GROWTH HYPERSPACES OF PEANO CONTINUA1

BY

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ABSTRACT. For X a nondegenerate Peano continuum, let 2^X be the hyperspace of all nonempty closed subsets of X, topologized with the Hausdorff metric. It is known that 2^X is homeomorphic to the Hilbert cube. A nonempty closed subspace \mathcal{G} of 2^X is called a growth hyperspace provided it satisfies the following condition: if $A \in \mathcal{G}$, and $B \in 2^X$ such that $B \supset A$ and each component of B meets A, then also $B \in \mathcal{G}$. The class of growth hyperspaces includes many previously considered subspaces of 2^X . It is shown that if X contains no free arcs, and \mathcal{G} is a nontrivial growth hyperspace, then $\mathcal{G} \setminus \{X\}$ is a Hilbert cube manifold. A corollary characterizes those growth hyperspaces which are homeomorphic to the Hilbert cube. Analogous results are obtained for growth hyperspaces with respect to the hyperspace cc(X) of closed convex subsets of a convex n-cell X.

1. Introduction. Wojdyslawski [17] showed that for every Peano continuum X, the hyperspace 2^X of nonempty closed subsets of X, topologized by the Hausdorff metric, is an absolute retract (AR) for the class of metrizable spaces. Kelley [10] gave another proof of this result which applies as well to any nonempty closed subspace \mathcal{G} of 2^X satisfying the following condition: if $A \in \mathcal{G}$ and $B \in 2^X$ such that $B \supset A$ and each component of B meets A, then $B \in \mathcal{G}$. We call such a subspace \mathcal{G} a growth hyperspace of X. Note that always $X \in \mathcal{G}$. Kelley's proof shows that every growth hyperspace of a Peano continuum is an AR.

More recently, it has been shown [6], [7], [12], [13] that the hyperspace 2^X of every nondegenerate Peano continuum X is homeomorphic to the Hilbert cube Q. This result has also been obtained (with additional hypotheses, in some cases) for certain other growth hyperspaces of X. In particular, if A is a proper closed subset of X, the hyperspaces $2_A^X = \{F \in 2^X | F \supset A\}$ and $2^X(A) = \{F \in 2^X | F \cap A \neq \emptyset\}$ are both homeomorphic to Q [8]. And if X contains no free arcs (i.e., admits no open imbedding of the line), the hyperspace C(X) of nonempty subcontinua of X, as well as the hyperspaces

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 $C_A(X) = C(X) \cap 2_A^X$ and $C(X; A) = C(X) \cap 2^X(A)$, are homeomorphic to O.

Our main objective in this paper is the appropriate extension of these results to the general class of growth hyperspaces of a Peano continuum. Of course not every nontrivial growth hyperspace is homeomorphic to Q (although Edwards' characterization of AR's as Q-factors [4] shows that every growth hyperspace is a Q-factor). For example, $\mathcal{G} = 2^{[-1,1]}_{[-1,0]} \cup 2^{[-1,1]}_{[0,1]}$ is the union of two Hilbert cubes intersecting in a point. Other examples and a more general result appear in §5. The extension takes the following form: under some rather general conditions, the subspace $\mathcal{G} \setminus \{X\}$ of every nontrivial growth hyperspace \mathcal{G} is a [0,1)-stable Q-manifold. As a corollary, we obtain a useful characterization of those growth hyperspaces which are homeomorphic to Q. The above result also has a converse: for every [0,1)-stable Q-manifold M and nondegenerate Peano continuum X, there is a growth hyperspace \mathcal{G} of X such that $\mathcal{G} \setminus \{X\}$ is homeomorphic to M.

For a given Peano continuum X, the class of all growth hyperspaces of X, when partially ordered by set inclusion, forms a complete lattice, with lower bound $\{X\}$ and upper bound 2^X . For any subcollection $\{\mathcal{G}_{\alpha}\}$ of growth hyperspaces, we have $\inf\{\mathcal{G}_{\alpha}\} = \bigcap\{\mathcal{G}_{\alpha}\}$ and $\sup\{\mathcal{G}_{\alpha}\} = \operatorname{cl} \bigcup\{\mathcal{G}_{\alpha}\}$. Thus every closed subspace \mathcal{C} of 2^X generates a growth hyperspace $\mathcal{G}_{\mathcal{C}} = \inf\{\mathcal{G} | \mathcal{G}_{\alpha}\}$ and in fact $\mathcal{G}_{\mathcal{C}} = \{F \in 2^X | \text{ for some } A \in \mathcal{C}, F \supset A \text{ and each component of } F \text{ meets } A\}$.

A growth hyperspace \mathcal{G} which satisfies the following stronger condition is called an *inclusion hyperspace*: if $A \in \mathcal{G}$ and $B \in 2^X$ such that $B \supset A$, then $B \in \mathcal{G}$. Thus 2_A^X and $2^X(A)$ are inclusion hyperspaces. The class of inclusion hyperspaces is a complete sublattice of the lattice of growth hyperspaces.

Finally, we consider the analogue of growth hyperspaces in the setting of the hyperspace cc(X) of nonempty closed convex subsets of a convex *n*-cell X.

2. Convex metrics. Every Peano continuum X admits a convex metric [1]; i.e., a metric d such that for each pair of distinct points x and y, there exists an arc α in X between x and y which is isometric to the closed interval [0, d(x, y)]. Such a metric d (which we may assume to be bounded by 1) defines a natural contraction η of the hyperspace 2^X to the element $\{X\}$: simply set $\eta(F, t) = \{x \in X | d(x, F) \le t\}$. Note that $\eta(\eta(F, t_1), t_2) = \eta(F, t_1 + t_2)$.

There are two fundamental properties of a growth hyperspace \mathcal{G} in relation to the map η :

- (1) $\eta(\mathcal{G} \times I) \subset \mathcal{G}$;
- (2) the function $2^X \to I$, defined by $F \to t_F$ where t_F is the smallest value of t for which $\eta(F, t) \in \mathcal{G}$, is continuous. Consequently, for each pair of growth

hyperspaces \mathcal{G} and \mathcal{K} such that $\mathcal{G} \subset \mathcal{K}$, there is a natural strong deformation retraction $\eta(\mathcal{G}; \mathcal{K}) \colon \mathcal{K} \to \mathcal{G}$, defined by $H \to \eta(H, t_H)$, and for growth hyperspaces $\mathcal{F} \subset \mathcal{G} \subset \mathcal{K}$, we have $\eta(\mathcal{F}; \mathcal{G})\eta(\mathcal{G}; \mathcal{K}) = \eta(\mathcal{F}; \mathcal{K})$. In particular, the existence of the retraction $\eta(\mathcal{G}; 2^X) \colon 2^X \to \mathcal{G}$ gives another proof that every growth hyperspace is an AR. Note that each retraction $\eta(\mathcal{G}; \mathcal{K})$ has contractible point-inverses.

In what follows, X will always denote a Peano continuum.

3. Growth hyperspaces of Peano continua with no free arcs. For $A \in 2^X$, define $G_A(X) = \{ F \in 2^X | F \supset A \text{ and each component of } F \text{ meets } A \}$. Thus $G_A(X)$ is the smallest growth hyperspace of X containing A. The finite union $\bigcup_{i=1}^n G_{A_i}(X)$ of such is the smallest growth hyperspace containing $\{A_1, \ldots, A_n\}$, and will be useful in the proof of our main result.

The proofs in [7] that $2^X \approx Q$ and, for X containing no free arcs, that $C(X) \approx Q$, are based on the construction of inverse sequences of hyperspaces of local dendra imbedded in X. These local dendra are constructed as 1-dimensional nerves of partitions of X, and if X contains no free arcs neither do the local dendra (i.e., the set of branch points is dense). In the following proofs we again consider such local dendra and certain of their growth hyperspaces. The local dendra themselves are most easily viewed as inverse limits of graphs. Thus, let $D = \text{inv} \lim_{\Gamma_i} \Gamma_i$, where each $\Gamma_i \subset D$ is a compact connected graph and each bonding map r_i : $\Gamma_{i+1} \to \Gamma_i$ is a PL retraction with contractible point-inverses. Thus the projection map $r: D \to \Gamma_1$ is a deformation retraction. We refer to Γ_1 as the base of the local dendron D.

LEMMA 3.1. Let A_1, \ldots, A_n be closed subsets of D such that each $A_i = r^{-1}(r(A_i))$ and $\bigcup_{i=1}^n A_i \neq D$. Then if the set of branch points of D is dense, the growth hyperspace $\bigcup_{i=1}^n G_{A_i}(D)$ is homeomorphic to Q.

PROOF. Let $\mathcal{F} = \{ F \in \bigcup_{i=1}^n G_{A_i}(D) | F \subset \bigcup \{A_i | F \in G_{A_i}(D)\} \cup \Gamma_1 \}$. We show that \mathcal{F} is a Z-set in $\bigcup_{i=1}^n G_{A_i}(D)$, and that $\bigcup_{i=1}^n G_{A_i}(D) \setminus \mathcal{F}$ is a Q-manifold. The lemma then follows from a result of Torunczyk [14]: if Y is a Q-factor, $A \subset Y$ is a Z-set, and $Y \setminus A$ is a Q-manifold, then Y is homeomorphic to Q.

For each $\varepsilon > 0$ we must find a map $f: \bigcup_{i=1}^n G_{A_i}(D) \to \bigcup_{i=1}^n G_{A_i}(D) \setminus \mathfrak{F}$ such that $\rho(f, \mathrm{id}) < \varepsilon$. Here ρ is the Hausdorff hyperspace metric induced by a convex metric d on D. Using the fact that D has a dense set of branch points, we may choose $0 < \delta < \varepsilon/2$ such that, for any subinterval J of the base Γ_1 with length $\varepsilon/4$, $\rho(J, r^{-1}(J)) > \delta$. Now define maps f_1 and f_2 of $\bigcup_{i=1}^n G_{A_i}(D)$ into itself as follows: $f_1(B) = B \cup \{x \in \Gamma_1 | d(x, B \cap \Gamma_1) < \varepsilon/2\}$ and $f_2(B) = \{x \in D | d(x, B) \le \delta\}$. Then $\rho(f_2 f_1, \mathrm{id}) \le \varepsilon/2 + \delta < \varepsilon$, and we claim that $f = f_2 f_1$ maps off of \mathfrak{F} . Consider $B \in \bigcup_{i=1}^n G_{A_i}(D)$, and

suppose first that $f_1(B) \cap \Gamma_1$ (which is simply the closed $\varepsilon/2$ -neighborhood of $B \cap \Gamma_1$ in Γ_1) is not contained in $\bigcup_{i=1}^n r(A_i)$. Then clearly $f_2(f_1(B)) \notin \mathcal{F}$. On the other hand, if $f_1(B) \cap \Gamma_1 \subset \bigcup_{i=1}^n r(A_i)$, then since $\bigcup_{i=1}^n r(A_i) \neq \Gamma_1$ and Γ_1 is connected, $f_1(B) \cap \Gamma_1$ must contain a subinterval J of Γ_1 with length $\varepsilon/4$ such that $J \cap B = \emptyset$. Then by the choice of δ , we again have $f_2(f_1(B)) \notin \mathcal{F}$. Thus \mathcal{F} is a Z-set in $\bigcup_{i=1}^n G_A(D)$.

Now consider an element B of $\bigcup_{i=1}^n G_{A_i}(D) \setminus \mathcal{F}$. Let $x \in B \setminus \Gamma_1$ such that $x \notin \bigcup \{A_i | B \in G_{A_i}(D)\}$, and let $x_0 = r(x)$. Then B, and every element of $\bigcup_{i=1}^n G_{A_i}(D)$ sufficiently close to B, must contain x_0 . Let $D_0 = (D \setminus r^{-1}(x_0)) \cup \{x_0\}$. Clearly, both D_0 and $r^{-1}(x_0)$ are compact connected local dendra whose sets of branch points are dense. Thus the growth hyperspace $G_0 = \bigcup \{G_{A_i}(D_0) | B \in G_{A_i}(D)\} \cap 2_{x_0}^{D_0}$ is a Q-factor, and the hyperspace of subcontinua $C_{x_0}(r^{-1}(x_0))$ is homeomorphic to Q, and clearly this product is homeomorphic to a neighborhood of the element B in $\bigcup_{i=1}^n G_{A_i}(D)$. Therefore $\bigcup_{i=1}^n G_{A_i}(D) \setminus \mathcal{F}$ is a Q-manifold.

LEMMA 3.2. Let X be a Peano continuum with no free arcs, and A_1, \ldots, A_n nonempty closed subsets of X such that $\bigcup_{i=1}^n A_i \neq X$. Then for each $\varepsilon > 0$ there exist elements $B_1 \in G_{A_1}(X), \ldots, B_n \in G_{A_n}(X)$ with $B_1 \subset \eta(A_1, \varepsilon), \ldots, B_n \subset \eta(A_n, \varepsilon)$, such that $\bigcup_{i=1}^n G_{B_i}(X)$ is homeomorphic to Q.

PROOF. We use the construction of partition refinements, nerves, and local dendra detailed in [7] for the proof that the hyperspace of subcontinua C(X) is homeomorphic to Q. This construction yielded a sequence $\{G_i\}$ of partitions of X, with each G_{i+1} refining G_i and mesh $G_i \to 0$, a corresponding sequence $\{\Gamma_i\}$ of compact connected graphs in X, with each Γ_i a nerve of G_i , and a sequence $\{D_i\}$ of compact connected local dendra in X, with each D_i based on Γ_i (see the discussion preceding Lemma 3.1) and having a dense set of branch points. For each partition element $g \in G_i$, we have $D_i \cap Bd g = \Gamma_i \cap Bd g$ and $D_i \cap \overline{g} = p_i^{-1}(\Gamma_i \cap \overline{g})$, where $p_i \colon D_i \to \Gamma_i$ is the projection map. Furthermore, there exists a sequence of C-monotone piecewise-linear maps $\varphi_i \colon \Gamma_{i+1} \to C(\Gamma_i)$, inducing in turn sequences of near-homeomorphisms $f_i \colon 2^{D_{i+1}} \to 2^{D_i}$ and $g_i = f_i|_{C(D_{i+1})} \colon C(D_{i+1}) \to C(D_i)$, such that

$$C(X) \approx \operatorname{inv} \lim (C(D_i), g_i) \approx Q$$

(using the inverse sequence Approximation Lemma 2.1 of [6]).

For each $i \le n$, let $G_1(A_i) = \{g \in G_1 | \bar{g} \cap A_i \neq \emptyset\}$ and $A_{i,1} = \bigcup \{\bar{g} | g \in G_1(A_i)\}$. Then $A_i \subset \text{int } A_{i,1}$, $A_{i,1} \in G_{A_i}(X)$, and if mesh G_1 is small enough, $A_{i,1} \subset \eta(A_i, \varepsilon)$ and $\bigcup_{i=1}^n A_{i,1} \neq X$. It follows from Lemma 3.1 that $\bigcup_{i=1}^n G_{A_{i,1} \cap D_1}(D_1) \approx Q$.

The construction in [7] of the partition refinement G_2 , nerve Γ_2 , and C-monotone map $\varphi_1: \Gamma_2 \to C(\Gamma_1)$ is such that, for arbitrary $\delta > 0$, we may

assume that for each $g \in G_2$, $\varphi_1(\bar{g} \cap \Gamma_2) \subset \bigcup \{\bar{g}' | g' \in G_1 \text{ and } g \cap N_{\delta}(g') \neq \emptyset\}$. Now set $G_2(A_i) = \{g \in G_2 | g \subset g' \in G_1(A_i) \text{ and } \varphi_1(\bar{g} \cap \Gamma_2) \subset A_{i,1}\}$, and $A_{i,2} = \bigcup \{\bar{g} | g \in G_2(A_i)\}$. It follows that if mesh G_2 is small enough, $A_i \subset \text{int } A_{i,2} \text{ and } A_{i,2} \in G_{A_i}(X)$. Again by Lemma 3.1, $\bigcup_{i=1}^n G_{A_{i,2} \cap D_2}(D_2) \approx Q$.

We claim that the map $f_1: 2^{D_2} \to 2^{D_1}$, induced essentially by the map φ_1 , restricts to a surjection $f_1: \bigcup_{i=1}^n G_{A_{i,2} \cap D_2}(D_2) \to \bigcup_{i=1}^n G_{A_{i,1} \cap D_1}(D_1)$ with contractible point-inverses. First note that, because φ_1 is C-monotone, and due to the choice of $G_2(A_i)$, we have $f_1(A_{i,2} \cap D_2) = A_{i,1} \cap D_1$ for each i < n. Thus $f_1(\bigcup_{i=1}^n G_{A_{i,2} \cap D_2}(D_2)) \subset \bigcup_{i=1}^n G_{A_{i,1} \cap D_1}(D_1)$. The argument that each point-inverse of the restriction of f_1 is nonempty and contractible follows from the argument given for Theorem 3.5 of [6]. Thus, for arbitrary $K \in G_{A_{i,1} \cap D_1}(D_1)$, i < n, set $K' = \{x \in D_2 | f_1(\{x\}) \subset K\}$. Then $f_1(K') = K$, and $K' \in G_{A_{i,2} \cap D_2}(D_2)$. Moreover, the "expansion homotopy" which contracts the point-inverse $f_1^{-1}(K) \subset 2^{D_2}$ of $f_1: 2^{D_2} \to 2^{D_1}$ to the element K' restricts to a contraction of $f_1^{-1}(K) \cap G_{A_{i,2} \cap D_2}(D_2)$ to K', since $G_{A_{i,2} \cap D_2}(D_2)$ is a growth hyperspace.

By a theorem of Chapman [4], every surjection between copies of Q which has contractible point-inverses is a near-homeomorphism. Thus the above restriction of f_1 is a near-homeomorphism.

Continuing in this fashion, we inductively set $G_{k+1}(A_i) = \{g \in G_{k+1} | g \subset g' \in G_k(A_i) \text{ and } \varphi_k(\bar{g} \cap \Gamma_{k+1}) \subset A_{i,k}\}$, and $A_{i,k+1} = \bigcup \{\bar{g} | g \in G_{k+1}(A_i)\}$, for each $i \leq n$ and $k \geq 1$. If mesh G_{k+1} is small enough, $A_{i,k+1} \in G_{A_i}(X)$. As before, the restricted map $f_k : \bigcup_{i=1}^n G_{A_{i,k+1} \cap D_{k+1}}(D_{k+1}) \to \bigcup_{i=1}^n G_{A_{i,k} \cap D_k}(D_k)$ is a near-homeomorphism. Then taking $B_i = \bigcap_{k=1}^\infty A_{i,k}$ for each i, we obtain

$$\bigcup_{i=1}^{n} G_{B_{i}}(X) \approx \operatorname{inv} \lim \left(\bigcup_{i=1}^{n} G_{A_{i,k} \cap D_{k}}(D_{k}), f_{k} \right) \approx Q.$$

A Q-manifold M is [0, 1)-stable if $M \approx M \times [0, 1)$. Chapman [2] showed that [0, 1)-stable Q-manifolds are topologically classified by homotopy type. Wong [18] showed that M is [0, 1)-stable if and only if M is properly contractible to infinity (i.e., for every compact subset $K \subset M$, there exists a proper homotopy $\{f_i\}: M \to M$ with $f_0 = \operatorname{id} \operatorname{and} f_1(M) \subset M \setminus K$).

THEOREM 3.1. If \mathcal{G} is a nontrivial growth hyperspace of a Peano continuum X with no free arcs, then $\mathcal{G} \setminus \{X\}$ is a [0, 1)-stable Q-manifold.

PROOF. Let $A \in \mathcal{G} \setminus \{X\}$, and let $\{A_i\}$ be a sequence in \mathcal{G} which is dense in a neighborhood of A in \mathcal{G} , and such that $\bigcup_{i=1}^{\infty} A_i \neq X$. By Lemma 3.2 there exists, for each $j \geq 1$ and $0 < \varepsilon_j < 2^{-j}$, elements B_1^j, \ldots, B_j^j of \mathcal{G} such that each $B_i^j \in G_{A_i}(X)$, $B_i^j \subset \eta(A_i, \varepsilon_j)$, and $\bigcup_{i=1}^{j} G_{B_i^j}(X) \approx Q$. We may assume also that each B_i^j is a neighborhood of A_i (simply replace each A_i by a sufficiently small neighborhood $\eta(A_i, \delta)$ before applying Lemma 3.2). Thus

the sequence of positive constants $\{\varepsilon_j\}$ may be inductively chosen so that $B_i^{j+1} \subset B_i^j$ for each i < j, with $\bigcap_{j=i}^{\infty} B_i^j = A_i$ for each i. Note that

$$\bigcup_{i=1}^{j} G_{B_i^i}(X) \subset \bigcup_{i=1}^{j+1} G_{B_i^{j+1}}(X) \subset \bigcup_{i=1}^{j+1} G_{A_i}(X) \subset \mathcal{G}$$

for each j, and

$$\lim_{j\to\infty}\bigcup_{i=1}^{j}G_{B_{i}^{j}}(X)=\operatorname{cl}\bigcup_{j=1}^{\infty}\bigcup_{i=1}^{j}G_{B_{i}^{j}}(X)\supset\operatorname{cl}\bigcup_{i=1}^{\infty}G_{A_{i}}(X)$$

is a neighborhood of A in \mathcal{G} (the limit operation indicated by $\lim_{j\to\infty}$ takes place in the space $2^{\mathcal{G}}$ of closed subspaces of \mathcal{G}).

Now consider the inverse sequence

$$G_{B_1^1}(X) \stackrel{f_1}{\leftarrow} G_{B_1^2}(X) \cup G_{B_2^2}(X) \stackrel{f_2}{\leftarrow} \ldots,$$

where each bonding map $f_j: \bigcup_{i=1}^{j+1} G_{B_i^{j+1}}(X) \to \bigcup_{i=1}^{j} G_{B_i^{j}}(X)$ is defined by

$$f_j = \eta \left(\bigcup_{i=1}^j G_{B_i^j}(X); \bigcup_{i=1}^{j+1} G_{B_i^{j+1}}(X) \right),$$

as in §2. Each f_j has contractible point-inverses, and is therefore a near-homeomorphism. By the Approximation Lemma of [6], $\lim_{j\to\infty} \bigcup_{i=1}^j G_{B_i^j}(X)$ $\approx \text{inv } \lim(\bigcup_{i=1}^j G_{B_i^j}(X), f_j) \approx Q$. Thus the element A has a Q-neighborhood in \mathcal{G} , and $\mathcal{G} \setminus \{X\}$ is a Q-manifold.

It remains to show that $\mathcal{G} \setminus \{X\}$ is properly contractible to infinity. Let \mathcal{K} be a compact subspace of $\mathcal{G} \setminus \{X\}$, and choose $\varepsilon > 0$ such that $\rho(K, X) > \varepsilon$ for each $K \in \mathcal{K}$. Let \mathcal{F} be the growth hyperspace $\{F \in \mathcal{G} | \rho(F, X) \leq \varepsilon\}$. Then the deformation $\{\eta_t\}$ associated with the retraction $\eta(\mathcal{F}; \mathcal{G}): \mathcal{G} \to \mathcal{F}$ restricts to the desired proper homotopy of $\mathcal{G} \setminus \{X\}$. Specifically, define $\eta_t(F) = \eta(F, ts_F)$, where s_F is the smallest value of s for which $\eta(F, s) \in \mathcal{F}$. Each η_t maps $\mathcal{G} \setminus \{X\}$ into itself, $\eta_0 = \mathrm{id}$, $\eta_1(\mathcal{G} \setminus \{X\}) \cap \mathcal{K} = \mathcal{O}$, and obviously $\{\eta_t\}$ is proper. Thus $\mathcal{G} \setminus \{X\}$ is a [0, 1)-stable Q-manifold.

4. Inclusion hyperspaces. We first obtain an analogue of Lemma 3.2.

LEMMA 4.1. Let A_1, \ldots, A_n be nonempty closed subsets of a Peano continuum X such that $\bigcup_{i=1}^n A_i \neq X$. Then for each $\varepsilon > 0$ there exist closed sets $B_1 = \eta(A_1, \delta_1), \ldots, B_n = \eta(A_n, \delta_n)$, with $0 < \delta_i \leq \varepsilon$ for each i, such that the inclusion hyperspace $\bigcup_{i=1}^n 2_{B_i}^X$ is homeomorphic to Q.

PROOF. We may assume that $A_i \setminus A_j \neq \emptyset$, and that in fact $A_i \setminus \eta(A_j, \varepsilon) \neq \emptyset$, for each $i \neq j$. Also assume that $\eta(\bigcup_{i=1}^n A_i, \varepsilon) \neq X$. Since X is connected, the proper closed subset $\bigcup_{i=1}^n A_i$ has a boundary; reindexing the A_i , we may suppose that $A_n \cap \operatorname{bd}(\bigcup_{i=1}^n A_i) \neq \emptyset$. Then take $B_n = \eta(A_n, \varepsilon)$. Note that

int $B_n \setminus \bigcup_{i=1}^{n-1} A_i \neq \emptyset$. By the same argument we may suppose that $A_{n-1} \cap \operatorname{bd}(\bigcup_{i=1}^{n-1} A_i) \neq \emptyset$. Then take $B_{n-1} = \eta(A_{n-1}, \delta)$, where $0 < \delta \le \varepsilon$ is small enough that int $B_n \setminus (\bigcup_{i=1}^{n-1} A_i \cup B_{n-1}) \neq \emptyset$. Note that int $B_{n-1} \setminus \bigcup_{i=1}^{n-2} A_i \neq \emptyset$. Continuing in this fashion we obtain closed sets B_1, \ldots, B_n such that $\bigcup_{i=1}^n B_i \neq X$, int $B_i \setminus \bigcup_{j=1}^{i-1} B_j \neq \emptyset$ for each i, and int $B_i \setminus B_j \neq \emptyset$ for i < j. The proof of Lemma 5.5 of [8] then shows immediately that $\bigcup_{i=1}^n 2_{B_i}^X \approx Q$.

THEOREM 4.1. If \mathcal{G} is a nontrivial inclusion hyperspace of a Peano continuum X, then $\mathcal{G} \setminus \{X\}$ is a [0, 1)-stable Q-manifold.

PROOF. One uses the same type of inverse sequence construction as in the proof of Theorem 3.1, with Lemma 4.1 taking the place of Lemma 3.2.

5. Applications and examples.

COROLLARY 5.1. Let G be a nontrivial growth hyperspace of a Peano continuum X, such that either X contains no free arcs or G is an inclusion hyperspace. Then the following statements are equivalent:

- (1) $\mathcal{G} \approx Q$;
- (2) $\mathcal{G} \setminus \{X\}$ is contractible;
- (3) $\{X\}$ is a Z-set in \mathcal{G} .

PROOF. Obviously $(1) \Rightarrow (2)$, (3). By Chapman's classification theorem [2], every contractible [0, 1)-stable Q-manifold is homeomorphic to $Q \times [0, 1)$. Thus $(2) \Rightarrow \mathcal{G} \approx \text{Cone } Q \approx Q$. The result of Torunczyk used in the proof of Lemma 3.1 (or an earlier version due to West [16]) shows that $(3) \Rightarrow (1)$.

It was shown in [8] that for $A_1, \ldots, A_n \in 2^X$, the inclusion hyperspace $2^X(A_1, \ldots, A_n) = \{F \in 2^X | F \cap A_i \neq \emptyset \text{ for each } i\}$ is homeomorphic to Q, and that the growth hyperspace $C(X; A_1, \ldots, A_n) = C(X) \cap 2^X(A_1, \ldots, A_n)$ is homeomorphic to Q if X contains no free arcs. Alternatively, these results may be deduced from Corollary 5.1. Let $y \in X \setminus \bigcup_{i=1}^n \operatorname{bd} A_i$. Given $\varepsilon > 0$, choose $0 < \delta < \varepsilon$ such that $\eta(y, \delta)$ does not intersect $\bigcup_{i=1}^n \operatorname{bd} A_i$. By Lemma 5.4 of [8], there exists a map $f: 2^X \to 2^X \setminus 2^X_{\eta(y,\delta/2)}$ such that $\rho(f,\operatorname{id}) < \delta/2$, $f(B) \setminus \eta(y,\delta/2) = B \setminus \eta(y,\delta/2)$ for each $B \in 2^X$, and if X contains no free arcs, f maps C(X) into itself. It follows that f maps $2^X(A_1, \ldots, A_n)$ into $2^X(A_1, \ldots, A_n) \setminus \{X\}$, and if X contains no free arcs, f maps $C(X; A_1, \ldots, A_n) \setminus \{X\}$.

The result (previously unpublished) that $\bigcup_{i=1}^{n} 2_{A_i}^{X}$ is homeomorphic to Q if $\bigcup_{i=1}^{n} A_i \neq X$ also follows from the Corollary 5.1. Let N be any closed subset of $X \setminus \bigcup_{i=1}^{n} A_i$ with nonempty interior; then again by Lemma 5.4 of [8], there exists for each $\varepsilon > 0$ a map $f: 2^X \to 2^X \setminus 2_N^X$ such that $\rho(f, \text{id}) < \varepsilon$ and $f(B) \setminus N = B \setminus N$ for each $B \in 2^X$. Thus f maps $\bigcup_{i=1}^{n} 2_{A_i}^X$ into $\bigcup_{i=1}^{n} 2_{A_i}^X \setminus \{X\}$. If furthermore X contains no free arcs, then f maps $\bigcup_{i=1}^{n} C_{A_i}(X)$ into $\bigcup_{i=1}^{n} C_{A_i}(X) \setminus \{X\}$, and thus $\bigcup_{i=1}^{n} C_{A_i}(X)$ is homeomorphic to Q. In this

case the same argument shows also that both $\bigcup_{i=1}^n G_{A_i}(X)$ and $\bigcap_{i=1}^n G_{A_i}(X)$ are homeomorphic to Q.

We can place these results in a more general setting by considering Q_0 -decompositions. Let $Q_0 = Q \setminus \text{point} \approx Q \times [0, 1)$. A Q_0 -decomposition of a separable locally compact metric space Y is a star-finite, locally finite closed cover $\{\beta_i\}$ of Y such that each nonempty intersection $\beta_{i_1} \cap \cdots \cap \beta_{i_n}$, $n \ge 1$, is homeomorphic to Q_0 . The nerve K of $\{\beta_i\}$ is the abstract complex whose vertices are the elements of $\{\beta_i\}$ and whose simplices are those subcollections of $\{\beta_i\}$ with a nonempty intersection.

LEMMA 5.1 [5]. Let $\{\beta_i\}$ be a Q_0 -decomposition of Y with nerve K. Then $Y \times Q \approx |K| \times Q_0$.

COROLLARY 5.2. Let X be a Peano continuum, with proper closed subsets A_1, \ldots, A_n , and let K be the abstract complex whose vertices are the sets A_i and whose simplices are those subcollections of $\{A_i\}$ whose union is a proper subset of X. Then $\bigcup_{i=1}^{n} 2_{A_i}^{X}$ is homeomorphic to the cone over $|K| \times Q$. If furthermore X contains no free arcs, then both $\bigcup_{i=1}^{n} C_{A_i}(X)$ and $\bigcup_{i=1}^{n} G_{A_i}(X)$ are homeomorphic to the cone over $|K| \times Q$.

PROOF. The collection $\{2_{A_i}^X \setminus \{X\}\}$ is a finite Q_0 -decomposition of $\bigcup_{i=1}^n 2_{A_i}^X \setminus \{X\}$, with nerve K. Then since $\bigcup_{i=1}^n 2_{A_i}^X \setminus \{X\}$ is a Q-manifold, $\bigcup_{i=1}^n 2_{A_i}^X \setminus \{X\} \approx (\bigcup_{i=1}^n 2_{A_i}^X \setminus \{X\}) \times Q \approx |K| \times Q_0$. Thus $\bigcup_{i=1}^n 2_{A_i}^X$ is homeomorphic to the one-point compactification of $|K| \times Q \times [0, 1)$, i.e., $\bigcup_{i=1}^n 2_{A_i}^X \approx \operatorname{Cone}(|K| \times Q)$. Similarly for $\bigcup_{i=1}^n C_{A_i}(X)$ and $\bigcup_{i=1}^n G_{A_i}(X)$; in the latter case we use the result established above that $\bigcap_{i=1}^k G_{A_i}(X) \approx Q$ if (and only if) $\bigcup_{i=1}^k A_i \neq X$.

Note that the cone over $|K| \times Q$ is homeomorphic to Q if and only if |K| is contractible. This includes, but is not limited to, the situation where $\bigcup_{i=1}^{n} A_i \neq X$.

COROLLARY 5.3. Let \mathcal{G} be a growth hyperspace of a Peano continuum X, such that either X contains no free arcs or \mathcal{G} is an inclusion hyperspace. If for each $\varepsilon > 0$ there exists an ε -net $\{A_1, \ldots, A_n\}$ in \mathcal{G} whose complex K (in the sense of Corollary 5.2) is contractible, then \mathcal{G} is homeomorphic to Q.

PROOF. Given $\varepsilon > 0$, let $\{A_1, \ldots, A_n\}$ be an $\varepsilon/2$ -net in \mathcal{G} with contractible complex K. The retraction $\eta = \eta(\bigcup_{i=1}^n G_{A_i}(X); \mathcal{G})$: $\mathcal{G} \to \bigcup_{i=1}^n G_{A_i}(X)$ is within $\varepsilon/2$ of the identity map. Now suppose X contains no free arcs. Then $\bigcup_{i=1}^n G_{A_i}(X)$ is homeomorphic to Q, the element $\{X\}$ is a Z-set in $\bigcup_{i=1}^n G_{A_i}(X)$, and there exists a map $f: \bigcup_{i=1}^n G_{A_i}(X) \to \bigcup_{i=1}^n G_{A_i}(X) \setminus \{X\}$ such that $\rho(f, \mathrm{id}) < \varepsilon/2$. The composition $f\eta: \mathcal{G} \to \mathcal{G} \setminus \{X\}$ satisfies $\rho(f\eta, \mathrm{id}) < \varepsilon$, thus $\{X\}$ is a Z-set in \mathcal{G} , and \mathcal{G} is homeomorphic to Q. The analogous

argument in the case that \mathcal{G} is an inclusion hyperspace uses the retraction $\eta(\bigcup_{i=1}^{n} 2_{A}^{X}; \mathcal{G})$.

We also use the Q_0 -decomposition lemma to obtain a converse for Theorems 3.1 and 4.1.

THEOREM 5.1. For every [0, 1)-stable Q-manifold M and nondegenerate Peano continuum X, there exists an inclusion hyperspace \mathcal{G} of X such that $\mathcal{G} \setminus \{X\} \approx M$.

PROOF. By Chapman's triangulation theorem [3], there exists a countable locally finite simplicial complex K such that $|K| \times Q_0 \approx M$. Let $\{\sigma_i\}$ be an enumeration of the simplices of K. Choose a sequence $\{U_i\}$ of disjoint nonempty open sets in X such that $\lim_{i\to\infty}\overline{U_i}=\{p\}$ for some $p\in X$. For each vertex v of K, define $U_v=\bigcup\{U_i|v\in\sigma_i\}$. Then take $\mathscr{G}=\bigcup\{2_{X\setminus U_v}^X|v$ a vertex of K}. The cover $\{2_{X\setminus U_v}^X\setminus\{X\}\}$ of $\mathscr{G}\setminus\{X\}$ is a Q_0 -decomposition with nerve K. Thus $\mathscr{G}\setminus\{X\}\approx(\mathscr{G}\setminus\{X\})\times Q\approx|K|\times Q_0\approx M$.

6. Convex growth hyperspaces. Let X be a convex n-cell, and cc(X) the hyperspace of nonempty closed convex subsets. It is known [11] that cc(X) is homeomorphic to Q for n > 1. A nonempty closed subspace \mathcal{G} of cc(X) is a convex growth hyperspace provided it satisfies the following condition: if $A \in \mathcal{G}$ and $B \in cc(X)$ such that $B \supset A$, then $B \in \mathcal{G}$.

Let d be the Euclidean metric on a convex n-cell $X \subset \mathbb{R}^n$. Then the contraction η of cc(X) to the point $\{X\}$ is defined as in §2, and for convex growth hyperspaces $\mathcal{G} \subset \mathcal{K}$, we also have the strong deformation retraction $\eta(\mathcal{G}; \mathcal{K})$ of \mathcal{K} to \mathcal{G} . Thus every convex growth hyperspace is a retract of cc(X), and is therefore an AR and a O-factor.

THEOREM 6.1. If G is a nontrivial convex growth hyperspace of a convex n-cell X, n > 1, then $G \setminus \{X\}$ is a [0, 1)-stable Q-manifold.

For the proof of Theorem 6.1 we consider the convex growth hyperspaces $cc_A(X) = \{B \in cc(X) | B \supset A\}$, where $A \in 2^X$. We could of course replace A by its convex hull conv A. If conv $A \neq X$ and n > 1, it is also known [11] that $cc_A(X)$ is homeomorphic to Q. We first obtain the convex analogue of Lemma 4.1.

LEMMA 6.1. Let A_1, \ldots, A_k be closed subsets of the convex n-cell X, n > 1, such that conv $(\bigcup_{i=1}^k A_i) \neq X$. Then $\bigcup_{i=1}^k \operatorname{cc}_{A_i}(X) \approx Q$.

The proof of Lemma 6.1 requires the following technical lemmas.

LEMMA 6.2. Let $A \in cc(X)$ and $p \in bd X \setminus A$. Then for every $\varepsilon > 0$ there exists a hyperplane H strictly separating A and p and such that $\rho(X, X \cap H^+) < \varepsilon$, where H^+ is the closed half-space of \mathbb{R}^n containing A.

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PROOF. Let $B \subset \operatorname{int} X$ be a compact set such that $\rho(X, B) < \varepsilon$. Then $\operatorname{conv}(A \cup B)$ and p are disjoint, and there exists a hyperplane H strictly separating them (Theorem 2.10 of [15]). Clearly, $\rho(X, X \cap H^+) < \rho(X, B) < \varepsilon$.

LEMMA 6.3. Let A be a closed subset of the convex n-cell X, n > 1, such that $A \cap \operatorname{bd} X \neq \emptyset$ and $\operatorname{conv} A \neq X$. Then $A \cap \operatorname{cl}(\operatorname{bd} X \setminus \operatorname{conv} A) \neq \emptyset$.

PROOF. Since X is the closed convex hull of the set of its exposed points [15, Theorem 11.6], there exists an exposed point q of X which is not in conv A. Let H be a supporting hyperplane for X through q such that $H \cap X = q$, and let H' be the translate of H supporting $A \cap \operatorname{bd} X$. Then H' must also support conv $A \cap \operatorname{bd} X$, and we have $\emptyset = H' \cap A \cap \operatorname{bd} X \subset A \cap \operatorname{cl}(\operatorname{bd} X \setminus \operatorname{conv} A)$.

PROOF OF LEMMA 6.1. Suppose first that $\bigcup_{i=1}^k A_i \subset \operatorname{int} X$. Let $\mathfrak{F} = \{B \in \bigcup_{i=1}^k \operatorname{cc}_{A_i}(X) | \operatorname{int} B \not\supseteq A_i \text{ for each } i\}$. We claim that \mathfrak{F} is a Z-set in $\bigcup_{i=1}^k \operatorname{cc}_{A_i}(X)$ and $\bigcup_{i=1}^k \operatorname{cc}_{A_i}(X) \setminus \mathfrak{F}$ is a Q-manifold. The ε -expansion defined by $B \to \eta(B, \varepsilon)$ gives a map $f \colon \bigcup_{i=1}^k \operatorname{cc}_{A_i}(X) \to \bigcup_{i=1}^k \operatorname{cc}_{A_i}(X) \setminus \mathfrak{F}$ with $\rho(f, \operatorname{id}) \leq \varepsilon$. And for any $B \in \bigcup_{i=1}^k \operatorname{cc}_{A_i}(X) \setminus \mathfrak{F}$, we have $A_j \subset \operatorname{int} B$ for some f, thus $\operatorname{cc}_{A_j}(X)$ is a Q-neighborhood of f in f in f in f in the theorem of Torunczyk previously cited implies that in this case the Q-factor f is homeomorphic to f.

Now suppose that $\bigcup_{i=1}^k A_i \cap \operatorname{bd} X \neq \emptyset$. The proof is by induction on k. By Lemma 6.3 we have $\bigcup_{i=1}^k A_i \cap \operatorname{cl}(\operatorname{bd} X \setminus \operatorname{conv}(\bigcup_{i=1}^k A_i)) \neq \emptyset$, and we may assume that $A_k \cap \operatorname{cl}(\operatorname{bd} X \setminus \operatorname{conv}(\bigcup_{i=1}^k A_i)) \neq \emptyset$. Let B_k be a sufficiently small closed neighborhood of A_k in X, so that $\operatorname{conv}(\bigcup_{i=1}^{k-1} A_i \cup B_k) \neq X$. We claim that the hyperspace $\bigcup_{i=1}^{k-1} \operatorname{cc}_{A_i}(X) \cup \operatorname{cc}_{B_k}(X)$ is homeomorphic to Q. By the induction hypothesis $\bigcup_{i=1}^{k-1} \operatorname{cc}_{A_i}(X)$, $\operatorname{cc}_{B_k}(X)$, and their intersection $\bigcup_{i=1}^{k-1} \operatorname{cc}_{A_i \cup B_k}(X)$ are each homeomorphic to Q. If we can show that $\bigcup_{i=1}^{k-1} \operatorname{cc}_{A_i \cup B_k}(X)$ is a Z-set in $\bigcup_{i=1}^{k-1} \operatorname{cc}_{A_i}(X)$, the claimed result follows from Handel's Sum Theorem for Hilbert cubes [9].

There exists $p \in (B_k \cap \operatorname{bd} X) \setminus \operatorname{conv}(\bigcup_{i=1}^k A_i)$. By Lemma 6.2 there exists, for every $\varepsilon > 0$, a hyperplane H strictly separating $\operatorname{conv}(\bigcup_{i=1}^{k-1} A_i)$ and p, such that the nearest-point map $\tau \colon X \to X \cap H^+$ satisfies $d(\tau, \operatorname{id}) \le \varepsilon$, where H^+ is the closed half-space of R^n containing $\operatorname{conv}(\bigcup_{i=1}^{k-1} A_i)$. Then the map $f \colon \bigcup_{i=1}^{k-1} \operatorname{cc}_{A_i}(X) \to \bigcup_{i=1}^{k-1} \operatorname{cc}_{A_i}(X) \setminus \operatorname{cc}_{B_k}(X)$, defined by $f(D) = \operatorname{conv} \tau(D)$, satisfies $\rho(f, \operatorname{id}) \le \varepsilon$. Thus $\bigcup_{i=1}^{k-1} \operatorname{cc}_{A_i}(X) \cup \operatorname{cc}_{B_k}(X)$ is homeomorphic to Q.

We may now routinely obtain the hyperspace $\bigcup_{i=1}^k \operatorname{cc}_{A_i}(X)$ as the limit of a monotone inverse sequence of hyperspaces of the above form $\bigcup_{i=1}^{k-1} \operatorname{cc}_{A_i}(X)$ $\cup \operatorname{cc}_{B_k}(X)$, by considering successively smaller neighborhoods B_k of A_k , and using as bonding maps the retractions derived from the expansion map η . This construction is the same as that given in the proof of Theorem 3.1. Thus

by the inverse sequence approximation lemma, $\bigcup_{i=1}^k \operatorname{cc}_{A_i}(X)$ is homeomorphic to Q.

PROOF OF THEOREM 6.1. Let $A \in \mathcal{G} \setminus \{X\}$. There exists a closed neighborhood \mathfrak{N} of A in \mathcal{G} such that for each subset $\{A_1, \ldots, A_k\} \subset \mathfrak{N}$, $\operatorname{conv}(\bigcup_{i=1}^k A_i) \neq X$. Let $\{A_i\}$ be a dense sequence in \mathfrak{N} , and consider the inverse sequence

$$\operatorname{cc}_{A_1}(X) \stackrel{f_1}{\leftarrow} \operatorname{cc}_{A_2}(X) \cup \operatorname{cc}_{A_3}(X) \stackrel{f_2}{\leftarrow} \cdots,$$

where each f_i is the η retraction. By Lemma 6.1 each coordinate space is homeomorphic to Q. The limit space is the closed neighborhood $\{F \in \operatorname{cc}(X)|F \supset B \text{ for some } B \in \mathfrak{N}\}$ of A in \mathcal{G} , and the approximation lemma applies, showing that this neighborhood is homeomorphic to Q. The argument that $\mathcal{G} \setminus \{X\}$ is properly contractible to infinity is the same as in the proof of Theorem 3.1.

COROLLARY 6.1. Let \mathcal{G} be a nontrivial convex growth hyperspace of a convex n-cell X, n > 1. Then the following statements are equivalent:

- (1) $\mathcal{G} \approx Q$;
- (2) $\mathcal{G} \setminus \{X\}$ is contractible;
- $(3)\{X\}$ is a Z-set in \mathcal{G} .

COROLLARY 6.2. Let A_1, \ldots, A_k be closed subsets of the convex n-cell X, n > 1, with each conv $A_i \neq X$, and let K be the abstract complex whose vertices are the sets A_i and whose simplices are those subcollections $\{A_{i_j}\}$ for which conv $(\bigcup A_{i_j}) \neq X$. Then $\bigcup_{i=1}^k \operatorname{cc}_{A_i}(X)$ is homeomorphic to the cone over $|K| \times Q$.

COROLLARY 6.3. Let A be a nonempty closed subset of the convex n-cell X, n > 1. Then the convex growth hyperspace $cc(X; A) = \{F \in cc(X) | F \cap A \neq \emptyset\}$ is homeomorphic to Q, unless A is precisely the vertex set $\{v_1, \ldots, v_k\}$ of a polyhedral X, in which case cc(X; A) is homeomorphic to the cone over $S^{k-2} \times Q$.

PROOF. The complex $K(x_1, \ldots, x_k)$ associated with a collection $\{x_1, \ldots, x_k\}$ of points in X, as in Corollary 6.2, is obviously contractible if $\operatorname{conv}\{x_1, \ldots, x_k\} \neq X$. On the other hand, if the convex hull of some proper subcollection of $\{x_1, \ldots, x_k\}$ is X, this subcollection must include all the vertices of X; there exists some x_i which is not a vertex; the complex $K(x_1, \ldots, x_k)$ is star-shaped from x_i , and therefore contractible. Thus $K(x_1, \ldots, x_k)$ is contractible unless $\{x_1, \ldots, x_k\}$ is a minimal spanning set for X, i.e., the vertex set of X, in which case $K(x_1, \ldots, x_k)$ is a combinatorial (k-2)-sphere.

If A is not the vertex set of X, there exists a dense sequence $\{x_i\}$ in A such

that for each k, $\{x_1, \ldots, x_k\}$ is not the vertex set of X. Then by the above argument and Corollary 6.2, the hyperspace $\bigcup_{i=1}^k \mathrm{cc}_{x_i}(X)$ is homeomorphic to Q for each k. Since $\lim_{k\to\infty}\bigcup_{i=1}^k \mathrm{cc}_{x_i}(X)=\mathrm{cc}(X;A)$, consideration of the inverse sequence

$$\operatorname{cc}_{x_1}(X) \stackrel{f_1}{\leftarrow} \operatorname{cc}_{x_1}(X) \cup \operatorname{cc}_{x_2}(X) \stackrel{f_2}{\leftarrow} \cdots,$$

where each f_i is the η retraction, shows that cc(X; A) is homeomorphic to Q. The result in the case where A is the vertex set of X follows directly from Corollary 6.2.

As before, Theorem 6.1 has a converse.

THEOREM 6.2. For every [0, 1)-stable Q-manifold M and every n > 1, there exists a convex growth hyperspace \mathcal{G} of a convex n-cell X such that $\mathcal{G} \setminus \{X\} \approx M$.

PROOF. First consider the case n=2. Let X be a convex 2-cell with a countable set of exposed points $E=\{x_1,x_2,\ldots,x_\infty\}$, such that $x_i\to x_\infty$ and bd $X=\overline{x_\infty x_1}\cup \overline{x_1x_2}\cup \overline{x_2x_3}\cup\cdots$. Let K be a countable locally finite simplicial complex such that $M\approx |K|\times Q_0$, and let $\{\sigma_i\}$ be an enumeration of the simplices of K. For each vertex v of K, set $E_v=E\setminus\{x_i|v\in\sigma_i\}$. Define $\mathcal{G}=\bigcup\{\operatorname{cc}_{E_v}(X)|v$ a vertex of K. Then \mathcal{G} is a convex growth hyperspace of X, and the cover $\{\operatorname{cc}_{E_v}(X)\setminus\{X\}\}$ of $\mathcal{G}\setminus\{X\}$ is a Q_0 -decomposition with nerve K. Thus $\mathcal{G}\setminus\{X\}\approx(\mathcal{G}\setminus\{X\})\times Q\approx|K|\times Q_0\approx M$.

For n > 2, we consider the convex *n*-cell $X \times I^{n-2}$, and take $\mathcal{G} = \bigcup \{ \operatorname{cc}_{E_n \times I^{n-2}}(X \times I^{n-2}) \}$.

A final remark: one can routinely verify (using projections onto finite-dimensional convex cells) that all the results of this section remain valid when X is an infinite-dimensional compact convex set in Hilbert space.

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