$. If u is nonpositive near $\partial B(0, 1)$, then u cannot possibly be a solution in B(0, 1) by the maximum principle. Without loss of generality we can assume that $G_1(x, 0) = |x|^{2-K} + C_5|x|^{2+\alpha-K}$. Since B(0, 1) is a Dirichlet domain we can also assume that H(x) vanishes on $\partial B(0, 1)$; set $g(x) \equiv G_1(x, 0)$ on $\partial B(0, 1)$ with Lg(x) = 0. Since g(x) takes its maximum on the boundary, $g(x) < G_1(x, 0)$ for |x| < 1, and $g(x) < G_1(x, 0) + C_5H(x)$, for H(x) is nonnegative. So G(x, 0) - g(x) vanishes on $\partial B(0, 1)$, is strictly positive in the interior, and is superelliptic. For a suitably large constant C_{15} and for x on $\partial B(0, \frac{1}{2})$

$$u(x) \le C_{15}[G(x, 0) - g(x)] = \mathcal{G}(x).$$

By Remark 4 every element of \mathcal{M} is majorized by $\mathcal{G}(x)$ on $\partial B(0, 1)$ and is majorized on $\partial B(0, \frac{1}{2})$ by u and therefore by \mathcal{G} . \mathcal{G} is superelliptic so every element in \mathcal{M} is majorized on $B(0, 1) - B(0, \frac{1}{2})$. Thus u is also majorized; its positive maximum cannot occur on $\partial B(0, 1)$ if it is a solution in B(0, 1).

Appendix. We now establish (23). Q is fixed and $|Q| \le r$.

$$S_1(r) = S(0, Q) - |\text{El}(Q: 0, r^1)|^{-1} \int_{\text{El}(Q: 0, r')} S(M, Q) dM$$

where $r \le r' = r\lambda_1^{-1/2}(Q)$. By a change of variables, the above is equal to

$$|Q'|^{2+\alpha-K}-|B(0,r')|^{-1}\int_{B(0,r')}|M'-Q'|^{2+\alpha-K}dM',$$

where $|Q'| \le r'$, which in turn is equal to

$$r'^{2+\alpha-K}\left\{|Q''|^{2+\alpha-K}-|B(0,1)|^{-1}\int_{B(0,1)}|M''-Q''|^{2+\alpha-K}dM''\right\}$$

where $|Q''| \le 1$. If the term in braces is larger than a positive constant C'_{11} which depends only on α , $0 < \alpha \le 1$, then clearly $C'_{11}r'^{2+\alpha-K} \le C_{11}r^{2+\alpha-K}$ where C_{11} is positive and depends only on C'_{11} , K, K_1 , and K_2 . The expression in braces is equal to

(28)
$$1 - |B(0, |Q''|^{-1})|^{-1} \int_{B(0, |Q''|^{-1})} |M''' - Q'''|^{2 + \alpha - K} dM'''$$

where $|Q'''| = 1 \le |Q''|^{-1}$. We consider

$$|B(0,|Q''|^{-1})|^{-1}\int_{B(0,|Q''|^{-1})}|M'''-Q'''|^{2+\alpha-K}dM'''=f(\alpha)$$

as a function of the complex variable α with domain $0 \le \text{Re } \alpha \le K-2, -1 \le \text{Im } \alpha \le 1$. It is a routine matter to show that $f(\alpha)$ is analytic.

Setting $\alpha = x + iy$ we observe that $|f(x+iy)| \le f(x)$, hence f takes a maximum modulus either at $\alpha = 0$ or at $\alpha = K - 2$. When $\alpha = K - 2$, $f(\alpha) = 1$; when $\alpha = 0$, $0 \le f(\alpha) \le |Q'''|^{2-K} = 1$ by the superharmonicity of the singular solution of Laplace's equation. Thus if f is nonconstant, for positive α we have that $f(\alpha) < 1$. But f is nonconstant if we extend its domain to $-2 < \text{Re } \alpha$.

We fix α in $0 < \alpha \le 1$ and vary |Q''| to show that (28) is strictly positive for $|Q''| \le 1$. But it is obvious since (28) tends to 1 as |Q''| tends to 0. Thus (28) is greater than some positive constant C'_{11} which depends on α .

Proof of Lemma 6. We use the technique in [14, p. 70]. Since u is continuous we can solve LV=0 in B and v=u on ∂B where \overline{B} is any fixed ball in Ω . We need only show that $u \le v$ in B.

Let x be any point in $B-B\cap E$. Since $\operatorname{Cap}(E)=0$, $\operatorname{Cap}(\bar{B}\cap E)=0$. Let $\mathcal{O}_1, \mathcal{O}_2, \ldots$ be a nested sequence of closed sets with smooth boundaries, converging to $\bar{B}\cap E$, such that $\operatorname{Cap}(\mathcal{O}_i)$ tends to 0. Denote by μ_i the equilibrium distribution for \mathcal{O}_i ; it is well known that

$$\Phi_{i}(x) = \int_{\theta_{i}} |x - y|^{2 - K} d\mu_{i}(y) \cdot I(\mu_{i})^{-1}$$

is identically 1 on $\partial \mathcal{O}_i$, where $I(\mu_i)$ is the energy integral and $I(\mu_i) \to \infty$ as $i \to \infty$ since Cap $(\mathcal{O}_i) \to 0$. Form

$$\Psi_{i}(x) = \int_{\mathcal{O}_{i}} G(x, y) d\mu_{i}(y) \cdot I(\mu_{i})^{-1}$$

with G as in Lemma 5. Clearly Ψ_i is superelliptic on $\Omega - \mathcal{O}_i$ and is bounded away from 0 on $\partial \mathcal{O}_i$ by a constant M_1 independent of i. If M_0 is the maximum of u-v in \overline{B} then $u-v \leq M_0 M_1^{-1} \Psi_i$ on $\partial \mathcal{O}_i$ and ∂B and thus in $B-\mathcal{O}_i$. So letting $i \to \infty$, $u(x)-v(x) \leq 0$ for x in $B-B \cap E$, thus, a.e. in \overline{B} , u and v are continuous, so $u \leq v$ in \overline{B} .

The following simple example shows that the t_{α} notion cannot be replaced by the generalized elliptic operators L^* or L_* in Theorems 1 and 3. It also shows that the continuity hypothesis cannot be simply eliminated in Theorem 2.

Define u(x) to be 1 in open upper half space, $0 < x_1, -1$ in open lower half space, and 0 for $x_1 = 0$. Then for each x in E_K

$$\lim_{r \to 0} 2(K+2)|B(0,r)|^{-1}r^{-2} \int_{B(0,r)} u(x+y) - u(x) \, dy = 0$$

so that $\Delta^* u(x) = \Delta_* u(x) = 0$. u is clearly not harmonic in E_K .

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