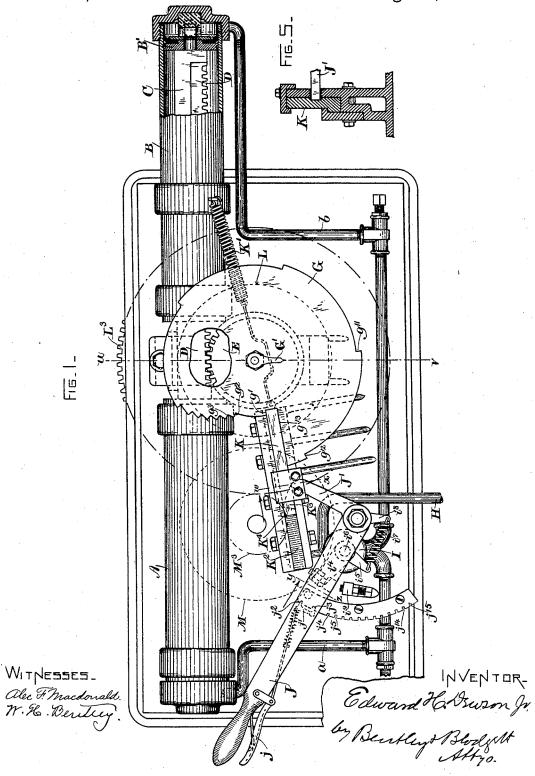
E. H. DEWSON, Jr. PNEUMATIC CONTROLLER.

No. 524,541.

Patented Aug. 14, 1894.



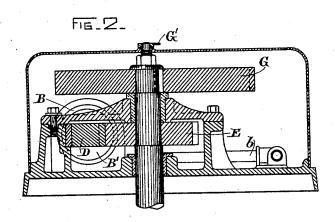
(No Model.)

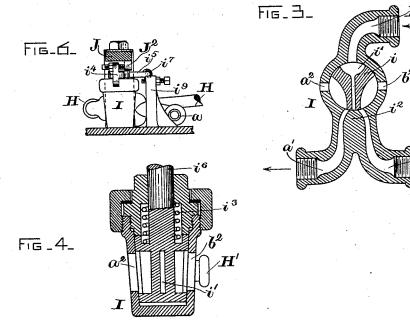
5 Sheets-Sheet 2.

E. H. DEWSON, Jr. PNEUMATIC CONTROLLER.

No. 524,541.

Patented Aug. 14, 1894.





WITNESSES. alse F. Macdonald.

INVENTOR:-Edward H. Drwson Jr by Benkley Blodgett Altzo (No Model.)

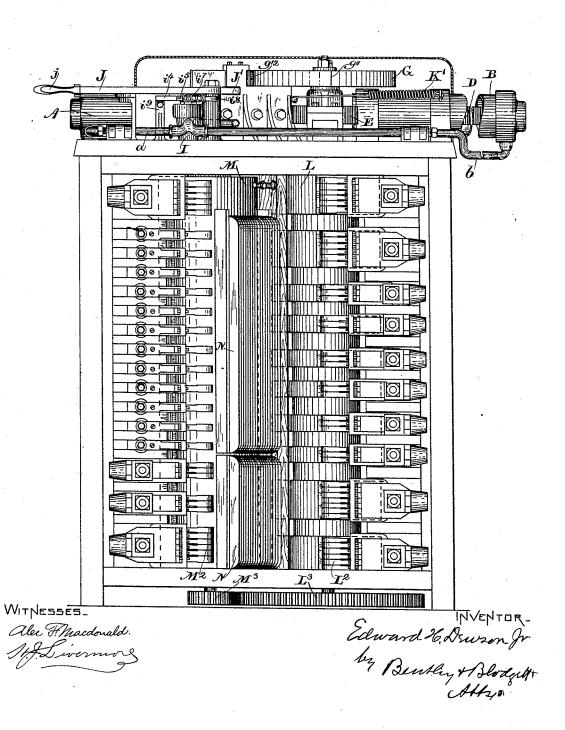
5 Sheets-Sheet 3.

E. H. DEWSON, Jr. PNEUMATIC CONTROLLER.

No. 524,541.

Patented Aug. 14, 1894.

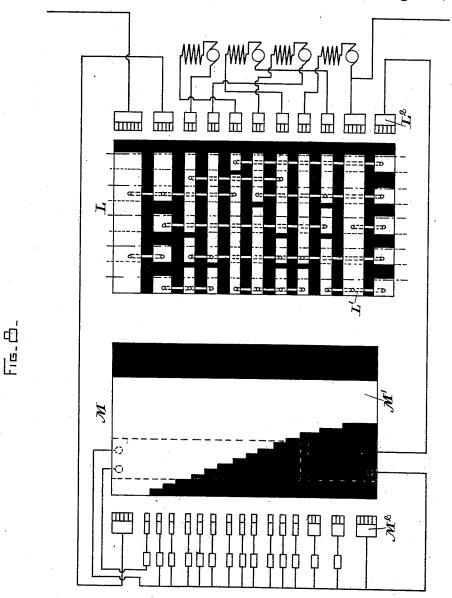
FIG. Z



E. H. DEWSON, Jr. PNEUMATIC CONTROLLER.

No. 524,541.

Patented Aug. 14, 1894.



WITNESSES.

alec F. Macdonald.

M. Livermore

Edward 26. Drwson from by Bentley Blidgett Aftyo.

E. H. DEWSON, Jr. PNEUMATIC CONTROLLER.

No. 524,541.

Patented Aug. 14, 1894.

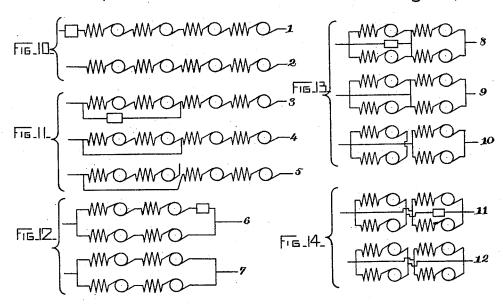
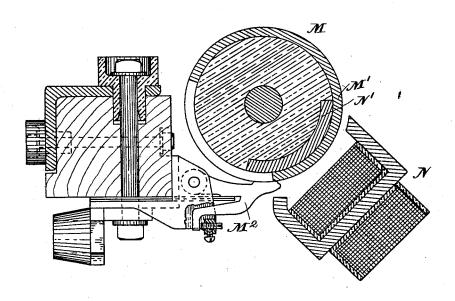


Fig. 9



WITNESSES. alec H. Maedonald. accelerie INVENTOR-Edward H. Drwson fr. by Bentley & Blodgett Aftyo.

United States Patent Office.

EDWARD H. DEWSON, JR., OF LYNN, ASSIGNOR TO THE GENERAL ELECTRIC COMPANY, OF BOSTON, MASSACHUSETTS.

PNEUMATIC CONTROLLER.

SPECIFICATION forming part of Letters Patent No. 524,541, dated August 14, 1894.

Application filed April 11, 1893. Serial No. 469,859. (No model.)

To all whom it may concern:

Be it known that I, EDWARD H. DEWSON, Jr., a citizen of the United States, residing at Lynn, county of Essex, State of Massachu-5 setts, have invented certain new and useful Improvements in Pneumatic Controllers, of which the following is a specification.

My invention relates to pneumatic or fluidpressure controllers, and I have devised it es-10 pecially with a view to its application to electric locomotives, although it might be equally well applied to other devices where an oscillatory or to and fro movement can be used.

In this specification and the accompanying 15 drawings, I have shown and described my apparatus as applied to a switch for controlling electric locomotives having a plurality of motors, by changing the connections of the several motors through various steps from series 20 to parallel and introducing resistance into the circuit at each change of connections to prevent arcing. This switch is fully described and claimed in an application for Letters Patent recently filed by Walter H. Knight and John W. Darley, Jr., and forms no part of the present invention, which relates only to means for operating such a switch or similar device. In carrying out my invention I provide a

cylinder or cylinders with a piston or system 30 of pistons therein, and connections through which fluid pressure may be brought to bear on either side of the said piston or pistons causing a movement thereof in either direction at will. I prefer, however, on account 35 of certain mechanical advantages hereinafter set forth to use two open ended cylinders, having their open ends opposed to each other, with a piston in each, the two pistons being connected together by a rod. Since I prefer 40 this form, I have shown it in the accompanying drawings, and will refer more particularly to it in the following description, it being understood, however, that a single cylinder might be arranged so as to form a substantial equivalent for the two shown. These cylinders are respectively connected to a common

source of fluid or gas under pressure, air being the most suitable medium, through independent pipes and a three-way cock, whereby 50 the air or fluid may be admitted to either at will, so that the pistons and connecting rod I the air cylinders is in section to show the

will be forced from the cylinder into which the pressure medium is introduced toward the opposed cylinder, the movement of the rod in one direction or the other being thus 55 controlled by the manipulation of the threeway cock. The movable rod carries a rack or other suitable gearing device whereby the switch cylinder is rotated. The switch cylinder has a stop-wheel rotating with it on 60 the same axis consisting of a disk having its periphery cut away so as to form shoulders adapted to be engaged by a stop acting thereon and actuated by the same lever which controls the three-way cock between the 65 source of pressure and the pipes leading to the cylinders. The said lever is provided with a eatch traveling over a notched scale corresponding to the position of the stop or locking device aforesaid so that by placing the 70 lever at the proper notch the stop-wheel and switch cylinder rotating therewith may be arrested at any desired point. The lever normally rests on the second notch in which position the cock is closed to both pipes. The 75 first forward step of the lever (viz. from the second into the third notch) operates the cock so that pressure is brought to bear on the piston which operates the mechanism in its forward direction; at the second step the stop so is moved so that the cylinder may rotate until brought up by the stop in its new position; at the third step the stop is again moved so that the cylinder may rotate a little further. and so on, the valve remaining in the same 85 position, so that the operating piston is constantly under pressure. When it is desired to reverse the operation the lever is quickly brought back to the extreme end of the notched scale namely to the first notch, there- 90 by reversing the valve and rotating the cylinder in the opposite direction.

The apparatus and mode of operation will now be more fully explained, reference being made to the accompanying drawings in which 95 like letters represent like parts.

Figure 1 is an elevation of the apparatus with a portion cut away to show the rod and rack carried by the pistons and the pinion actuated thereby. The switch cylinders are 100 also shown in dotted lines. Part of one of

2 524,541

piston. Fig. 2 is a cross section of the same on the line u, v, Fig. 1. Figs. 3 and 4 are sectional views of the cock. Figs. 5 and 6 are details in cross section on lines w, x, and 5 y, z, of Fig. 1 respectively. Fig. 7 is a view of the apparatus applied to a series-parallel switch set forth in the application of Knight and Darley aforesaid. Fig. 8 is a development of the switch cylinder, to which I have shown 10 my device as applied, with the contacts thereon, and the fixed contacts engaged thereby showing how the various combinations are effected by the revolution of the cylinder. Fig. 9 is a cross-section of a portion of the 15 switch showing the resistance cylinder and blow-out magnet and Figs. 10, 11, 12, 13 and 14 are diagrams showing the circuit of four motors as affected by the switch.

Referring to Fig. 1, A and B are open-ended 20 cylinders in line with each other having their open ends opposed to each other, and each is provided with a piston, the two pistons being connected together by a rod. A portion of the cylinder B is cut away, showing the piston B' 25 and the connecting rod C which carries the rack D. Meshing with the rack D is the pinion E to which is imparted a rotary motion in one direction or the other as the piston rod moves between the cylinders. This pinion 30 carries with it the main switch cylinder L and the stop-wheel G the function of which will be hereinafter explained. In order to operate the rod, a suitable pressure medium such as compressed air is introduced to one cylinder 35 or the order through the pipes a and b respectively, by a pipe H communicating with a source of supply, and a three-way cock I connecting the pipe H to the pipe a or b as desired. The construction of the said cock is 40 clearly shown in Figs. 3 and 4 in which i is the valve provided with a port i' having a wide mouth to receive air from the inlet H' and a narrow opening which may be opposed, as the valve is turned, to the outlet a', to the closed 45 portion i^2 or to the outlet b'.

 a^2 and b^2 are exhaust ports for the discharge of air from the pipes \bar{a} and b respectively; that is when air is admitted to cylinder A by turning the cock to the outlet a', the air from 30 cylinder b exhausts through pipe b and port

 b^{2} as the piston moves into said cylinder B. i3 is a spring which holds the valve in close

contact with its seat.

To operate the valve, arms i^4 and i^5 , (Fig. 55 1,) are radially attached to the shaft i6 thereof, the former adapted to be engaged by a projection J2 (Fig. 6) on the main operating lever J, and the latter acted on by a spring i7 between it and some fixed part of the apparatus, 60 as i^8 . A projection i^9 is provided, against which the arm i^4 is normally held by said spring i' when not engaged by the lever J. In the position of the valve corresponding to said normal position of said valve arm i 65 pressure is admitted to the cylinder B, which tends to rotate the pinion E and the stop-wheel

cylinder and the mechanism controlled thereby. The rotation of the stop-wheel, however, is at this stage of the operation prevented by 70 a stop K hereinafter described, which is operated by the lever J, but not so operated until after the valve is opened to the cylinder B, a further movement of the lever being required after the valve is in its normal posi- 75 tion aforesaid, to actuate the said stop K and release the stop-wheel. The said stop-wheel G consists of a disk baving its periphery radially cut into at predetermined intervals so as to form, as it were, a consecutive series of 80 integral concentric segments increasing in length of radius from the starting point of rotation, so that the periphery of the disk is made up of a series of concentric arcs terminated respectively by the shoulders g', g^2 , &c. 85 These shoulders are adapted to be engaged as the disk rotates in its forward direction by a stop K consisting of a bolt or bar springpressed against the periphery of the disk. A spring K' for this purpose is shown in Fig. 1 90 attached to a ring or projection on cylinder B.

The stop K travels in a grooved track K2 radial to the periphery of the stop-wheel and is shown in the drawings in its normal position, namely against the periphery of the stop- 95 wheel and engaged by the shoulder g' whereby the said stop-wheel is held stationary in its initial position. A slot K³ (shown in dotted lines Fig. 1) is provided near the outer end of said stop, whereby the arm J' of the lever J 100 is free to engage with the portion K4 of the stop K and draw said stop away from the stopwheel as the lever J is pushed down. A reverse movement of the lever, however, is not communicated to the stop so that its move- 105 ment in the other direction is entirely dependent upon the spring above described. The lever J is provided with a supplementary handle j controlling a catch j' adapted to engage successively with the notches $j^2 j^3 j^4$, &c., 110 each of which corresponds to a predetermined position of the switch cylinder as will now be described. Assuming the lever to be in such a position that the eatch j' is in the notch j^3 (in which position the valve I is closed) let it 115 be moved to the next position with eatch jin notch j^4 . The valve, following the lever through the action of its spring i7, is then open to the pipe b and pressure is brought to bear on the piston B'. The arm J' however 120 has not yet acted on the stop K but is in contact with portion K4 ready to move the stop at the next step. The lever J is now in a neutral position between the valve and the stop, both of which are in their normal positions 125 and substantially acting against one another so that pressure is at hand to rotate the cylinder as soon as the removal of the stop K from engagement with shoulder g' will admit of such movement. The lever is then pushed 130 down until the eatch j' is in the notch j^5 , thus withdrawing the stop K from the shoulder g'and permitting the cylinder to rotate until G from right to left and thus start the switch 1 stopped by the shoulder g^2 coming in contact

524,541

with the stop K, it being understood that the valve is constantly open to cylinder B during the further movement of the lever in this direction. The next stop brings the shoulder g^3 into contact with the stop K, after due rotation of the cylinder, and so on around to g^{12} which is the limit of positive rotation of the stop-wheel. The segment between g^{12} and g'forms a long shoulder g^{13} , which engages the stop K when the cylinder has completed its rotation in its backward direction and reaches its initial position after a reversal of the valve as shown hereinafter. Since the operating lever is so arranged that the valve 15 must be in a position to admit pressure to the piston B' before the stop K can be operated at all, it is obvious that the action of the switch will be sudden and rapid, and that said switch will be firmly and positively held at 20 the desired position determined by the position of the lever and stop, by the pressure constantly tending to rotate it and the stop acting against the pressure to prevent rotation. In its application to an electric switch this is an important feature, since it is essential that the changes of connection be made rapidly and absolutely without the possibility of resting in an intermediate position where a destructive are might be playing unknown 30 to the operator.

When it is desired to reverse the switch and stop the motor the operation is as follows: The lever J is quickly brought back to the position shown in Fig. 1 of the drawings with the catch j' in notch j^2 , thereby engaging the arm i^4 of the valve and turning said valve to admit pressure to the pipe a, when the cylinder will begin to rotate in the opposite direction, while the stop K under the action of 40 its spring will pass from one shoulder to another of the stop-wheel like a pawl on a ratchet without affecting the rotation of said stopwheel. Suppose for example the lever is in the last position (noted j^{15}) and the stop K against the shoulder g^{12} . When the lever is drawn back to the first position, air is admitted to cylinder A rotating the stop wheel from left to right. When the shoulder g^{11} reaches the stop, the latter under the action 50 of its spring drops over said shoulder to the surface of the next and the stop-wheel continues to rotate until it reaches its normal position between the shoulder g' and the long shoulder g^{13} on the opposite side of the seg-55 ment which forms shoulder g^{12} . The cylinder is now held by the stop K so that it cannot rotate in either direction until said stop is operated again by the lever J; and the motors are out of circuit.

60 If it is desired to reduce the speed of the motors by stopping the switch cylinder at any intermediate position when rotating in its backward direction (from left to right) the lever is quickly brought to the position shown 65 in the drawings, and the cylinder allowed to rotate in its backward or negative direction until just after the desired point is reached,

when the lever may be returned to the proper notch j^2 , reversing the direction of rotation of the cylinder and setting the stop K so as 70 to engage the desired portion of the stop-wheel. Suppose, for example, the stop is at g^{12} and it is desired to move the switch one step back. The lever is moved as just described to notch j^3 and held there until the 75 indicator G' which may be provided with a suitable scale on the casing of the device, although it is not shown in the drawings, shows that the shoulder g^{11} has passed the stop, and then the lever is quickly moved to notch j^{14} , 80 when the cylinder is reversed and stopped at g^{11} .

It is of course obvious that the stop-wheel G may be arranged in any manner suitable for the work it has to do; that is the cuttings 85 may be so spaced that the cylinder will travel any predetermined distance at each step in the regulation. Notches or teeth moreover might be substituted for the shoulders shown in the drawings by slightly modifying the ar- 90 rangement of the operating lever. In the present instance it will be noted that as the cylinder begins to rotate it travels a very short distance at each step, but after it has completed about a fifth of its revolution a con- 95 siderable distance is traversed at one movement of the lever. The reason for this is that it would be unsafe to take the first steps in controlling electric motors suddenly, while after the motors have attained a considerable 100 rate of speed, so that counter-electro-motive force is being developed, it is possible to change connections rapidly. This is fully set forth in the application of Knight and Darley above referred to. It is obvious, however, 105 that the same principle would apply to any other source of motive power in overcoming the inertia at starting.

The special advantage of a pneumatic controller of this kind is its absolute accuracy in 110 obeying the movement of the lever and the certainty that the switch will be in precisely the position indicated by the lever, while a mechanically operated switch is liable through looseness of gearing or other cause, 115 to fail in the accuracy of action required in this work. The pressure medium may be easily obtained by means of a compressing pump operated by a small motor in the same circuit with the locomotives; and if an air brake 120 is to be used the same source can be made to supply both brake and controller.

The apparatus embodied in my invention, comprising two open ended cylinders with a connecting-rod reciprocating between them 125 is simple and compact. The cylinders themselves afford a support and guide for the rod, obviating the need of special guides or ways for the same, as would be necessary with a double-headed cylinder. The valve arrangement also is simple and effective, admitting as it does a constant supply of the pressure medium to the working cylinder during the "step-up" movement of the switch cylinder

controlled by the operating lever and step-bystep device described, without the possibility of being accidentally shut off, since it is independent of the operating lever when once opened.

The switch or controller for the operation of which I have especially designed my pneumatic device herein set forth, is illustrated in Figs. 7 to 14 of the drawings, and may be 10 briefly described as follows: It consists of two cylinders, L and M, the cylinder L carrying a series of contacts L'engaged by brushes L² connected to the terminals of the motors, so that by its rotation the motors may be con-15 nected up in various ways; and the cylinder M carrying a single contact M' connecting as it rotates with a series of rheostat terminals M2, so as to bring more or less resistance into circuit to prevent arcing while the changes 20 of connection are being made. The two cylinders are geared together, so that the cylinder M or rheostat cylinder, makes five revolutions, while the cylinder L, or switch cylinder, makes only one, whereby the same re-25 sistance is used five times during one complete change in the connections of the motors. The rheostat cylinder is so adjusted that by its rotation the full resistance afforded by the rheostat is in circuit at the be-30 ginning of a change of motor connections and decreased gradually until the change is effected, when no resistance is left in circuit. A blow-out magnet N is provided for the purpose of extinguishing any arc that may be 35 formed at the contacts, and in order to render said magnet more efficient a plate of iron N' is placed within the cylinder M and underneath the contact plate thereon forming an armature for said magnet when the said 40 cylinder is in the position where the action of the magnet is required, said plate or arma-

ture completing the magnetic circuit. The drawings show the general construction of the apparatus clearly enough for the 45 purposes of the present application, and it is not deemed necessary to go into a more detailed description. Fig. 7 illustrates the switch with my pneumatic controlling device applied thereto, and indicates plainly the 50 manner in which the main or switch cylinder L is rotated by the pinion E and controlled in its rotation by the stop-wheel G, as hereinbefore described, and also shows the connection between the two switch cylinders through 55 the gear-wheels L³ and M³. The general arrangement of the motor and rheostat connections and the blow-out magnet may also be readily understood from this figure. Figs. 10 to 14 show in diagram the changes in con-60 nections of the four motors as applied to which this switch is shown; first, all in series with a resistance; second, in series with no resistance, (both of said stops being shown in Fig. 10;) third, two motors short-circuited through 65 a resistance and the remaining two in series; fourth, the same, with the resistance cut out circuited and the remaining two in series (the third, fourth and fifth steps being shown in Fig. 11); and so on to the last step in Fig. 14 70 where all four motors are connected in parallel, it being unnecessary to trace the intermediate stages.

While I have stated that my pneumatic device herein set forth may be used with 75 switches of any kind, or even rheostats, it is of especial value in connection with switches of the kind set forth in the application of Knight and Darley above referred to, and herein shown and briefly described, inasmuch 80 as these switches when used to establish different groupings of a number of large railway motors, are of necessity very complicated and require an exactitude of operation which can be attained only with a powerful mechanical 85 controller or operating device such as I have herein shown.

What I claim as new, and desire to secure by Letters Patent, is-

1. In a pneumatic controller, a cylinder, a 90 piston therein geared to the switch or other device to be operated, a valve controlling the admission of air or other fluid under pressure to said cylinder, a stop adapted to control the movement of said switch, and a common lever 95 which first operates said valve and then actuates said stop to control the movement of the switch.

2. In a pneumatic controller, actuated by constantly acting pressure, a step-by-step 100 device comprising a rotating disk co-operating in its movement with the switch to be controlled, shoulders on the periphery of said disk, a stop consisting of a bolt or bar radial to said disk, and means whereby said bar may 105 be caused to engage with any of said shoulders and hold the switch in the position desired, substantially as described.

3. In a pneumatic controller actuated by constantly acting pressure, a step-by-step 110 device comprising a rotating disk co-operating in its movement with the mechanism to be controlled, and having its periphery made up of a series of arcs to its own center of rotation, the said arcs increasing in length of ra- 115 dius from the starting point of forward rotation, whereby a series of shoulders g, g', g^2 , &c., are formed thereon, and a stop consisting of a bolt or bar adapted to be moved to and fro in a direction radial to said disk so 120 as to engage with any of said shoulders at will to stop said disk and the mechanism controlled thereby in any of a number of positions predetermined by the arrangement of the shoulders on the disk.

4. In a pneumatic controller actuated by constantly acting pressure in either direction, a step-by-step device consisting of a rotating disk co-operating with the mechanism to be controlled, said disk being limited in its for- 130 ward movement by mechanical means manually controlled, but free to move in the reverse direction if so actuated, until it reaches of the short circuit; fifth, two motors open- its initial position, or until it is stopped and

125

524,541

again actuated in its forward direction by a reversal of the actuating pressure.

5. In a pneumatic device for operating motor controllers a source of substantially constant pressure, a piston actuated thereby, a valve controlling the pressure medium and determining the direction of movement of the said piston, a regulating or step-by-step device for limiting and controlling the movement of said piston, and common means for operating said valve and step-by-step device as described.

6. In a pneumatic device comprising a cylinder and reciprocating piston, a three-way valve controlling the admission of pressure to said cylinder, said valve being normally held open by a spring to admit pressure to one side of said piston, a step-by-step device substantially as described adapted to limit the movement of said piston after said valve is in its normal position aforesaid, and a lever operating said step-by-step device after said valve is in said normal position and adapted by a reverse movement to close and then reverse the valve without acting on the step-by-step device.

7. In a pneumatic device actuated by a reciprocating piston, the combination with a valve for admitting pressure to said piston to operate the same, of a step-by-step device substantially as described, limiting and determining the movement of the said pneumatic device, and an operating lever whereby said valve and step-by-step device are co-opera-

35 tively controlled.

8. In a pneumatic device actuated by a reciprocating piston, the combination with a valve for admitting pressure to one side or the other of said piston to operate the same in either direction, of a step-by-step device substantially as described limiting and determining the movement of the said pneumatic device in one direction but not in the other, and an operating lever whereby said valve and step-by-step device are co-operatively controlled.

9. The combination with a three-way cock for operating a pneumatic reciprocating system, of a step-by-step device substantially as
50 described for controlling and limiting the movement of said system, and common means for operating said cock and said step-by-step

device as set forth.

10. The combination with a three-way cock for operating a pneumatic reciprocating system, of a step-by-step device substantially as described for controlling and limiting the movement of said system in one direction but not in the other, and common means for first operating said cock so that pressure is admitted to said system before said system is released by said step-by-step device, and afterward operating said step-by-step device to release and control the further movement of 5 said system, substantially as set forth.

11. The combination with a three-way cock for operating a pneumatic reciprocating sys-

tem, of a step-by-step device substantially as described for controlling and limiting the movement of said system, a cylinder geared 70 to said system and rotated thereby carrying electric contacts on its surface whereby the terminals of a plurality of electric motors are variously connected and the power and speed of said motors thereby controlled, and common means for manually operating said valve and said step-by-step device as set forth.

12. The combination with a double openended cylinder having co-operating reciprocating pistons actuated by fluid pressure in 80 said cylinders, of a rack carried by said pistons, a pinion meshing therewith, and a cylinder rotating with said pinion and carrying electrical contacts whereby the connections of a plurality of motors are varied as and for 85

the purpose described.

13. The combination with two open-ended cylinders having their open ends opposed to each other, of a reciprocating system comprising a piston in each cylinder and a connecting rod between said pistons, the whole of said reciprocating system being supported and guided by said cylinders, and operated in one direction or the other by pressure admitted to said cylinders respectively, and a 95 rack carried by said connecting rod whereby the reciprocating movement thereof is translated and utilized.

14. The combination with a switch or similar device to be operated, of a cylinder, a reciprocating piston therein, a valve controlling the admission of fluid pressure to said cylinder, gearing between said piston and said switch, a stop acting on a series of shoulders moving with said switch to control the extent 105 of movement thereof, and a common operating device for said valve and said stop.

15. The method of pneumatically controlling an electric switch or similar device, which consists in first subjecting the said device to air pressure tending to actuate it, and then controlling mechanically the movement of the

switch due to said pressure.

16. The method of controlling an electric switch or similar device, which consists in 115 first subjecting said device to air pressure tending to actuate it in one direction, said device being mechanically locked until after said air-pressure is caused to act thereon, then unlocking said device and regulating 120 the consequent movement thereof, and finally reversing the direction of the said pressure whereby the device is actuated in the opposite direction until restored to its normal position.

17. The method of controlling an electric switch or similar device, which consists in first subjecting said device to air pressure tending to actuate it in a forward direction, then mechanically releasing and controlling 130 the consequent movement of said switch, then reversing the direction of action of said pressure so as to actuate said switch in a backward direction, and finally causing said switch

to rest in the desired intermediate position | by again reversing the direction of action of said pressure so as to stop the backward movement of said switch and again actuate it 5 in its forward direction, and then mechanically controlling its movement in said forward direction as before.

In witness whereof I have hereunto set my

EDWARD H. DEWSON, JR.

Witnesses: H. J. LIVERMORE, ALEC F. MACDONALD.